



Superior Clamping and Gripping



Product Information

Long-stroke gripper PHL 40

Flexible. Precise. Powerful.

Long-stroke gripper PHL

2-finger parallel gripper with long jaw stroke for large parts and/or a broad range of parts

Field of application

Optimum standard solution for many fields of application. Universal application in clean and slightly dirty surroundings in machine building and plant building industry, assembly and handling as well as automotive industry.



Advantages – Your benefits

Modular with two alternative guidances for optimal adaption to your application

High maximum moments possible suitable for using long gripper fingers

Double piston rack and pinion principle for centric clamping

Fastening at one gripper side in two screw directions for universal and flexible gripper assembly

Air supply via hose-free direct connection or screw connections for flexible pressure supply in all automated systems

Comprehensive sensor accessory program for versatile querying possibilities and stroke position monitoring

Stroke versions for highest flexibility



Sizes
Quantity: 5



Weight
1.38 .. 23.55 kg



Gripping force
390 .. 4630 N



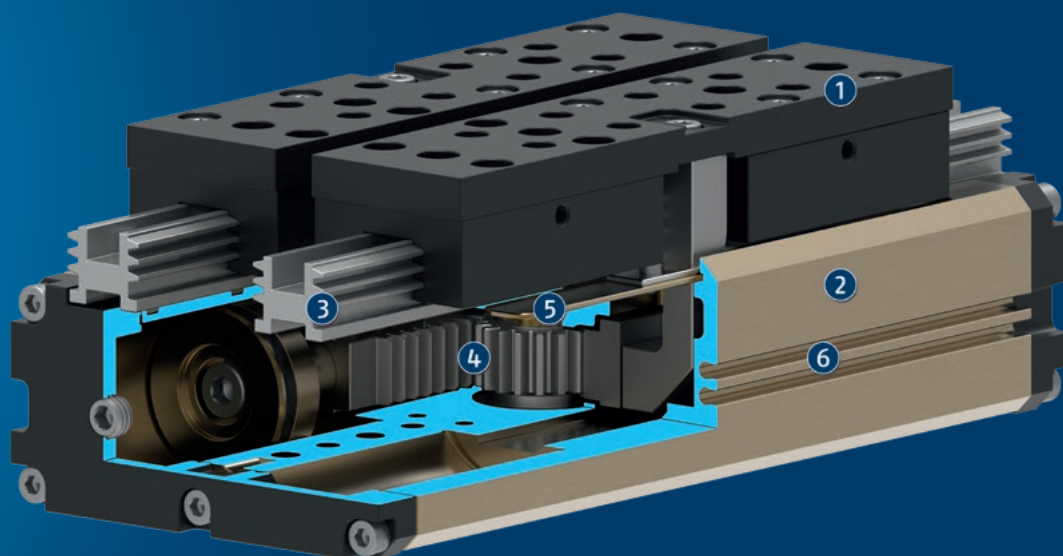
Stroke per jaw
30 .. 160 mm



Workpiece weight
1.95 .. 15.5 kg

Functional description

By pressure actuation of the opposing piston, the base jaws are guided by a carrier on the piston, and are set in motion. The synchronization of the jaw stroke is done with a rack and pinion principle.



- ① **Base Jaw**
for the connection of workpiece-specific gripper fingers
- ② **Housing**
is weight-optimized due to the use of high-strength aluminum alloy
- ③ **Multi-tooth guidance**
highly loadable, nearly backlash-free base jaw guidance for long finger lengths

- ④ **Kinematics**
pinion and rack principle for centric clamping, even at large strokes
- ⑤ **Dust cover**
along the whole guidance length against coarse dirt
- ⑥ **Sensor system**
Brackets for proximity switches and adjustable control cams in the housing

General notes about the series

Operating principle: Double piston rack and pinion principle

Housing material: Aluminum (extruded profile)

Base jaw material: Aluminum alloy, anodized

Actuation: pneumatic, with filtered compressed air as per ISO 8573-1:2010 [7:4:4].

Warranty: 24 months

Scope of delivery: Centering sleeves, O-rings for direct connection, assembly instructions (operating manual with declaration of incorporation is available online)

Gripping force maintenance: possible by using the version with mechanical gripping force maintenance or pressure maintenance valve SDV-P

Gripping force: is the arithmetic sum of the individual force applied to each jaw at distance P (see illustration).

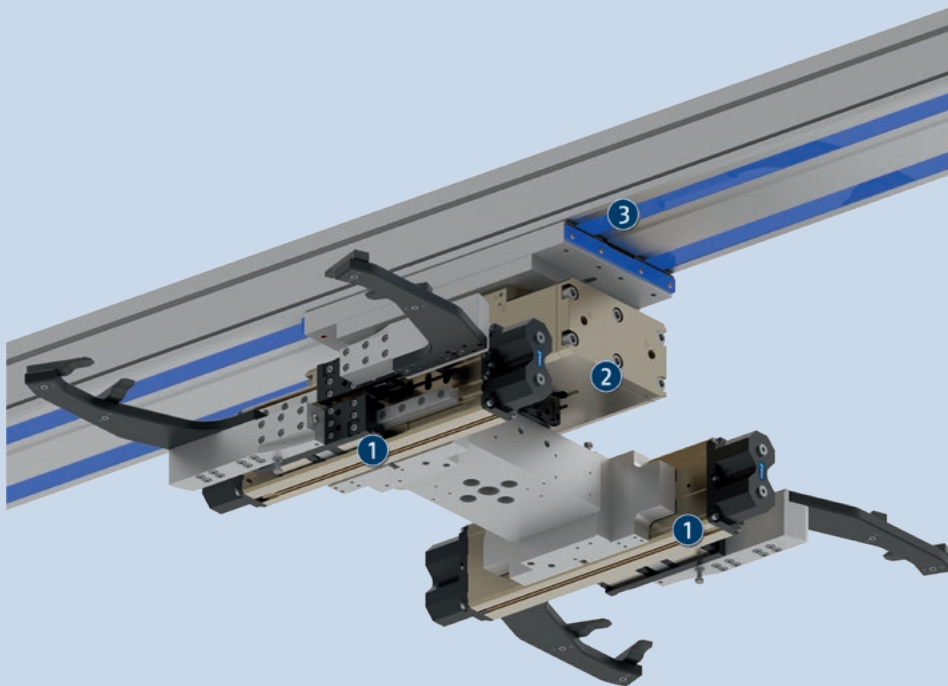
Finger length: is measured from the reference surface as the distance P in direction to the main axis.

The maximum permissible finger length applies until the nominal operating pressure is achieved. With higher pressures, the finger length must be reduced proportionally to the nominal operating pressure.

Repeat accuracy: is defined as a distribution of the end Position for 100 consecutive strokes.

Workpiece weight: is calculated for force-fit gripping with a coefficient of static friction of 0.1 and a safety factor of 2 against workpiece slippage at acceleration due to gravity g. For form-fit or capture gripping, there are significantly higher permissible workpiece weights.

Closing and opening times: are purely the times that the base jaws or fingers are in motion. Valve switching times, hose fill times, or PLC reaction times are not included, and are to be considered when cycle times are calculated.



Application example

Turning unit for reorientation of large workpieces

- ❶ 2-finger long-stroke gripper PHL
- ❷ Universal rotary actuator SRU-plus

- ❸ Flat linear module Delta with toothed-belt drive

SCHUNK offers more ...

The following components make the product PHL even more productive – the suitable addition for the highest functionality, flexibility, reliability, and controlled production.



Quick change system



Universal swivel unit



Pressure maintenance valve



Universal intermediate jaw



Inductive proximity switches



Magnetic switches



Finger blank



Jaw quick-change system

① For more information on these products can be found on the following product pages or at schunk.com. Please contact us: SCHUNK technical hotline +49-7133-103-2696

Options and special information

Sliding bearing version PHL-G: with proven SCHUNK multi-tooth guidance for robust and reliable applications

Roller bearing version PHL-W: with play-free, pre-loaded profile rail guides for higher precision, even larger loads, and longer finger lengths, and at the same time with an increased gripping force

Mechanical gripping force maintenance: ensures a minimum gripping force in the event of a pressure loss This acts as the closing force in the S version. The design of the top jaws means that they can also be used as an opening force.

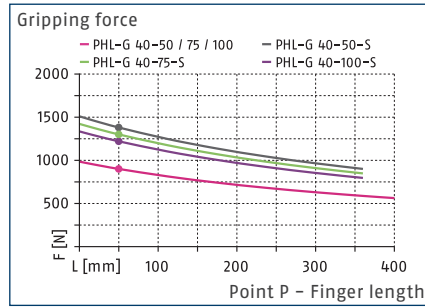
High-temperature version V/HT: for use in hot environments

Additional stroke versions: available in three stroke variants as standard

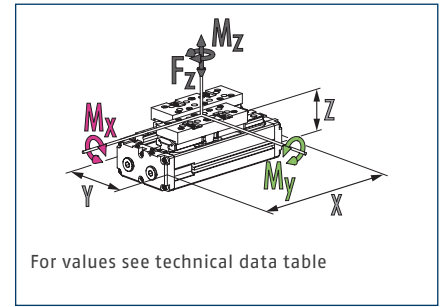
Additional versions: Various options can be combined with each other. Numerous additional options are also available – just tell us what your task is!



Gripping force



Dimensions and maximum loads



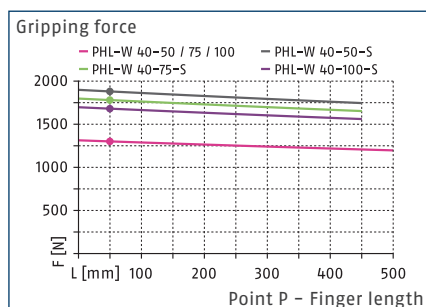
PHL-G technical data

Description		PHL-G 40-050	PHL-G 40-050-S	PHL-G 40-075	PHL-G 40-075-S	PHL-G 40-100	PHL-G 40-100-S
ID		0308160	0308163	0308161	0308164	0308162	0308165
Stroke per jaw	[mm]	50	50	75	75	100	100
Closing/opening force	[N]	900/900	1380/-	900/900	1300/-	900/900	1220/-
Min. spring force	[N]		480		400		320
Weight	[kg]	4.72	5.57	5.54	7.1	6.35	7.49
Recommended workpiece weight	[kg]	4.5	4.5	4.5	4.5	4.5	4.5
Fluid consumption double stroke	[cm³]	302	559	430	686	558	814
Min./nom./max. operating pressure	[bar]	2/6/8	4/6/6.5	2/6/8	4/6/6.5	2/6/8	4/6/6.5
Closing/opening time	[s]	0.32/0.32	0.34/0.58	0.42/0.42	0.45/0.78	0.53/0.53	0.57/0.97
Max. permissible finger length	[mm]	400	360	400	360	400	360
Max. permissible mass per finger	[kg]	5	5	5	5	5	5
Protection class IP		41	41	41	41	41	41
Min./max. ambient temperature	[°C]	5/90	5/90	5/90	5/90	5/90	5/90
Repeat accuracy	[mm]	0.02	0.02	0.02	0.02	0.02	0.02
Dimensions X x Y x Z	[mm]	247 x 110 x 84.8	350 x 110 x 84.8	320 x 110 x 84.8	423 x 110 x 84.8	395 x 110 x 84.8	498 x 110 x 84.8
Moments M _x max./M _y max./M _z max.	[Nm]	83/290/121	83/290/121	100/290/121	100/290/121	117/290/121	117/290/121
Forces F _i max.	[N]	3000	3000	3000	3000	3000	3000

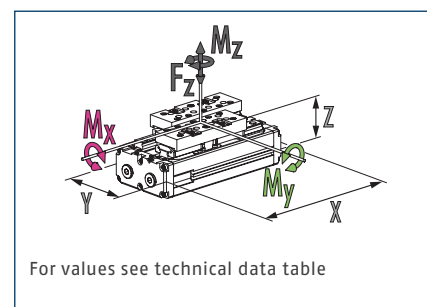
- ① In certain circumstances, the full gripping force as per the data table will only become effective for the PHL-G version, equipped with floating bearings after around 100 gripping cycles.
- ① The specified torques and forces are static values, apply for each base jaw, and may occur simultaneously. M_y may arise in addition to the moment generated by the gripping force itself.



Gripping force



Dimensions and maximum loads

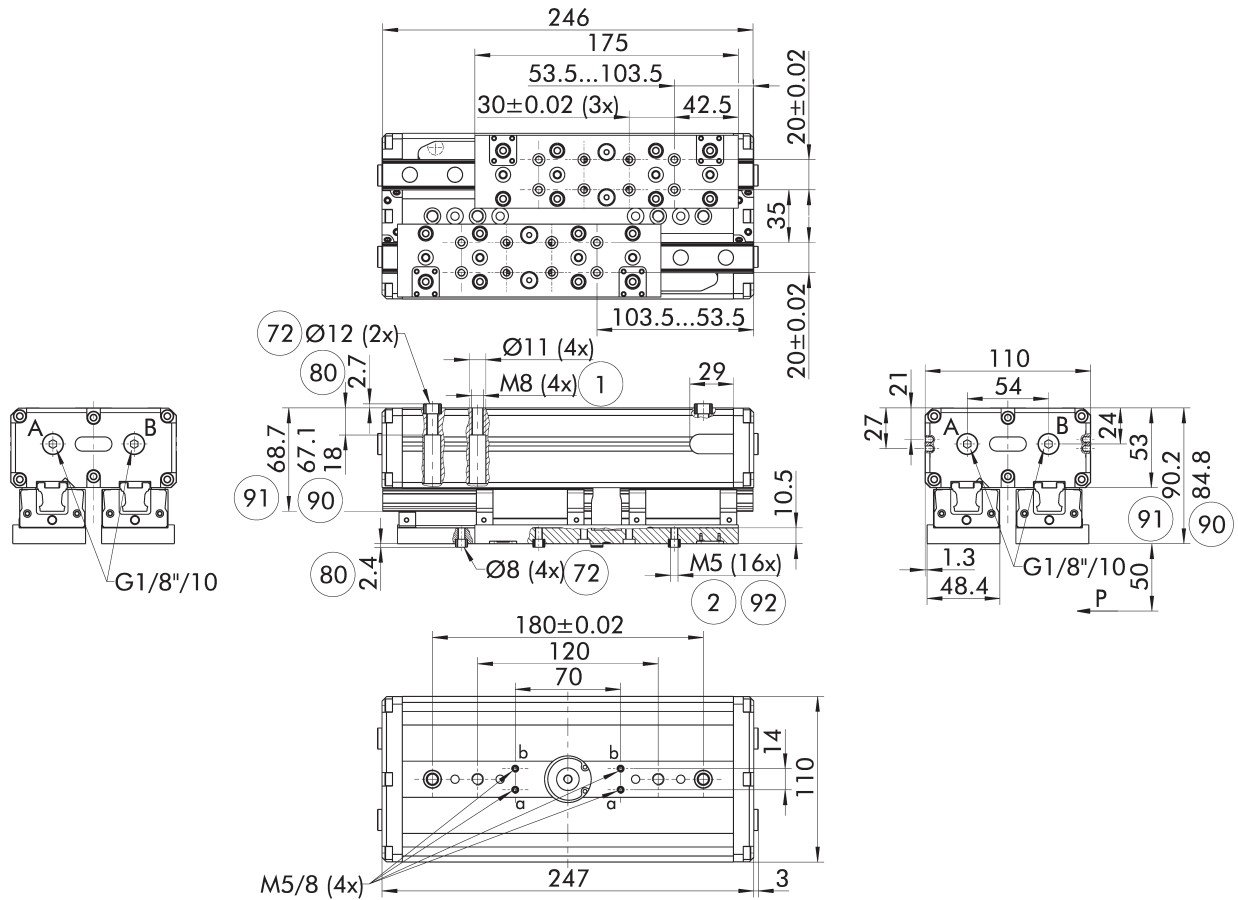


PHL-W technical data

Description		PHL-W 40-050	PHL-W 40-050-S	PHL-W 40-075	PHL-W 40-075-S	PHL-W 40-100	PHL-W 40-100-S
ID		0308170	0308173	0308171	0308174	0308172	0308175
Stroke per jaw	[mm]	50	50	75	75	100	100
Closing/opening force	[N]	1300/1300	1880/-	1300/1300	1780/-	1300/1300	1680/-
Min. spring force	[N]		580		480		380
Weight	[kg]	5.71	6.42	6.53	8.05	7.34	8.39
Recommended workpiece weight	[kg]	6.5	6.5	6.5	6.5	6.5	6.5
Fluid consumption double stroke	[cm³]	302	559	430	686	558	814
Min./nom./max. operating pressure	[bar]	2/6/8	4/6/6.5	2/6/8	4/6/6.5	2/6/8	4/6/6.5
Closing/opening time	[s]	0.28/0.28	0.3/0.51	0.38/0.38	0.4/0.68	0.47/0.47	0.49/0.85
Max. permissible finger length	[mm]	500	450	500	450	500	450
Max. permissible mass per finger	[kg]	5	5	5	5	5	5
Protection class IP		41	41	41	41	41	41
Min./max. ambient temperature	[°C]	5/90	5/90	5/90	5/90	5/90	5/90
Repeat accuracy	[mm]	0.02	0.02	0.02	0.02	0.02	0.02
Dimensions X x Y x Z	[mm]	247 x 110 x 90.2	350 x 110 x 90.2	320 x 110 x 90.2	423 x 110 x 90.2	395 x 110 x 90.2	498 x 110 x 90.2
Moments M _x max./M _y max./M _z max.	[Nm]	100/350/121	100/350/121	117/350/121	117/350/121	133/350/121	133/350/121
Forces F _i max.	[N]	3000	3000	3000	3000	3000	3000

- ① In certain circumstances, the full gripping force as per the data table will only become effective for the PHL-G version, equipped with floating bearings after around 100 gripping cycles.
- ① The specified torques and forces are static values, apply for each base jaw, and may occur simultaneously. M_y may arise in addition to the moment generated by the gripping force itself.

Main view PHL 40-050



The drawing shows the gripper in the basic version with closed jaws, without dimensional consideration of the options described below.

① The SDV-P pressure maintenance valve can be used as a gripping force maintenance device (see catalog section on accessories).

A, a Main / direct connection, gripper opening

B, b Main / direct connection, gripper closing

① Gripper connection

② Finger connection

72 Fit for centering sleeves

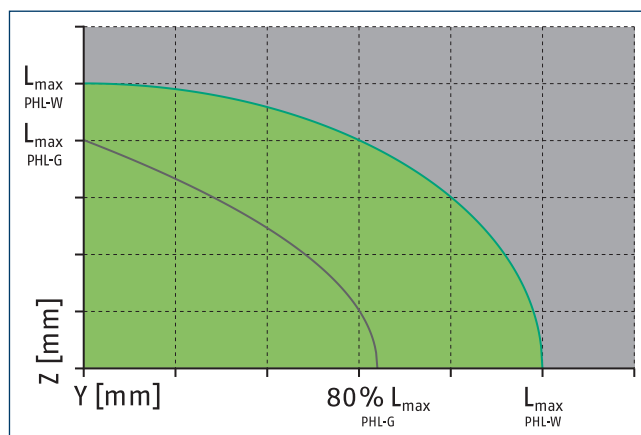
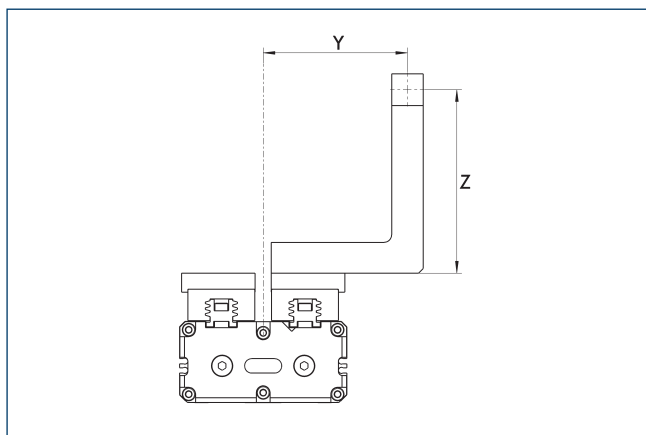
80 Depth of the centering sleeve hole in the counter part

90 Height of version G

91 Height of version W

92 Min. six screws per base jaw

Maximum permitted finger projection

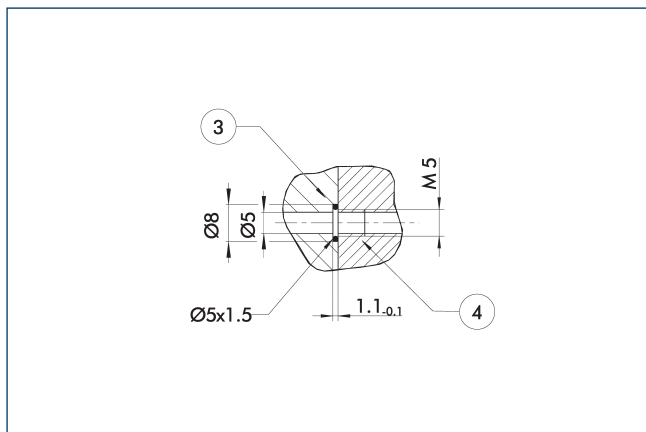


■ Permitted range

■ Inadmissible range

L_{max} is equivalent to the maximum permitted finger length, see the technical data table.

Hose-free direct connection M5

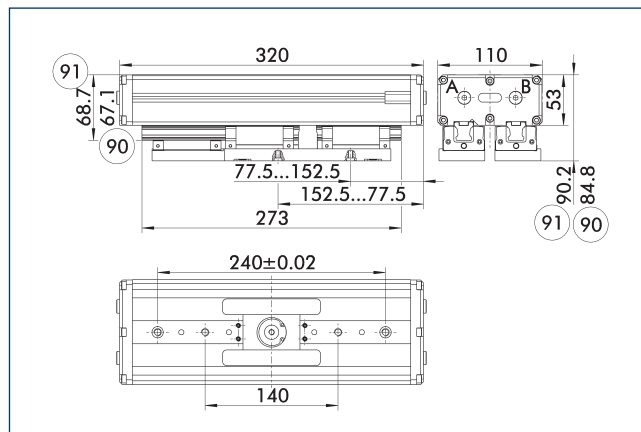


③ Adapter

④ Grippers

The direct connection is used for supplying compressed air without hoses. Instead, the pressure medium is fed through bore-holes in the mounting plate.

Stroke version PHL 40-075

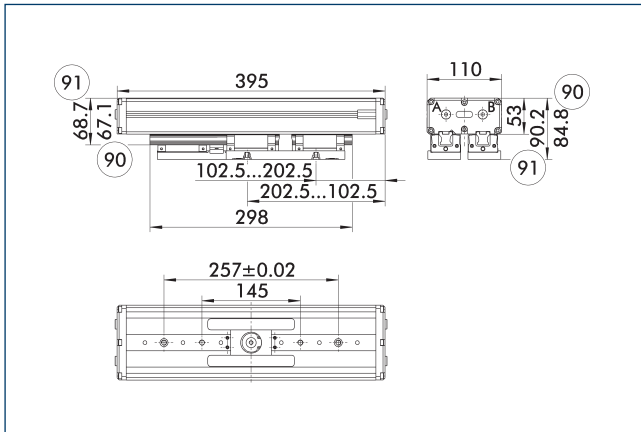


90 Height of version G

91 Height of version W

The drawing shows changes in dimensions of the version with a different stroke compared to the version shown in the main view.

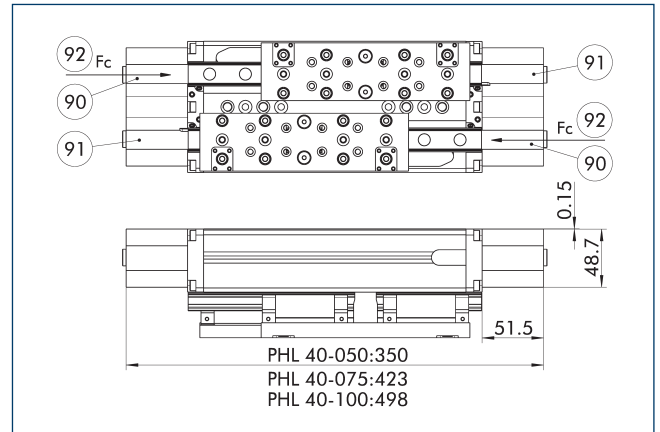
Stroke version PHL 40-100



- 90 Height of version G 91 Height of version W

The drawing shows changes in dimensions of the version with a different stroke compared to the version shown in the main view.

Gripping force maintenance S

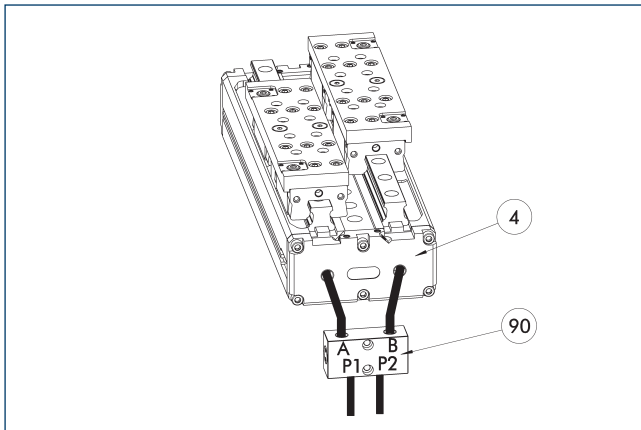


- 90 Piston chamber with spring 92 Direction of force of the pressure springs
91 Piston chamber without spring

The mechanical gripping force maintenance ensures a minimum clamping force in the event of a pressure drop. This acts as the closing force in the S variant. The design of the top jaws means that they can also be used as an opening force. Besides this, the gripping force maintenance can be used to increase the gripping force.

- ① The gripper is shown in the basic position, closed by springs.

SDV-P pressure maintenance valve



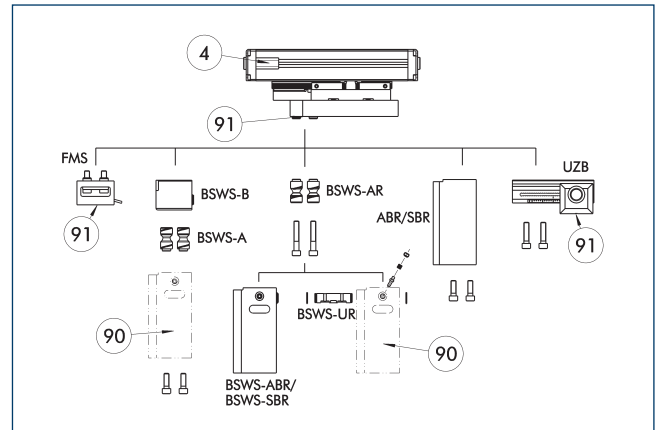
- 4 Grippers 90 SDV-P pressure maintenance valve

The SDV-P pressure maintenance valve ensures in emergency STOP situations that the pressure in the piston chamber of pneumatic gripper, swivel, linear, and quick-change modules is temporarily maintained.

Description	ID	Recommended hose diameter
		[mm]
Pressure maintenance valve		
SDV-P 04	0403130	6
SDV-P 07	0403131	8
Pressure maintenance valve with air bleed screw		
SDV-P 04-E	0300120	6
SDV-P 07-E	0300121	8

- ① In order to achieve the specified closing and opening time for each gripper variant, the recommended hose diameter must be used. The direct allocation of the respective variant of the gripper for the respective SDV-P can be found at schunk.com.

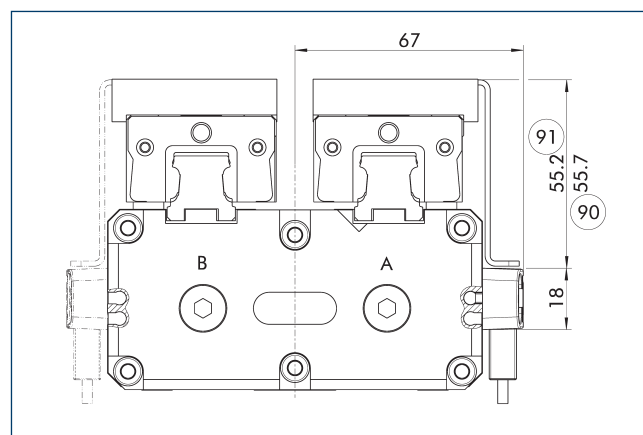
Intermediate jaw interface



- 4 Grippers 91 Uniform screw connection pattern
90 Customized gripper fingers

By using the intermediate jaw, you have the possibility of directly connecting a wide range of accessories directly. This includes force-measuring jaws, jaw quick-change systems, finger blanks, and universal intermediate jaws.

Attachment kit for proximity switch



- ⑨⑩ Height of version G ⑨⑪ Height of version W

End position monitoring can be mounted with an attachment kit.

Description	ID	
Attachment kit for proximity switch		
AS-PHL 40-IN80	0308832	

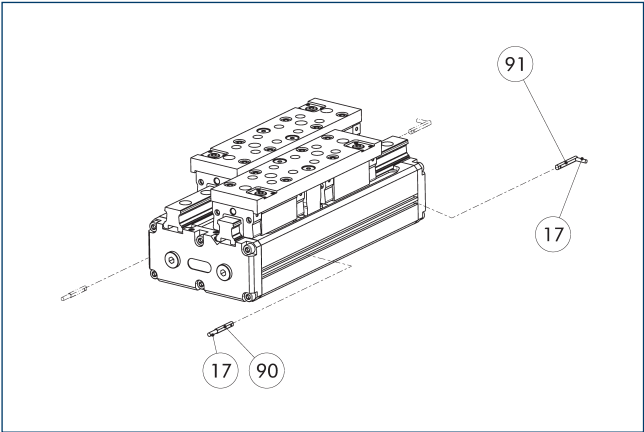
- ① This attachment kit needs to be ordered optionally as an accessory.

This diagram shows the T8000 tool head assembly in an exploded view. The main component is a large, rectangular tool head with a complex internal structure. It features a top plate with multiple circular holes and a side plate with a vertical slot. Two cylindrical components, likely nozzles or guides, are shown being inserted into the side plate. A separate assembly of two small, square components is shown being inserted into the top plate. The diagram is a technical line drawing with dashed lines indicating the assembly path.

End position monitoring can be mounted with an attachment kit.

① Two sensors (closer/S) are required for each unit and extension cables are available as an option. This attachment kit needs to be ordered optionally as an accessory. For sensor cables, note the minimum permissible bending radii. These are generally 35 mm.

Electronic magnetic switch MMS



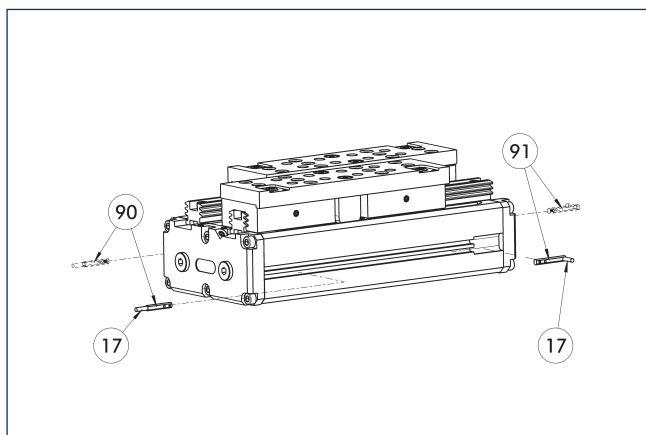
- 17 Cable outlet 91 Sensor MMS 22...-SA
90 Sensor MMS 22..

End position monitoring for mounting in the C-slot.

Description	ID	Often combined
Electronic magnetic switch		
MMS 22-S-M8-PNP	0301032	●
MMSK 22-S-PNP	0301034	
Electronic magnetic switches with lateral cable outlet		
MMS 22-S-M8-PNP-SA	0301042	●
MMSK 22-S-PNP-SA	0301044	
Reed Switches		
RMS 22-S-M8	0377720	●
Cable extension		
KV BW08-SG08 3P-0030-PNP	0301495	
KV BW08-SG08 3P-0100-PNP	0301496	
KV BW08-SG08 3P-0200-PNP	0301497	●
clip for plug/socket		
CLI-M8	0301463	
Connection cables		
KA BG08-L 3P-0300-PNP	0301622	●
KA BG08-L 3P-0500-PNP	0301623	
KA BW08-L 3P-0300-PNP	0301594	
KA BW08-L 3P-0500-PNP	0301502	
Sensor distributor		
V2-M8	0301775	●
V4-M8	0301746	
V8-M8	0301751	
Wireless sensor system		
RSS-T2	0377715	
RSS-T2-US/CA	0377717	

① Two sensors are required per unit for monitoring two positions. On option, extension cables and sensor distributors are available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor system.

Programmable magnetic switch MMS 22-PI1



- 17 Cable outlet
91 Sensor MMS 22 ..-PI1-...-SA
90 Sensor MMS 22 PI1-...

Position monitoring with one programmable position per sensor and integrated electronic system in the sensor. Can be programmed using MT magnetic teaching tool (included in the scope of delivery) or ST plug teaching tool (optional). End position monitoring for mounting in the C-slot. If the ST plug teaching tools are listed in the table provided, teaching is only possible with the ST teaching tools.

Description	ID	Often combined
Programmable magnetic switch		
MMS 22-PI1-S-M8-PNP	0301160	●
MMSK 22-PI1-S-PNP	0301162	
Programmable magnetic switch with stainless steel housing		
MMS 22-PI1-S-M8-PNP-HD	0301110	●
MMSK 22-PI1-S-PNP-HD	0301112	
Programmable magnetic switch with lateral cable outlet		
MMS 22-PI1-S-M8-PNP-SA	0301166	●
MMSK 22-PI1-S-PNP-SA	0301168	

- ① Two sensors are required per unit for monitoring two positions. On option, extension cables and sensor distributors are available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor system.

SCHUNK GmbH & Co. KG
Spann- und Greiftechnik

Bahnhofstr. 106 - 134
D-74348 Lauffen/Neckar
Tel. +49-7133-103-0
Fax +49-7133-103-2399
info@de.schunk.com
schunk.com



Jens Lehmann, German goalkeeper legend, SCHUNK brand ambassador since 2012 for safe, precise gripping and holding.
schunk.com/Lehmann