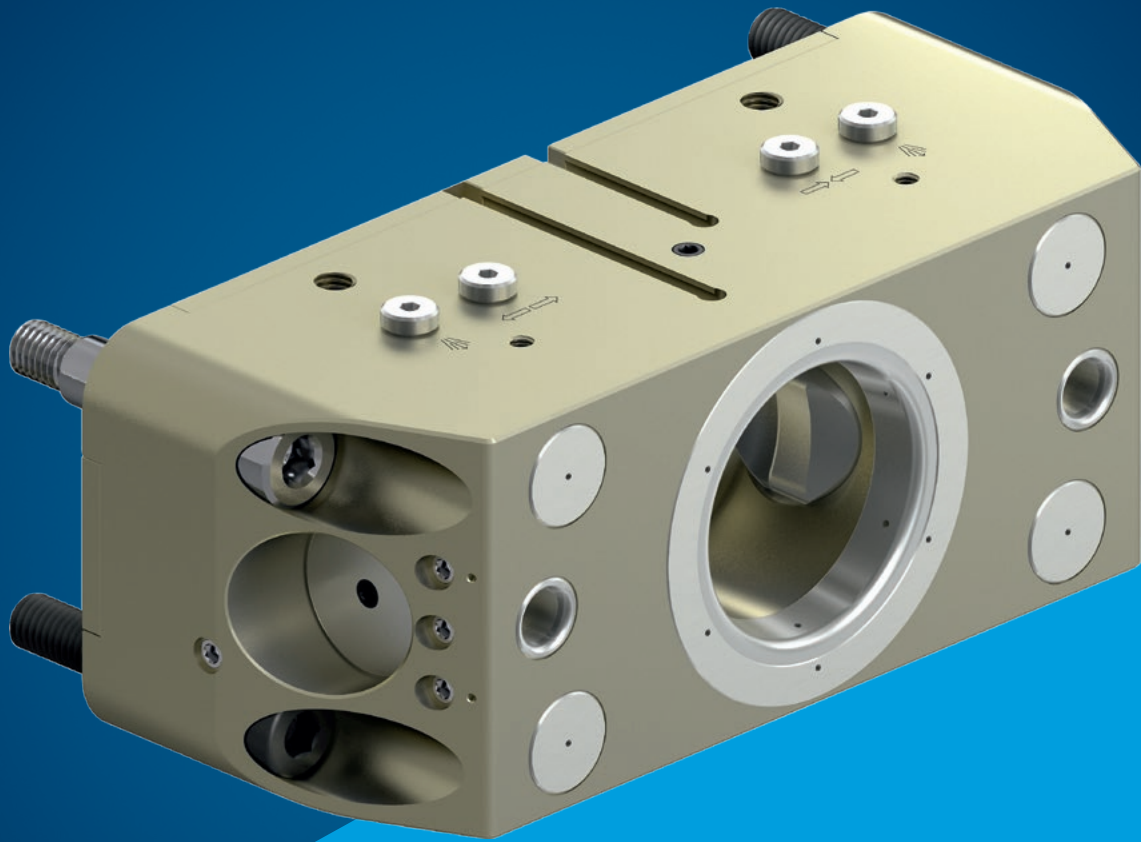




VERO-S NSR

**Robot couplings for high-end
palletizing**

Maintenance-free robot coupling for pallet handling extremely close to the machine table

The robot couplings of the VERO-S NSR series have been setting benchmarks for high-efficiency, robot-assisted pallet change on machine tools for many years. The three robot modules NSR mikro 60, NSR mini 100 and NSR 160 are made of high-strength and hard-anodized aluminum alloy. Due to their low weight and extremely slim design, these modules allow for loading extremely close to the machine table. Heavy pallets, meanwhile, can be easily handled with the robust robot modules NSR3 138 and NSR maxi 220.



Advantages – Your benefits

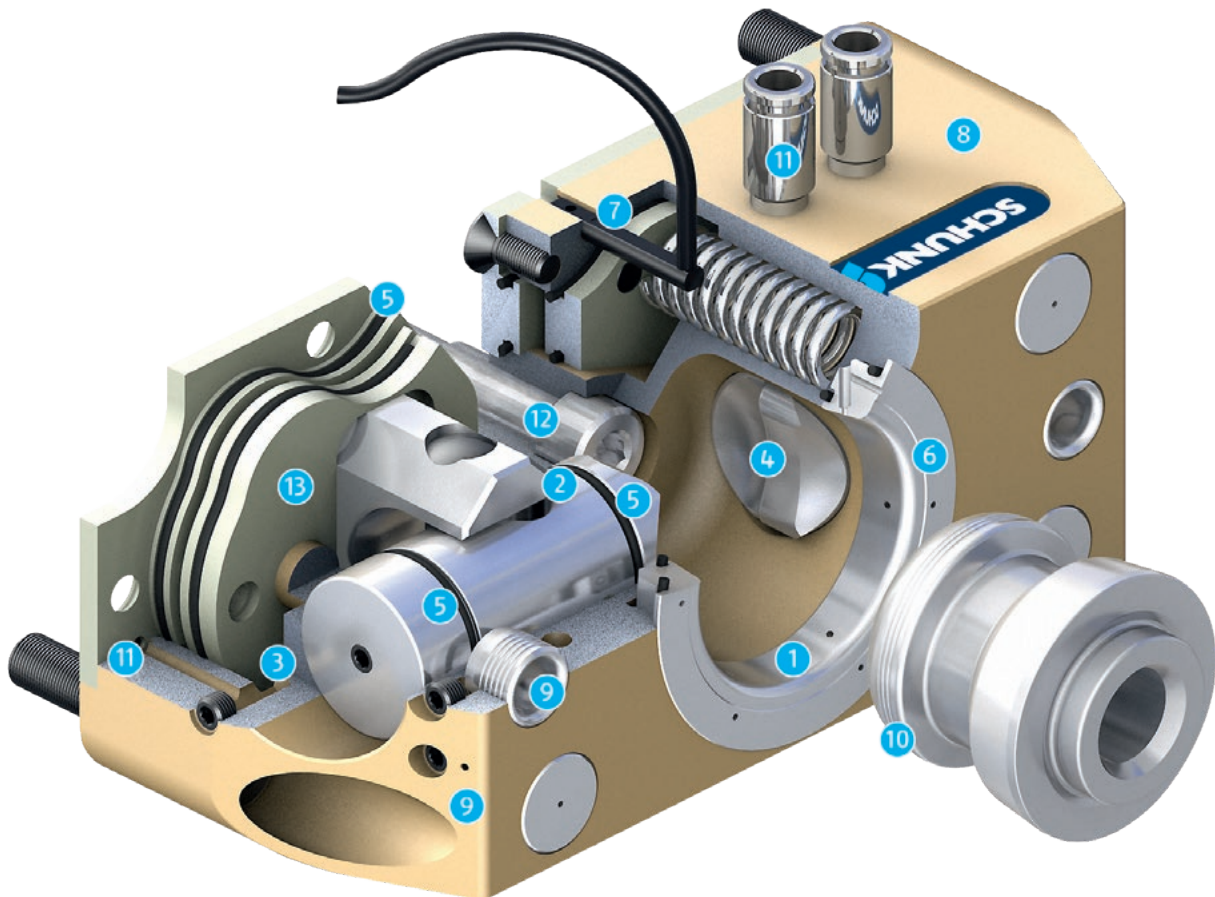
- + Perfectly suitable for automation**
Loading extremely close to the machine table.
- + All modules can be operated with a system pressure of 6 bar**
Additional pressure intensifiers are not required
- + Positioning via short taper**
Very easy connecting interface with a repeat accuracy of < 0.02 mm
- + Patented dual stroke system for highest pull-down forces**
High force transmission in smallest space
- + Form-fit, self-retained locking**
Full pull-down force is maintained even in the event of a pressure drop
- + Turbo integrated by default**
Pull down forces increased by up to 300%
- + Air purge cleaning integrated in the standard version**
To protect all functional surfaces from dust and chips for maximum process reliability
- + Inductive monitoring of module opened or closed and of pallet presence**
For a maximized process reliability

Technical data

Description	Turbo function	Pull-down force [kN]	Pull-down force with turbo [kN]	Max. moment Mx [Nm]	Max. moment Mz [Nm]
NSR mikro 60	●	0.5	1.5	15	32
NSR mini 100	●	1	4	75	200
NSR 160	●	4	15	600	1600
NSR3 138	●	8	28	1500	1600
NSR maxi 220	●	12	50	4000	4000

Function NSR 160

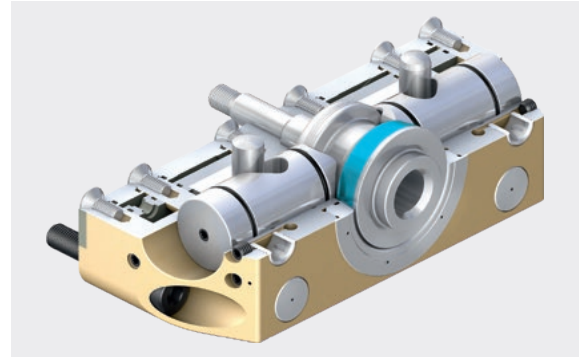
The clamping procedure of the robot module is carried out by an integrated spring assembly. An axial piston and a patented drive kinematics convert the spring force into a maximum pull-down force on the clamping pin. Clamping is carried out by two clamping slides and is self-retained. In addition, the pull-down force can be increased by means of an integrated turbo function. The module is opened pneumatically with a system pressure of 6 bar.



- | | |
|--|---|
| <ul style="list-style-type: none"> ❶ High-precision short taper centering
Ensures μ-precise connection ❷ Patented dual stroke system
High pull-down forces are ensured between the piston and the clamping slide ❸ Turbo function
For amplification of the pull-down force ❹ Large contact surfaces
For transmitting the pull-down and holding forces ❺ Completely sealed system
Therefore absolutely maintenance-free ❻ Steel inlays with integrated cleaning function
For the greatest possible wear resistance ❼ Monitoring of the clamping slide position module open and module closed
Possible via inductive proximity switches | <ul style="list-style-type: none"> ❽ Weight-optimized design
For greatest payloads ❾ Anti-rotation protection
For position orientation of the clamping pallet ❿ Insertion radii on the clamping pin
For fast and safe connecting even in the event of tilt angle and eccentricity ⓫ Actuation of the module
From the side or bottom as desired ⓬ Fitting screws
For exact positioning of the robot coupling ⓬ Pneumatic system
Actuation with 6 bar |
|--|---|

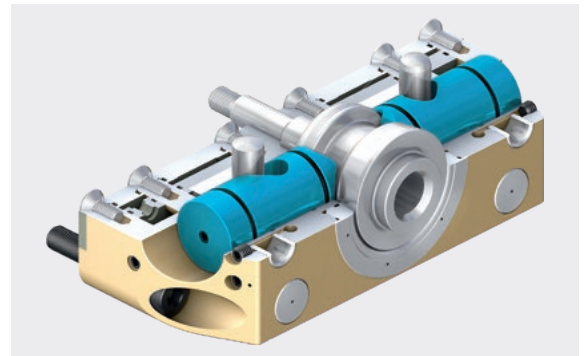
Centering via short taper

The precise short taper centering combined with the form-fitting and self-retaining locking characterizes SCHUNK robot coupling.



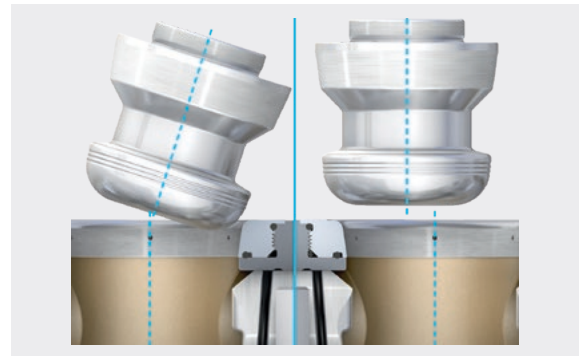
Locking via clamping slides

Large contact surfaces between clamping slides and clamping pin ensure a low surface pressure, resulting in a long service life.



Simple joining – incredibly user-friendly

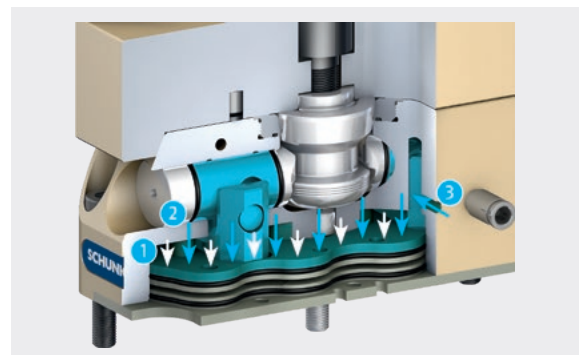
Entry radii on the clamping pin and clamping module enable quick and safe joining, even with a tilt angle and eccentricity. Benefit: The robot's inaccuracies are compensated.



Integrated turbo function

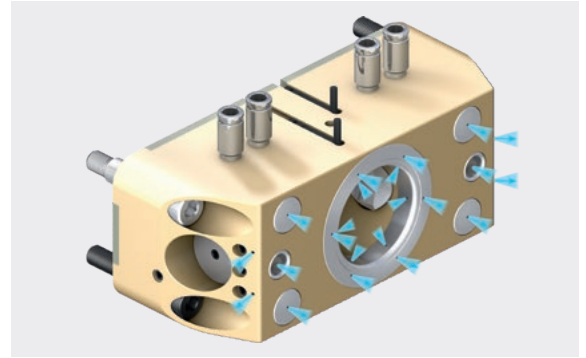
In order to raise the pull-in force, the quick-change pallet module is additionally pressurized with compressed air during clamping. The turbo function increases the pull-down force by up to a factor of 4 (max. 50,000 N) compared to clamping merely based on spring force. With turbo function active, higher loading weights are facilitated.

- ❶ **Spring force**
Stainless, fatigue-resistant pressure springs.
- ❷ **Additional force**
Resulting from the turbo function.
- ❸ **Turbo function connection**



Cleaning based on air purge

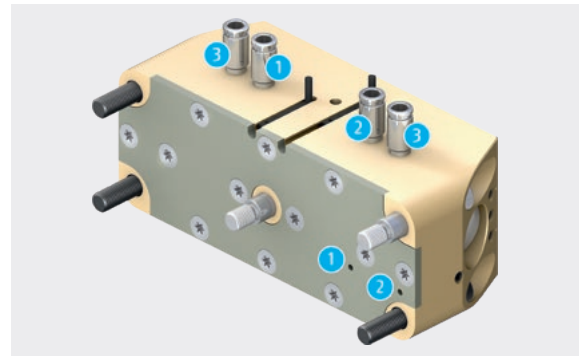
The cleaning function integrated into the standard ensures optimal cleaning of the flat work surface, centering cone, center bore and anti-rotation protection. Bore holes form an air film between the robot coupling and the pallet coupling, which ensures that all reference surfaces are clean.



Control of the robot coupling

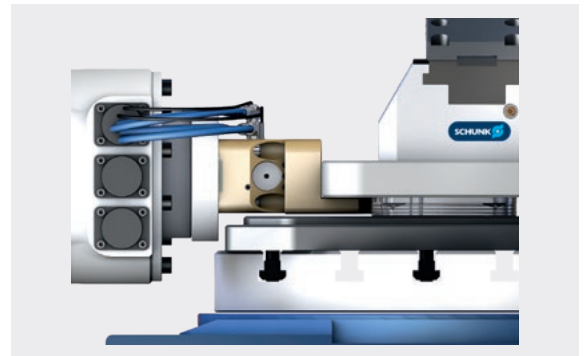
Actuation for opening and turbo function can be performed either at the side or on the base side. The connections for the air purge are fixed at the side.

- 1 Open
- 2 Turbo function
- 3 Air purge



Slim design

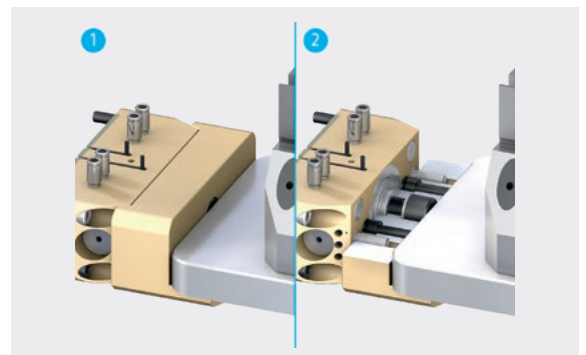
The extra slim design of the robot coupling makes it possible to load pallets extremely close to the machine table. Combining with the NSA3 palletizing modules allows for implementation of very low heights – the machine room is still available for the workpieces.



Anti-rotation protection for pallets

The pallet is drawn in by the robot coupling via a clamping pin. The anti-rotation protection around the middle longitudinal axis is located either via slanted surfaces on the sides or via two cylindrical pins in the front.

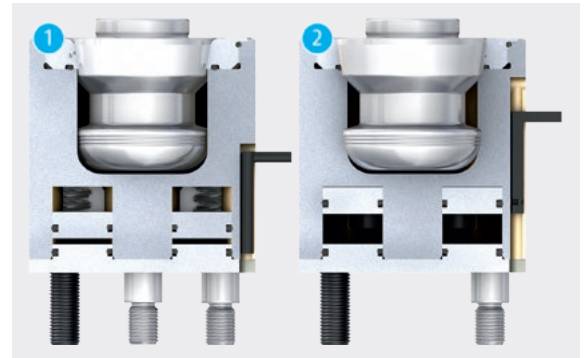
- 1 Possibility 1
Anti-rotation protection via lateral surfaces on the robot coupling
- 2 Possibility 2
Anti-rotation protection via two cylindrical pins in the front of the robot coupling



Monitoring open or clamped (optional)

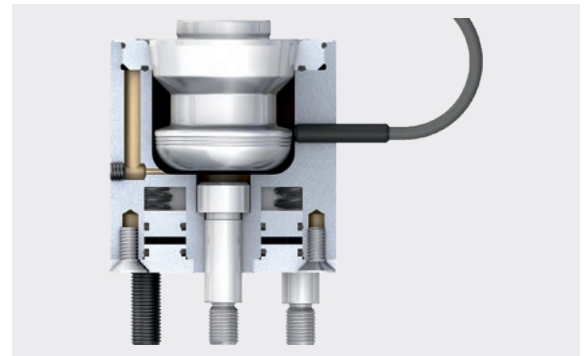
The position of the clamping slides can be monitored with suitable magnetic switches (accessories) (module open – closed). The magnetic switches are attached and clipped to the outside of the module – retrofitting takes just a few minutes. This monitoring ensures maximum process reliability with daily use of NSR.

- ① Robot coupling open
- ② Robot coupling closed



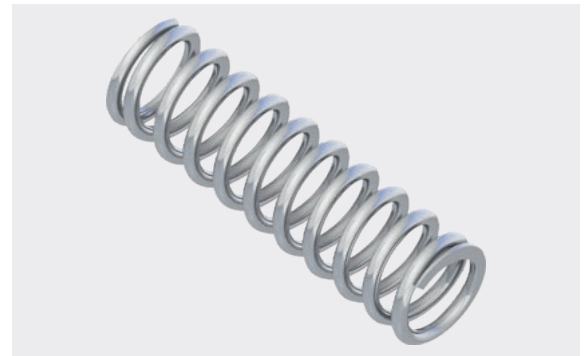
Monitoring of pallet presence (optional)

An inductive proximity switch (accessories) directly monitors the presence of the clamping pin and hence the presence of a pallet. This monitoring ensures maximum process reliability with daily use of NSR.



Pressure spring made of stainless steel

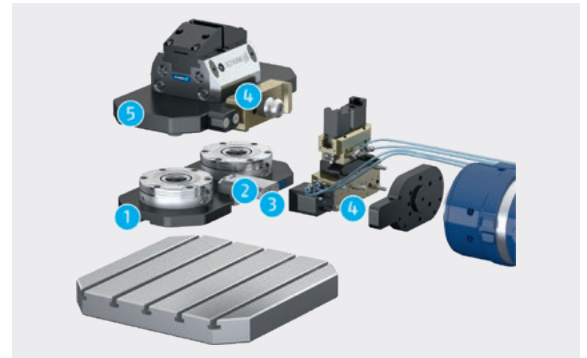
For maximum service life, all of the actuating springs are made of fatigue-free stainless steel.



Economic automation of machine tools without media feed-through

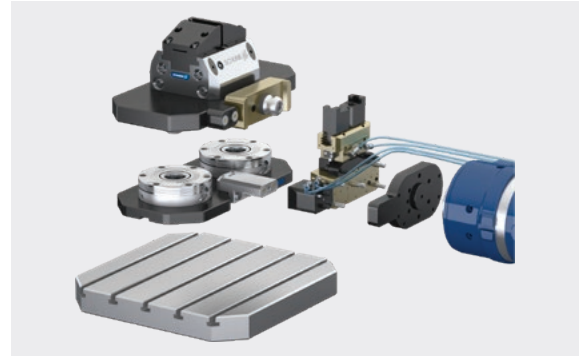
With the VERO-S media coupling, machine tools that have no media routing in the interior of the machine, can now be loaded automatically. Both the VERO-S modules and the pneumatic clamping systems can be actuated via the media coupling at the robot-sided media routing. The media coupling can be retrofitted to all standard VERO-S NSL plus and VERO-S NSL3 clamping stations.

- 1 **VERO-S NSL3 clamping station**
Used as a basis for fast and repeatable exchange of clamping devices
- 2 **Media coupling**
Simple retrofitting on all standard clamping stations
- 3 **Coupling nipple**
Coupling forces depend on the robot, clamping station, and clamping device
- 4 **Robot coupling**
Required positioning accuracy:
Radial ± 0.3 mm
Axial $+0.5$ mm
- 5 **Clamping pallet with TANDEM KSP3 clamping force block**
Clamping pallets for actuating pneumatic clamping devices through the pallet cannot be retrofitted



VERO-S Media Coupling

With the VERO-S media coupling, machine tools that have no media routing in the interior of the machine, can now be loaded automatically. Both the VERO-S modules and the pneumatic clamping systems can be actuated via the media coupling at the robot-sided media routing. The media coupling can be retrofitted to all standard VERO-S NSL plus and VERO-S NSL3 clamping stations.



1. Clamping station with media coupling

Each NSL3 clamping station can be equipped with a specially designed media coupling.



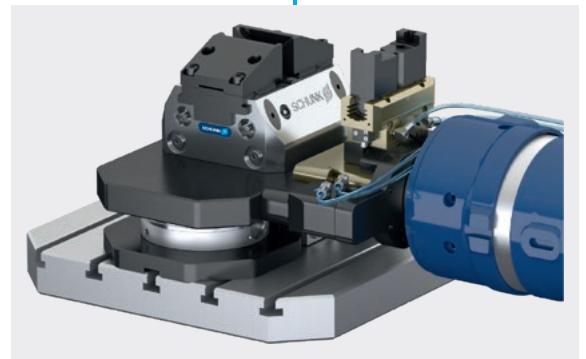
2. Opening the clamping station

The robot opens the clamping station with a media transfer unit that is laterally attached to the machine table. A check valve ensures that the clamping station remains open.



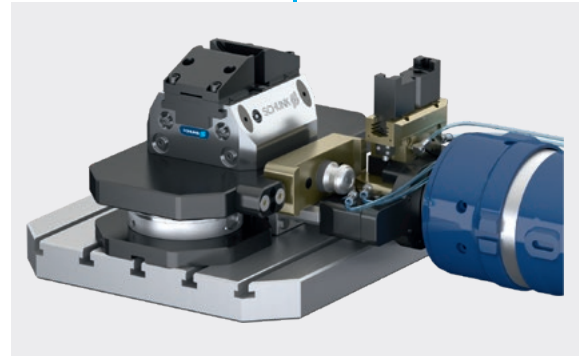
3. Automated loading of the clamping station

The clamping device can then be loaded on the clamping station. During the loading process, the clamping device can be simultaneously opened and, due to the check valve, it remains permanently open even after uncoupling.



4. Locking the clamping station

The modules can be ventilated and closed by docking them to the media transfer unit of the clamping station again. As a result, the clamping device is process-reliably clamped to the clamping station and at a high repeat accuracy.



5. Automated workpiece loading

The workpiece can then be loaded quickly and easily using a SCHUNK gripper.



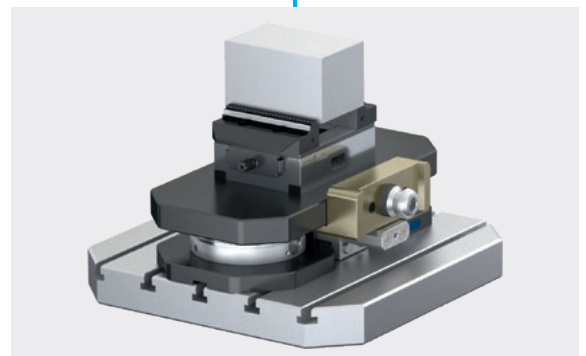
6. Locking the clamping device

The clamping device is clamped by docking the robot to the clamping pallet again. Machining can then begin.



Alternative clamping version

Alternatively, this clamping principle can also be implemented using mechanically actuated clamping devices. In this example, with a KONTEC KSC3 centric clamping vise.



Robot module

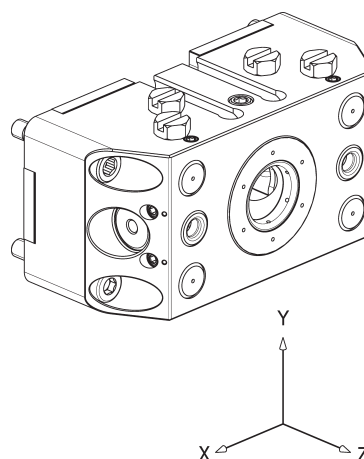
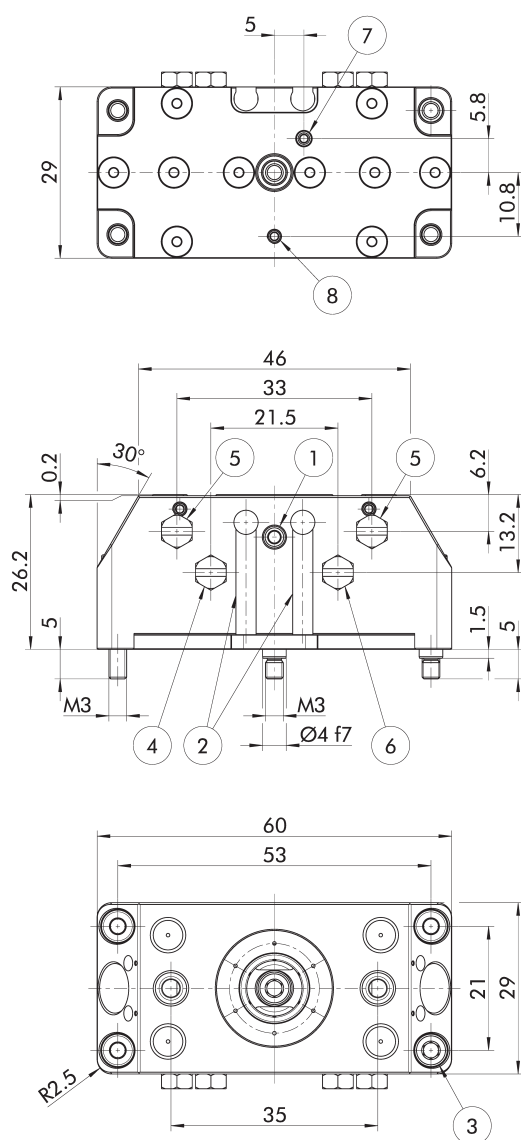
Made of hard-anodized aluminum with matching clamping pin interface SPA mikro 10

Scope of delivery

Robot module, mounting screws, fitting screw, 0-rings, operating manual; without proximity switch

Technical data

Description	ID	Pull-down force [kN]	Pull-down force with turbo [kN]	Unlocking pressure [bar]	Repeat accuracy [mm]	Max. moment Mx [Nm]	Max. moment Mz [Nm]	Weight [kg]
NSR mikro 60	1357111	0.5	1.5	6	< 0.02	15	32	0.15



Subject to technical changes.

- ① Inductive proximity switch M4 x 0.5 (ID 1325755) for pallet presence
- ② Inductive proximity switch (ID 0301042) for module detection
- ③ Fitting screw for positional orientation
- ④ Unlocking connection via screw connection M3
- ⑤ Air purge connection via screw connection M3 (2 bar)
- ⑥ Turbo connection via screw connection M3
- ⑦ Hose-free direct connection module open
- ⑧ Hose-free direct connection turbo function

Pallet coupling

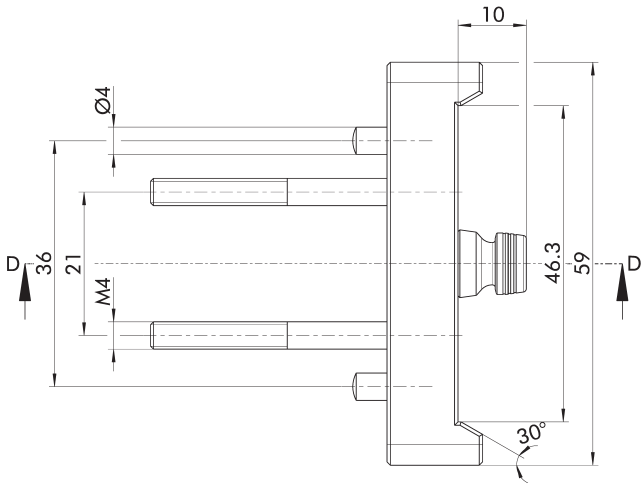
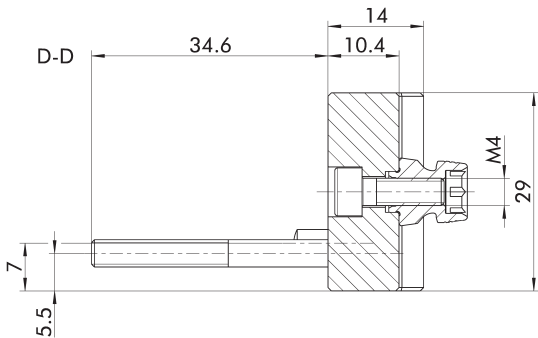
Suitable for robot module NSR mikro 60

Scope of delivery

Pallet coupling, clamping pin, mounting screws, cover caps, operating manual

Technical data

Description	ID	Material	Max. pallet size [mm]	Weight [kg]
PKL mikro 60	1357112	Aluminum	100 x 100	0.07



Subject to technical changes.

Robot module

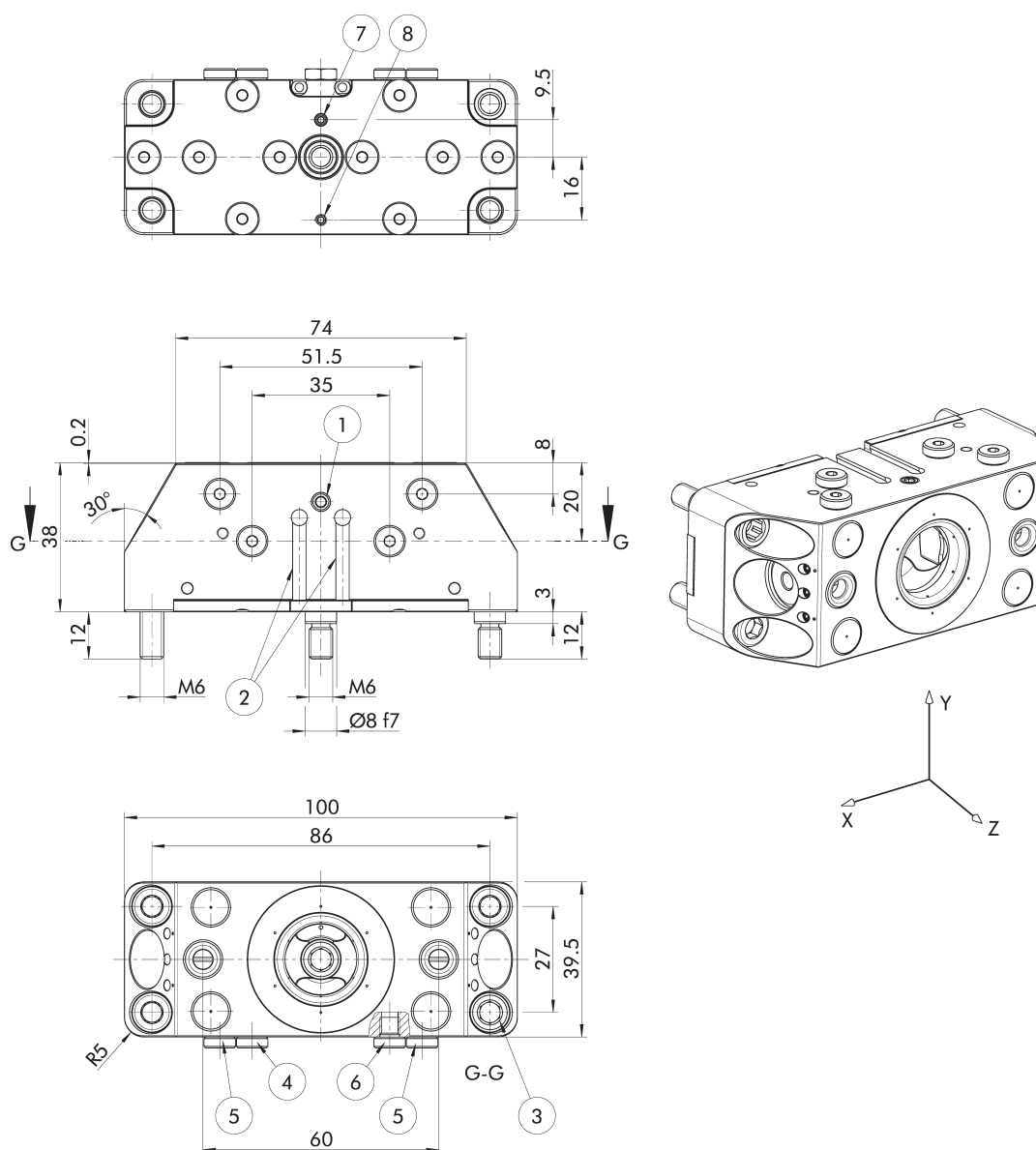
Made of hard-anodized aluminum with matching clamping pin interface SPA mini 20

Scope of delivery

Robot module, mounting screws, fitting screw, O-rings, operating manual; without proximity switch

Technical data

Description	ID	Pull-down force [kN]	Pull-down force with turbo [kN]	Unlocking pressure [bar]	Repeat accuracy [mm]	Max. moment Mx [Nm]	Max. moment Mz [Nm]	Weight [kg]
NSR mini 100	0471960	1	4	6	< 0.02	75	200	0.4



Subject to technical changes.

- ① Inductive proximity switch M5 x 0.5 (ID 0301575) for pallet presence
- ② Inductive proximity switch (ID 0301042) for module detection
- ③ Fitting screw for positional orientation
- ④ Unlocking connection via screw connection M5
- ⑤ Air purge connection via screw connection M5 (2 bar)
- ⑥ Turbo connection via screw connection M5
- ⑦ Hose-free direct connection module open
- ⑧ Hose-free direct connection turbo function

Pallet coupling

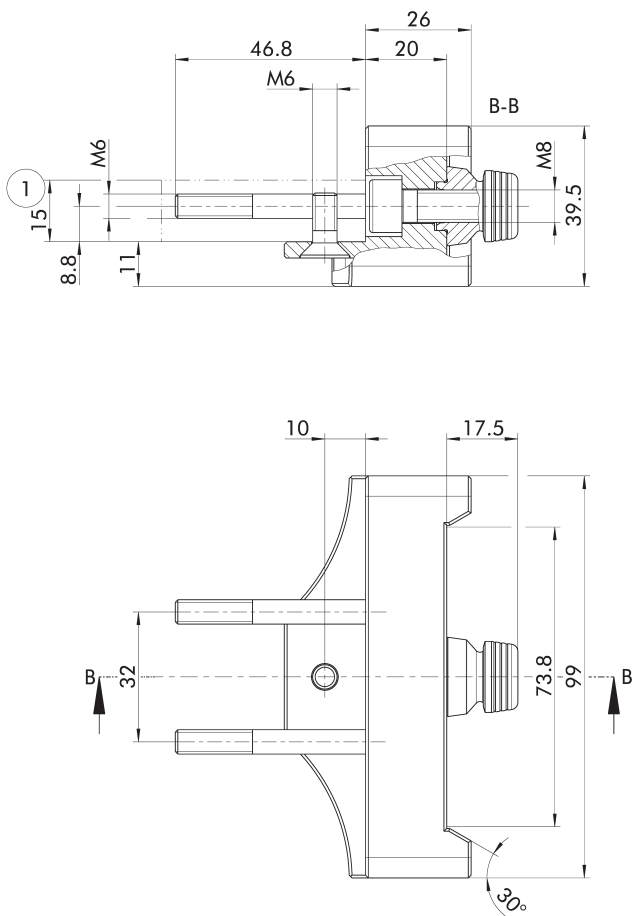
Suitable for robot module NSR mini 100

Scope of delivery

Pallet coupling, clamping pin, mounting screws, cover caps, operating manual

Technical data

Description	ID	Material	Max. pallet size [mm]	Weight [kg]
PKL mini 100	0471970	Aluminum	200 x 200	0.3



Subject to technical changes.

① Minimum plate thickness

Robot module

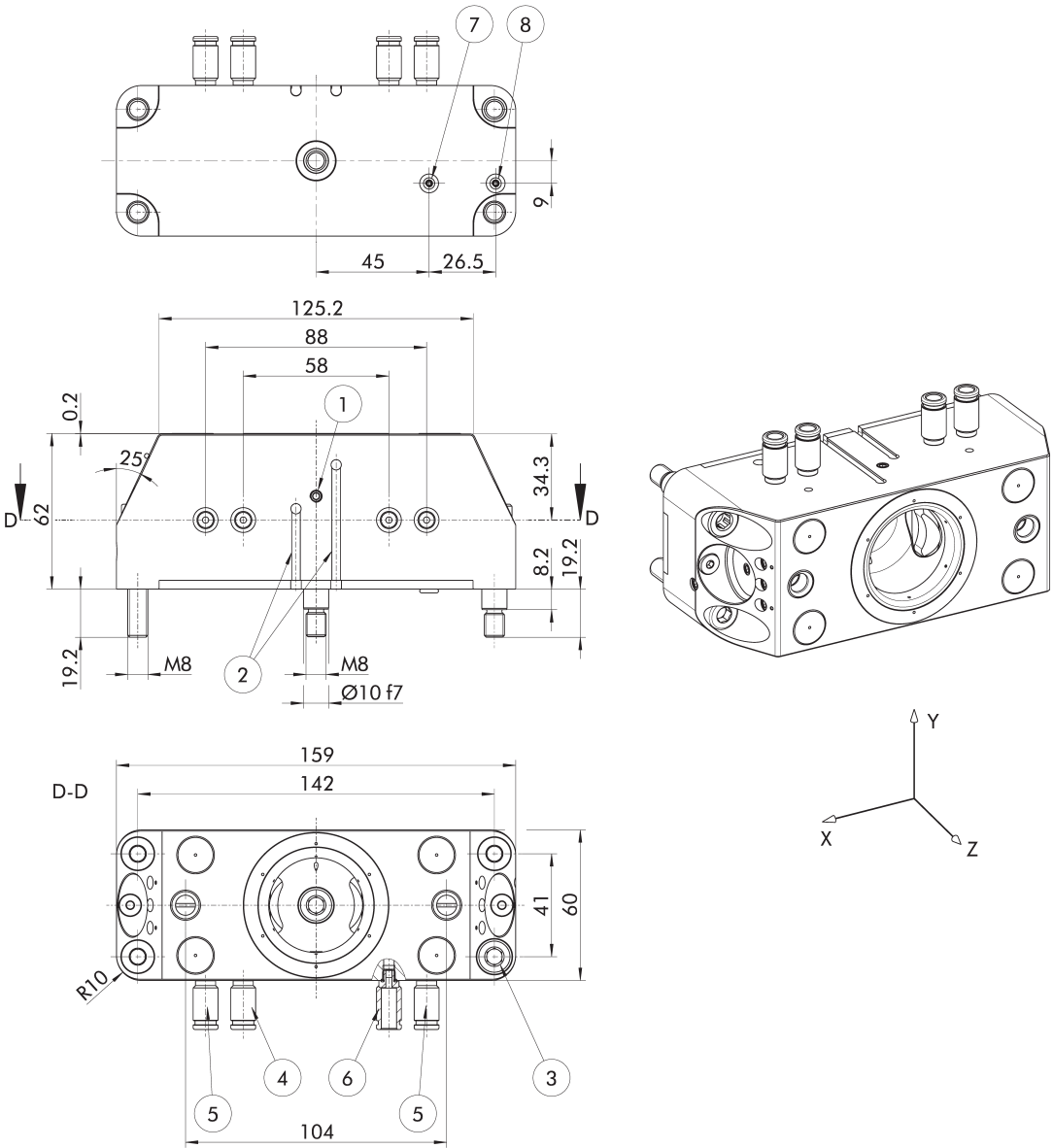
Made of hard-anodized aluminum with matching clamping pin interface SPA 40

Scope of delivery

Robot module, mounting screws, fitting screw, 0-rings, operating manual; without proximity switch

Technical data

Description	ID	Pull-down force [kN]	Pull-down force with turbo [kN]	Unlocking pressure [bar]	Repeat accuracy [mm]	Max. moment Mx [Nm]	Max. moment Mz [Nm]	Weight [kg]
NSR 160	0471915	4	15	6	< 0.02	600	1600	1.6



Subject to technical changes.

- ① Inductive proximity switch M5 x 0.5 (ID 0301575) for pallet presence

② Inductive proximity switch (ID 0301042) for module monitoring

③ Fitting screw for positional orientation

④ Unlocking connection via screw connection M5
- ⑤ Air purge connection via screw connection M5 (2 bar)

⑥ Turbo connection via screw connection M5

⑦ Hose-free direct connection module open

⑧ Hose-free direct connection turbo function

Pallet coupling

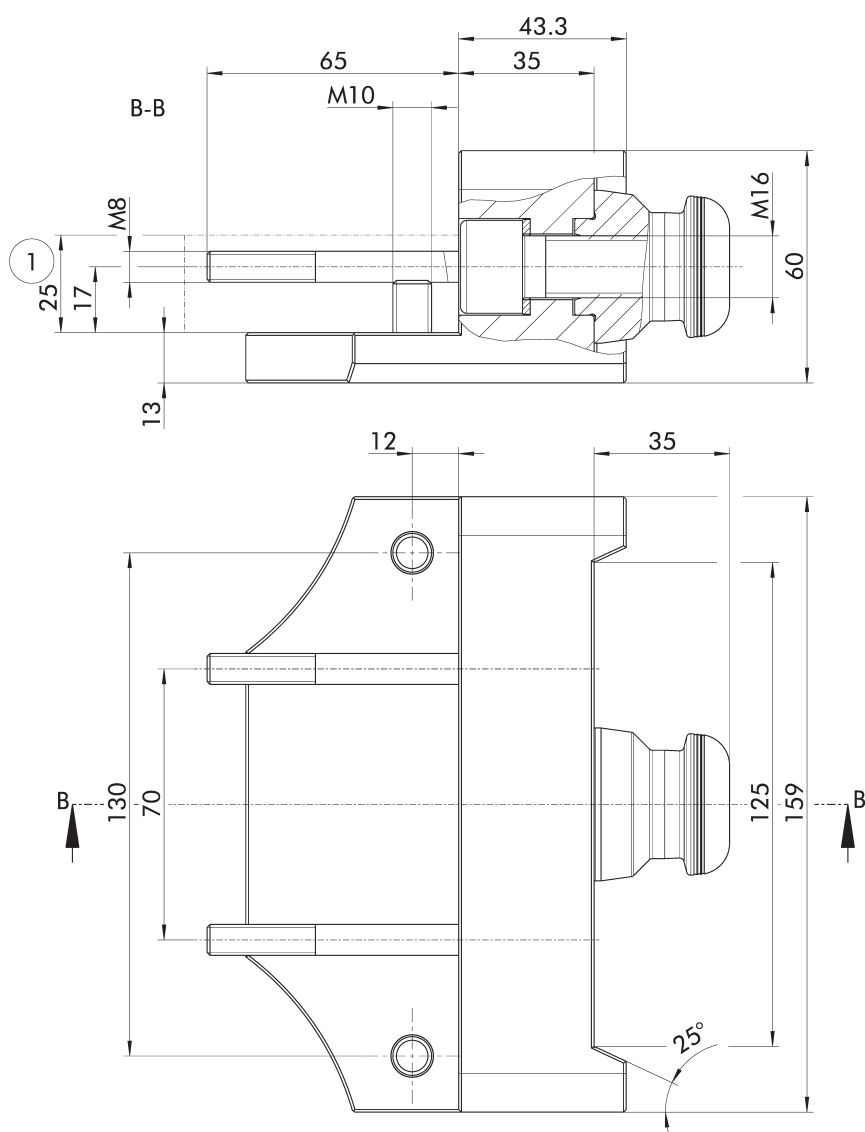
Suitable for robot module NSR 160

Scope of delivery

Pallet coupling, clamping pin, mounting screws, cover caps, operating manual

Technical data

Description	ID	Material	Max. pallet size [mm]	Weight [kg]
PKL 160	0471930	Aluminum	500 x 500	1.5



Subject to technical changes.

① Minimum plate thickness

Pallet coupling

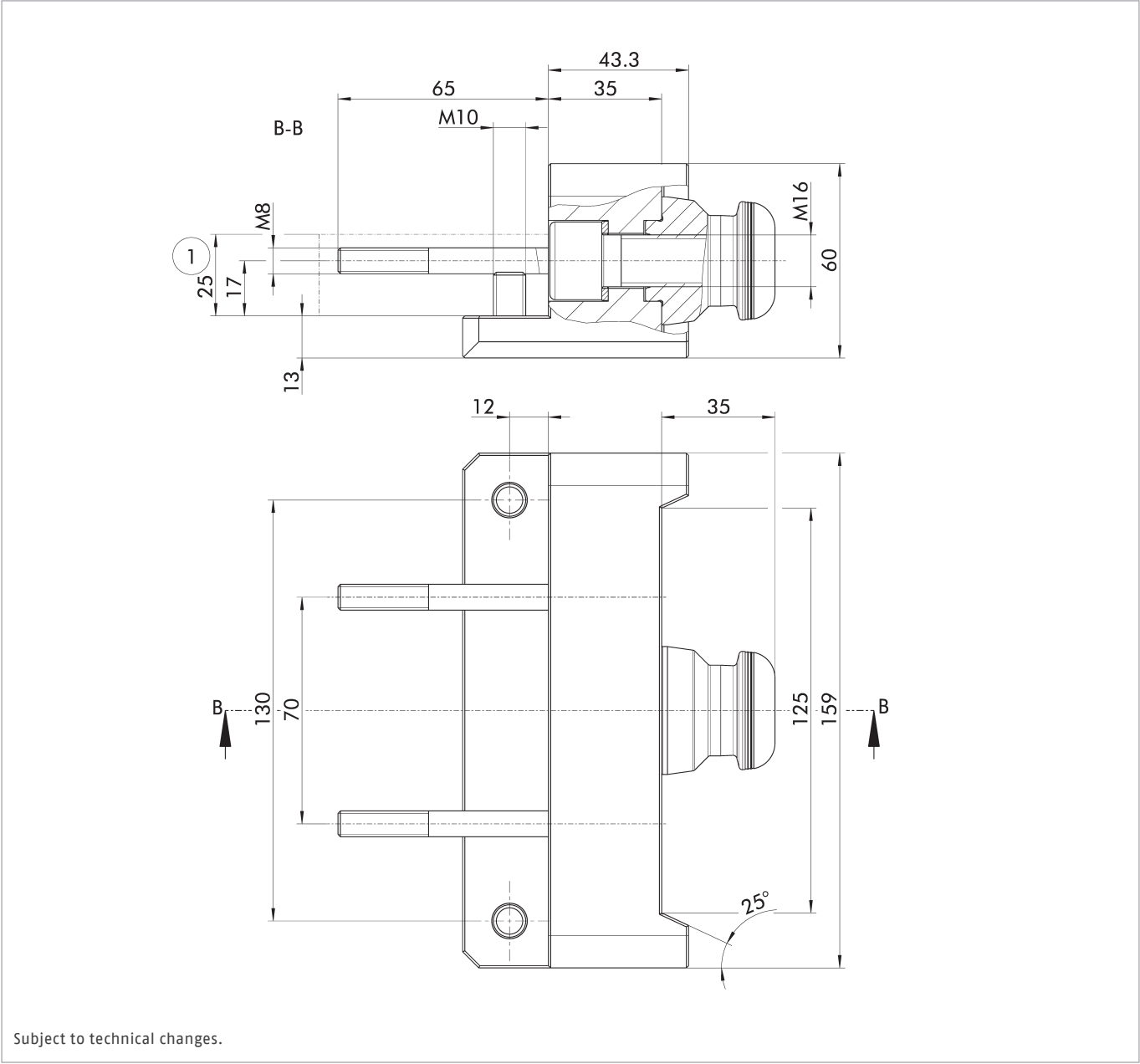
Suitable for robot module NSR 160

Scope of delivery

Pallet coupling, clamping pin, mounting screws, cover caps, operating manual

Technical data

Description	ID	Material	Max. pallet size [mm]	Weight [kg]
PKL-K 160	1642386	Aluminum	500 x 500	1.2



① Minimum plate thickness

Pallet coupling

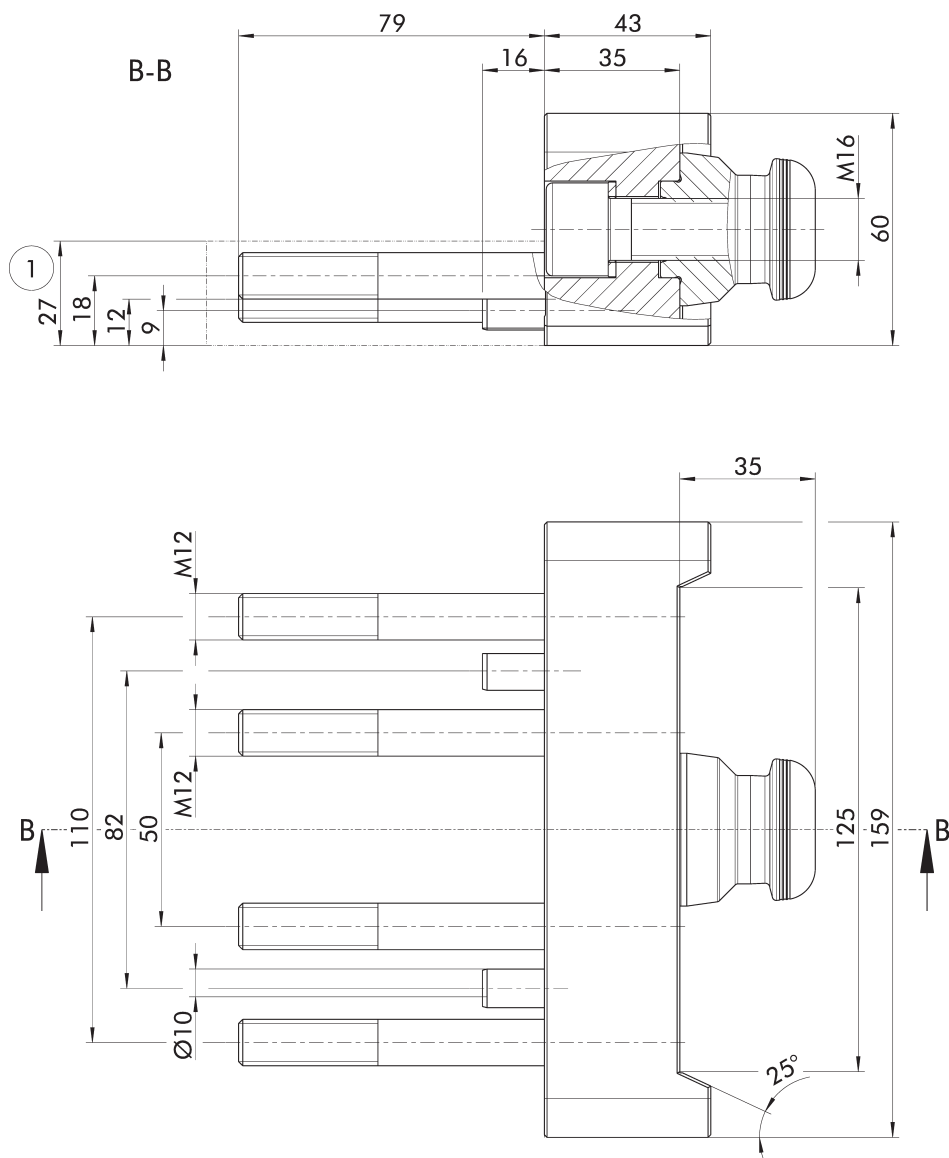
Suitable for robot module NSR 160

Scope of delivery

Pallet coupling, clamping pin, mounting screws, cover caps, operating manual

Technical data

Description	ID	Material	Max. pallet size [mm]	Weight [kg]
PKL 160 Lean	40103658	Aluminum	500 x 500	1.6



Subject to technical changes.

① Minimum plate thickness

Robot module

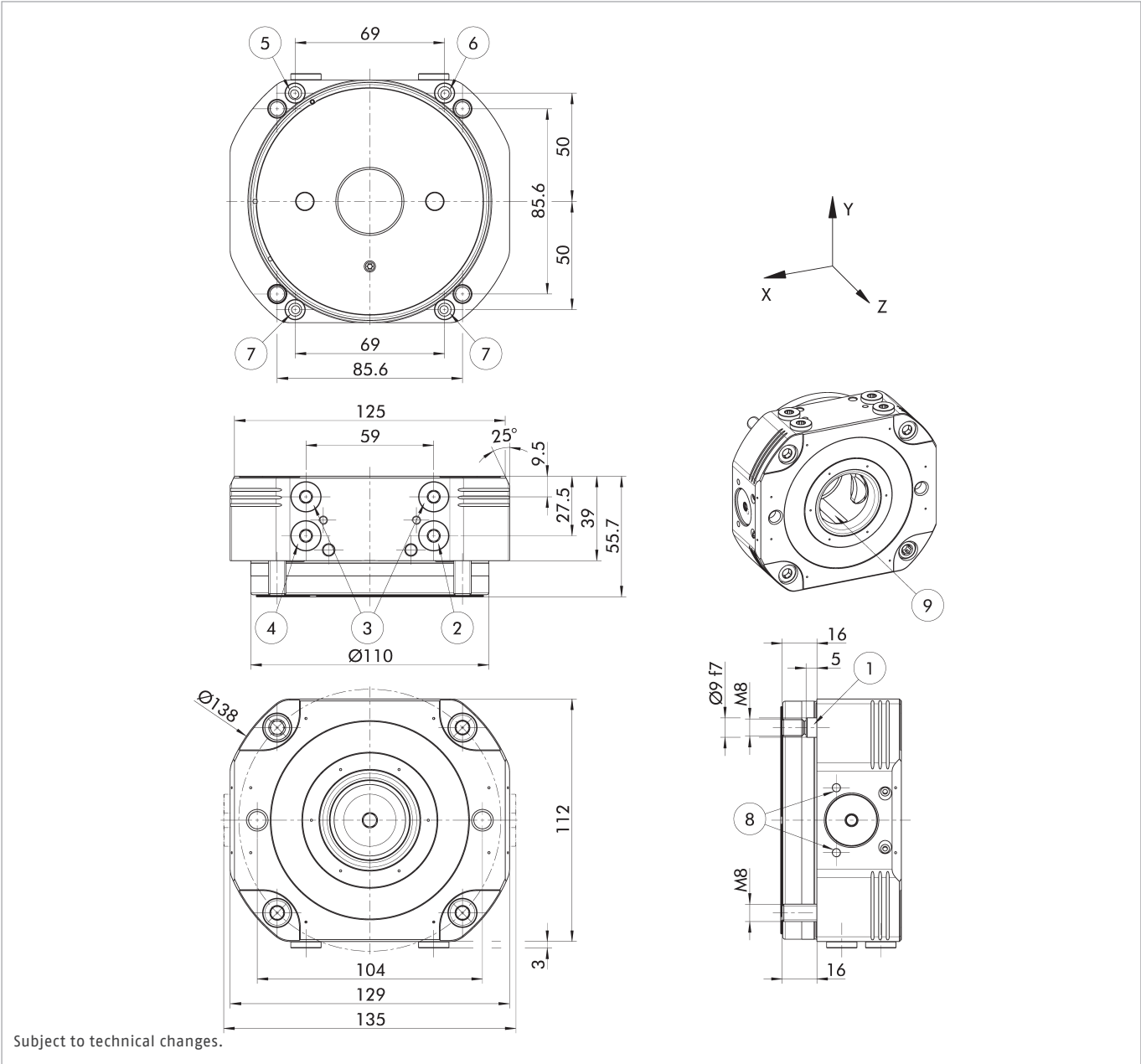
Made of hardened stainless steel with matching clamping pin interface SPA 40

Scope of delivery

Robot module, mounting screws, fitting screw, O-rings, operating manual; without AFS3-R IOL monitoring unit

Technical data

Description	ID	Pull-down force [kN]	Pull-down force with turbo [kN]	Unlocking pressure [bar]	Repeat accuracy [mm]	Max. moment Mx [Nm]	Max. moment Mz [Nm]	Weight [kg]
NSR3 138	1492479	8	28	6	< 0.02	1500	1600	3.8



- ① Fitting screw for positional orientation
- ② Unlocking connection via screw connection G1/8
- ③ Air purge connection with cleaning function via screw connection G1/8 (2 bar)
- ④ Turbo connection via screw connection G1/8
- ⑤ Hose-free direct connection turbo function
- ⑥ Hose-free direct connection module open
- ⑦ Hose-free direct connection for air purge
- ⑧ Optional: Connection for programmable positioning sensors
- ⑨ Optional: Cone seal

Pallet coupling

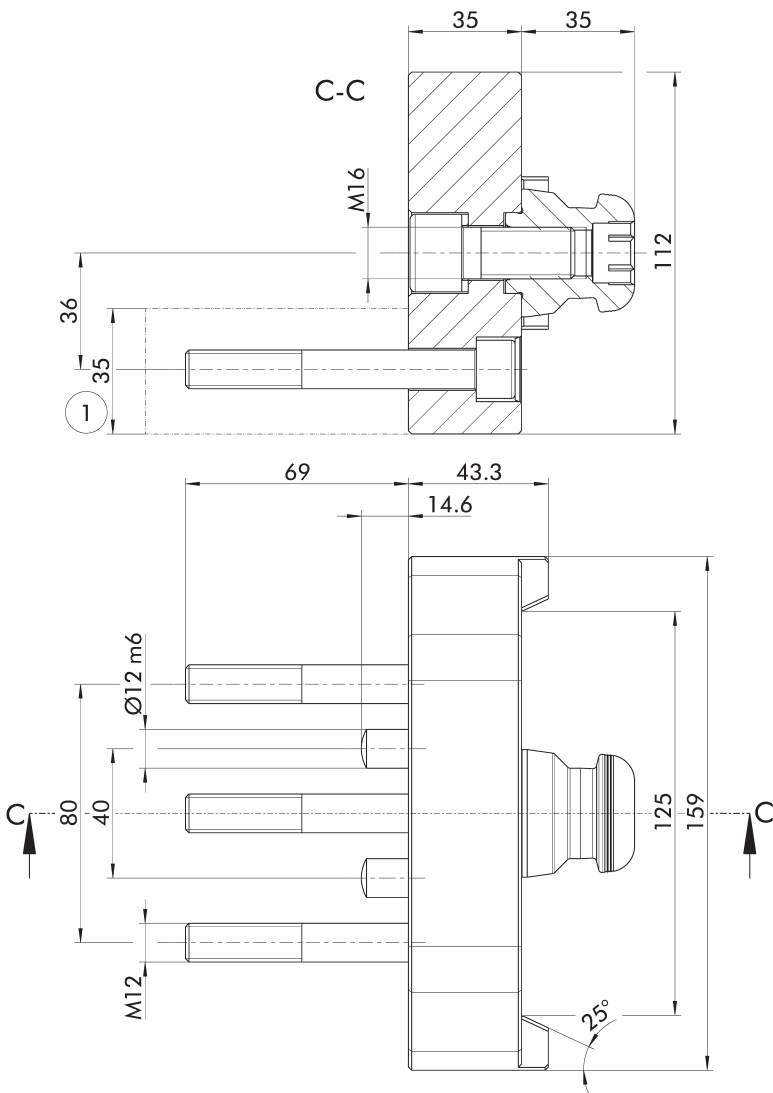
Suitable for robot module NSR3 138

Scope of delivery

Pallet coupling, clamping pin, mounting screws, cover caps, operating manual

Technical data

Description	ID	Material	Max. pallet size [mm]	Weight [kg]
PKL 138	1492512	Aluminum	630 x 630	2.1



Subject to technical changes.

① Minimum plate thickness

Robot module

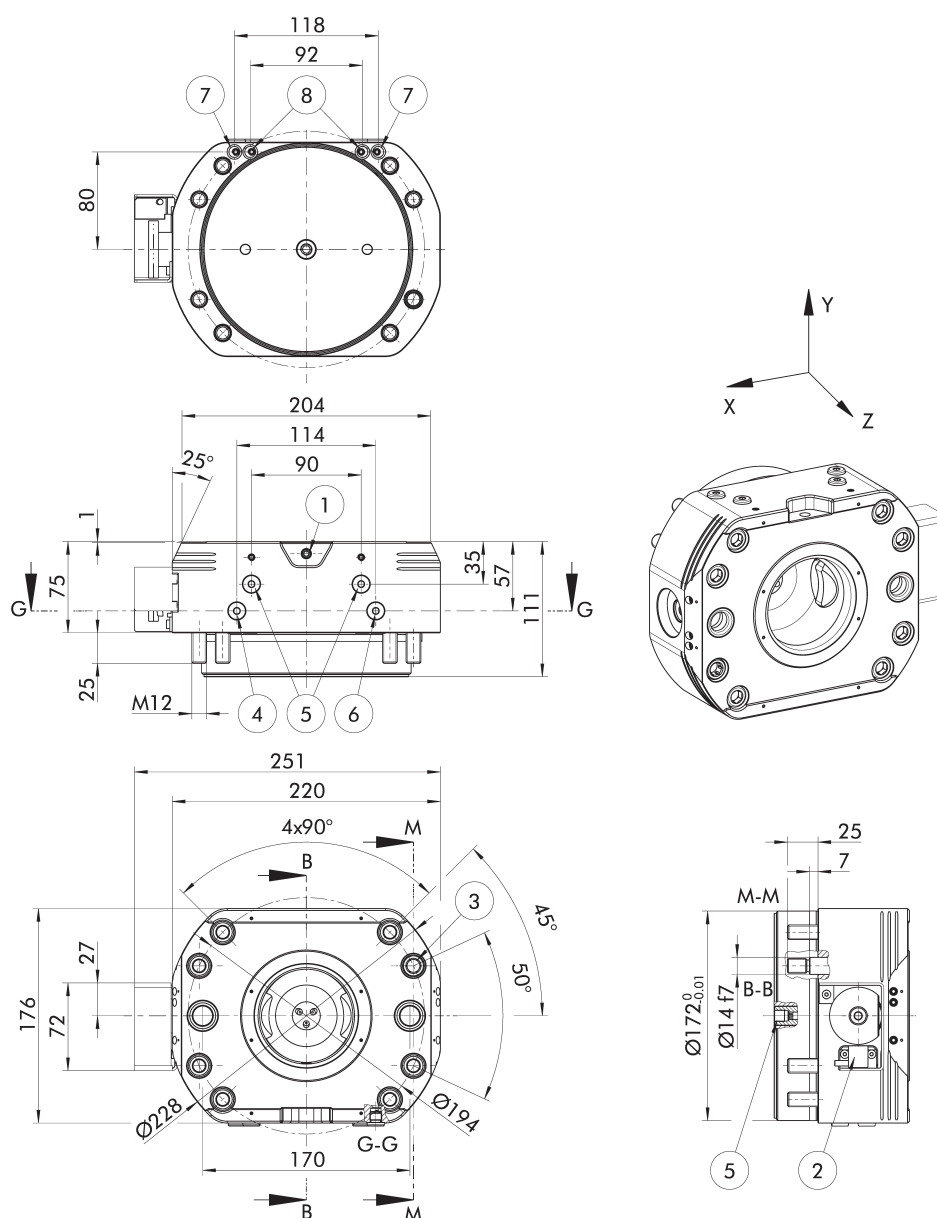
Made of hardened stainless steel with matching clamping pin interface SPA 80

Scope of delivery

Robot module, mounting screws, fitting screw, O-rings, proximity switch, operating manual

Technical data

Description	ID	Pull-down force	Pull-down force with turbo	Unlocking pressure	Repeat accuracy	Max. moment Mx	Max. moment Mz	Weight
		[kN]	[kN]	[bar]	[mm]	[Nm]	[Nm]	[kg]
NSR maxi 220	0471940	12	50	6	< 0.05	4000	4000	21



Subject to technical changes.

- ① Inductive proximity switch M8 x 1 (ID 0313425) for pallet presence
- ② Inductive position measuring system for module monitoring
- ③ Fitting screw for positional orientation
- ④ Unlocking connection via screw connection G1/8
- ⑤ Air purge connection with cleaning function via screw connection G1/8 (2 bar)
- ⑥ Turbo connection via screw connection G1/8
- ⑦ Hose-free direct connection
- ⑧ Hose-free direct connection (2 bar)

Pallet coupling

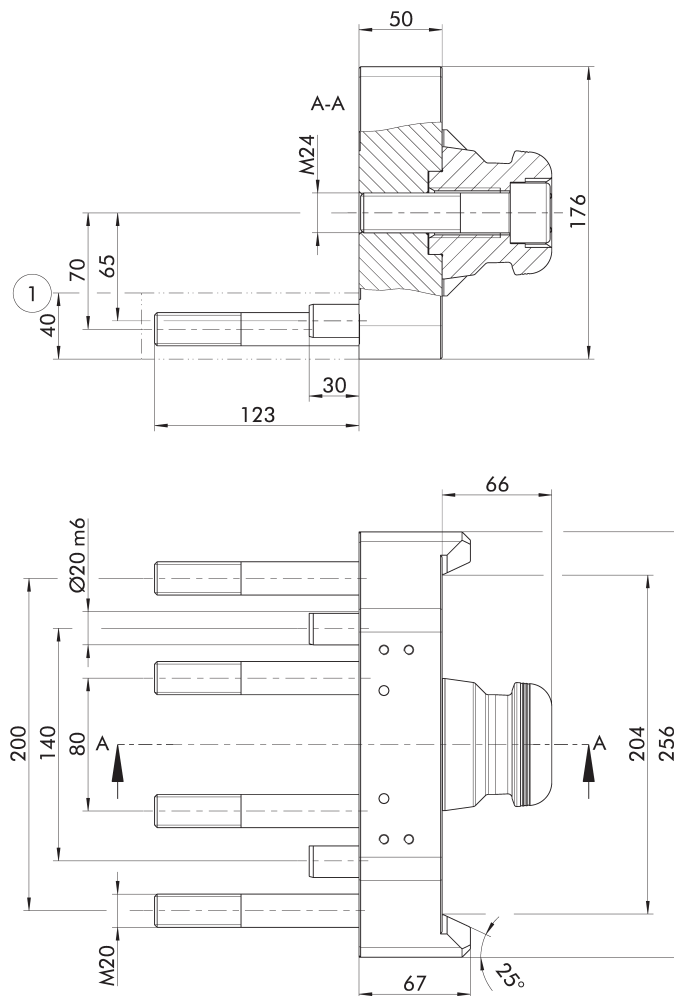
Suitable for robot module NSR maxi 220

Scope of delivery

Pallet coupling, clamping pin, mounting screws, cover caps, operating manual

Technical data

Description	ID	Material	Max. pallet size [mm]	Weight [kg]
PKL maxi 220	0471950	Steel	630 x 630	19.9



Subject to technical changes.

① Minimum plate thickness

Accessories

Clamping pins SPx mikro

Standard clamping pins for form-fit connection of workpieces or devices with the NSE mikro clamping modules.



Suitable for	Description	ID
PKL mikro 60	SPA mikro 10	0436610

Clamping pins SPx mini

Clamping pin for positive connection with NSE mini clamping modules.



Suitable for	Description	ID
PKL mini 100	SPA mini 20	0435610

Clamping pins SPx

Standard clamping pins with M16 thread for form-fit connection of workpieces or devices with NSE3 clamping modules.



Suitable for	Description	ID
PKL 160 PKL-K 160 PKL 160 Lean PKL 138	SPA 40-16	0471064

Clamping pins SPx maxi

Standard clamping pin for form-fit connection of the pallet coupling with the NSR maxi robot module.



Suitable for	Description	ID
PKL maxi 220	SPA 80-30	0471181

Monitoring unit

Integrated monitoring of clamping slide positions, pallet presence and the pressure in the turbo chamber via IO-Link



Suitable for	Description	ID
NSR3 138	AFS3-R IOL 138	1491363

Inductive proximity switches

For monitoring pallet presence



Suitable for	Description	ID
NSR mikro 60	IN 41-S-M8	1325755
NSR mini 100		
NSR 160	IN 50-S-M12	0301575
NSR maxi 220	NI 32	0313425

Magnetic switches

For monitoring the clamping positions module opened and closed.



Suitable for	Description	ID
NSR mikro 60		
NSR mini 100	MMS 22-S-M8-PNP	0301032
NSR 160	MMS 22-S-M8-PNP-SA	0301042

Accessories media coupling

Adapter flange for robot module

Used as a connecting element for robot, robot module, and coupling nipple. The adapter flange is available upon request and needs to be adjusted to the respective robot interface.



Description

FFA-NSR

Coupling nipple for robot module

With one-way media transfer for actuating clamping stations and clamping devices via the appropriate coupling strip.



Description

ID

MDR-NSR-1

1350336

Coupling strip for clamping pallet

With one-way mounting for the transmission of compressed air from the robot module to the clamping device.



Description

Min. coupling force
N

ID

MDR-PAL-1

94

1440495

Coupling strip for clamping station

With one-way mounting for the transmission of compressed air from the robot module to the clamping station.



Description

Min. coupling force
N

ID

MDR-NSL-1

94

1350331

Coupling nipple for robot module

With two-way media transfer for actuating clamping stations and clamping devices via the appropriate coupling strip.



Description

ID

MDR-NSR-2

1350334

Coupling strip for clamping pallet

With two-way mounting for the transmission of compressed air from the robot module to the clamping device.



Description

Min. coupling force
N

ID

MDR-PAL-2

188

1426829

Coupling strip for clamping station

With two-way mounting for the transmission of compressed air from the robot module to the clamping station.



Description

Min. coupling force
N

ID

MDR-NSL-2

188

1350323



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