



Hand in hand for tomorrow



Product data sheet

Gripper for small components MPZ 30

MPZ

Gripper for small components

Precise. Compact. Reliable.

Gripper for small components MPZ

Small 3-finger centric gripper with base jaws guided on T-slots

Field of application

for universal use in clean to slightly dirty working environments, especially suitable for gripping small workpieces

Advantages – Your benefits

T-slot guidance for precise gripping at high moment loads

Finger position monitoring also possible via FPS

Air supply via hose-free direct connection or screw connections for flexible pressure supply in all automated systems

Compact dimensions for minimal interfering contours in handling



Sizes
Quantity: 6



Weight
0.01 .. 0.29 kg



Gripping force
20 .. 310 N



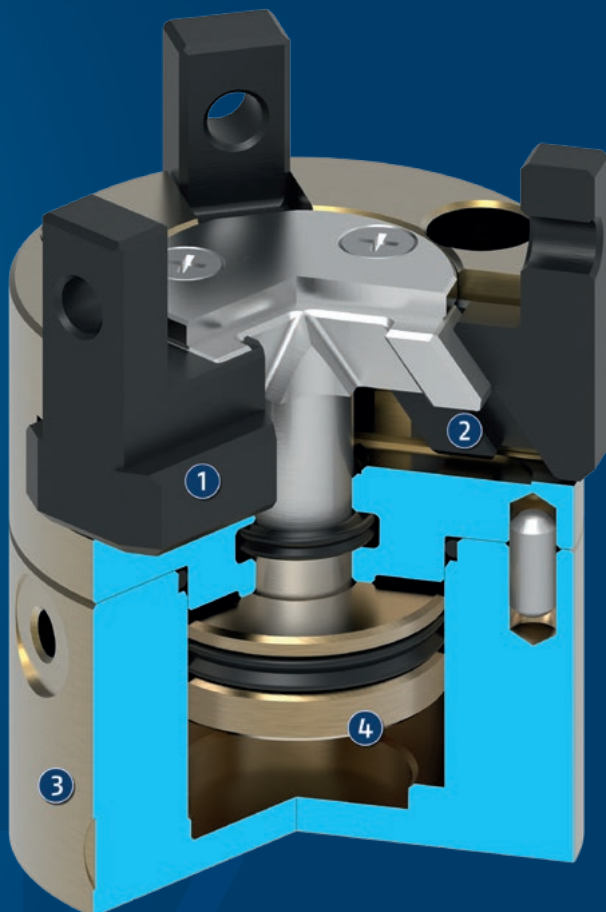
Stroke per jaw
1 .. 5 mm



Workpiece weight
0.05 .. 1.15 kg

Functional description

The piston is moved up and down by compressed air.
The angled active surfaces of the wedge-hook produce a synchronized, centric jaw movement.



- ① **T-slot guidance**
for precise gripping with high moment loads
- ② **Wedge-hook design**
for high force transmission and centric gripping

- ③ **Housing**
is weight-optimized due to the use of high-strength aluminum alloy
- ④ **Drive**
pneumatic, efficient, and easy to handle

General notes about the series

Operating principle: Wedge-hook kinematics

Housing material: Aluminum alloy, anodized

Base jaw material: Steel

Actuation: pneumatic, with filtered compressed air as per ISO 8573-1:2010 [7:4:4].

Warranty: 24 months

Service life characteristics: on request

Scope of delivery: Gripper in the ordered variant, accessory kit (centering sleeves, O-rings for direct connection/detailed contents see operating manual) and safety information. Product-specific instructions can be downloaded at schunk.com/downloads-manuals.

Gripping force maintenance: possible by using the version with mechanical gripping force maintenance or pressure maintenance valve SDV-P

Gripping force: is the arithmetic sum of the individual force applied to each jaw at distance P (see illustration).

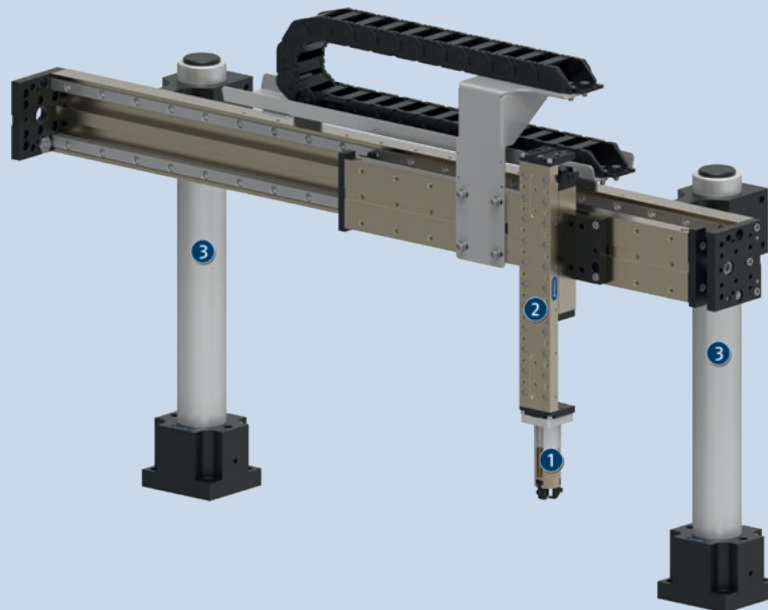
Finger length: is measured from the reference surface as the distance P in direction to the main axis.

The maximum permissible finger length applies until the nominal operating pressure is achieved. With higher pressures, the finger length must be reduced proportionally to the nominal operating pressure.

Repeat accuracy: is defined as a distribution of the end Position for 100 consecutive strokes.

Workpiece weight: is calculated for force-fit gripping with a coefficient of static friction of 0.1 and a safety factor of 2 against workpiece slippage at acceleration due to gravity g. For form-fit or capture gripping, there are significantly higher permissible workpiece weights.

Closing and opening times: are movement times of the base jaws only, without application-specific gripper fingers. Valve switching times, hose fill times, or PLC reaction times are not included, and are to be considered when cycle times are calculated.



Application example

Pneumatically driven 2-axis line gantry with centric gripper for gripping and repositioning small round workpieces.

① 3-finger centric gripper MPZ

② Linear axis LM

③ Pillar assembly system SAS

SCHUNK offers more ...

The following components make the product even more productive – the suitable addition for the highest functionality, flexibility, reliability, and controlled production.



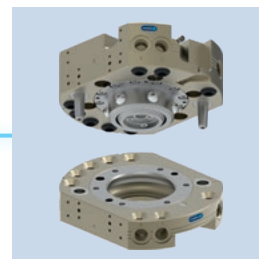
Miniature swivel unit



Linear axis



Pick & Place Unit



Tool changer



Flexible position sensor



Micro valve



Pressure maintenance valve



Finger blank



Magnetic switches

① For more information on these products can be found on the following product pages or at [schunk.com](https://www.schunk.com).

Options and special information

Gripping force maintenance version AS/IS: The mechanical gripping force maintenance version ensures minimum gripping force even in the event of a pressure drop. In the AS/S version this acts as a closing force, in the IS version as an opening force.

Version FPS for flexible position sensor: This version is prepared for the use with the flexible position sensor FPS, and allows monitoring of several gripping positions.

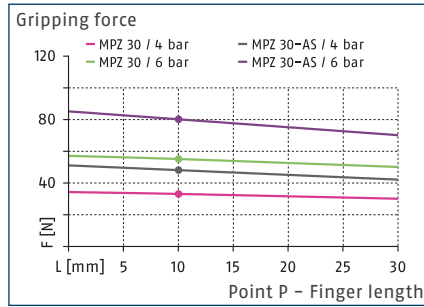
Food-grade lubrication: The product contains food-compliant lubricants as standard. The requirements of EN 1672-2:2020 are not fully met. The relevant NSF certificates are available at <https://info.nsf.org/USDA/Listings.asp> using the lubricant information in the operating manual.

MPZ 30

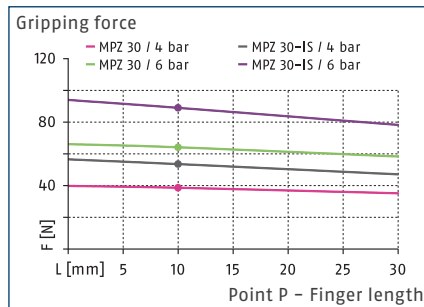
Gripper for small components



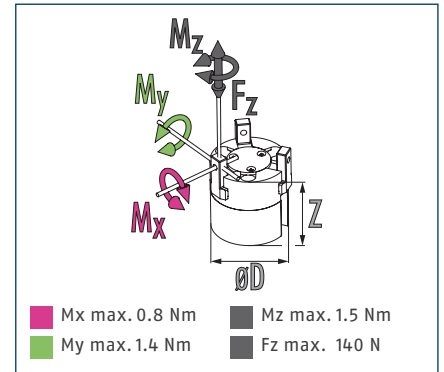
Gripping force O.D. gripping



Gripping force I.D. gripping



Dimensions and maximum loads



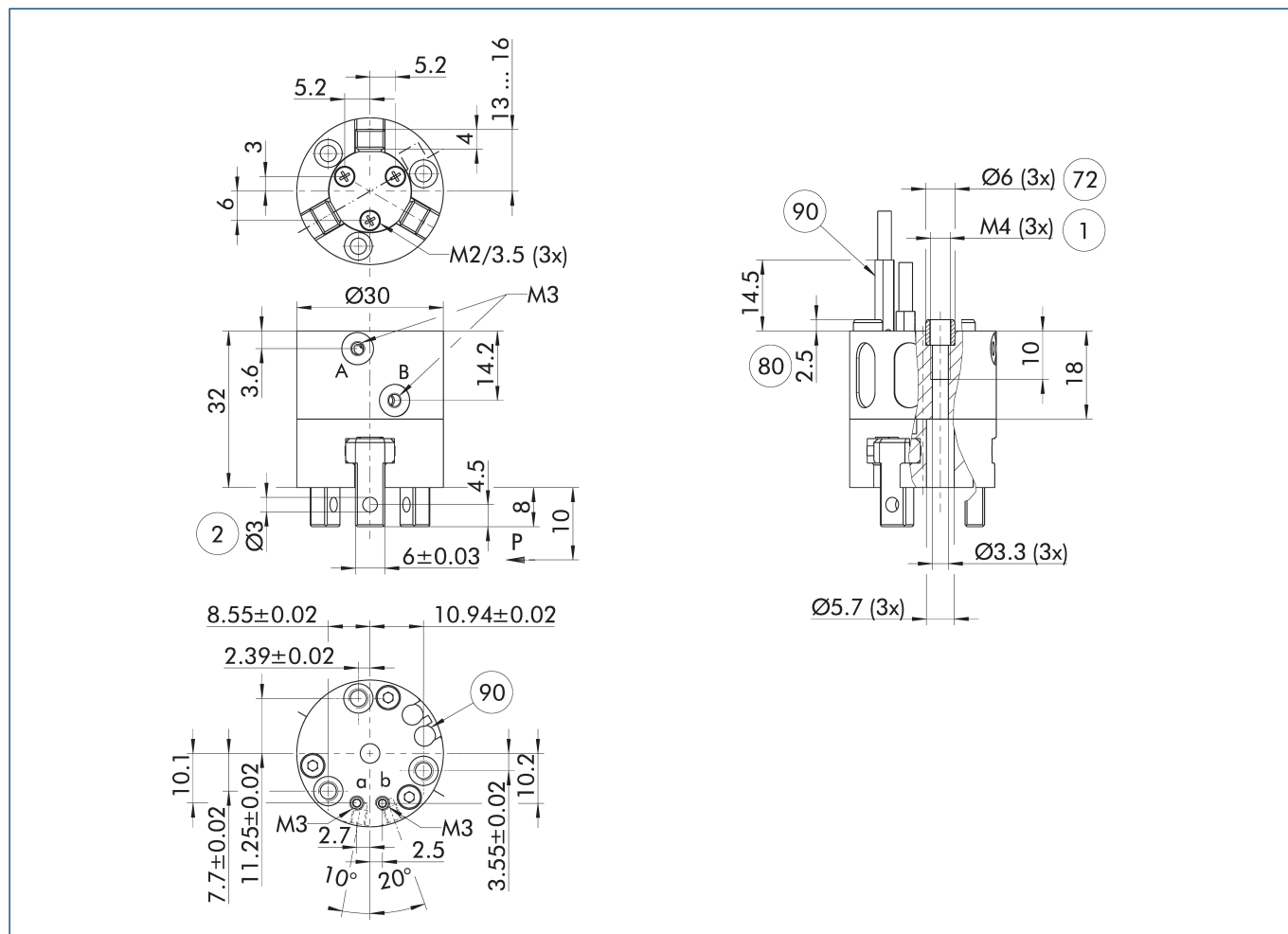
① The indicated moments and forces are static values, apply for each base jaw and may appear simultaneously. Loads may additionally occur to the moment produced by the gripping force itself.

Technical data

Description		MPZ 30	MPZ 30-FPS	MPZ 30-AS	MPZ 30-IS
ID		0340510	0340513	0340511	0340512
Stroke per jaw	[mm]	3	3	3	3
Closing/opening force	[N]	55/65	55/65	80/-	-/90
Min. spring force	[N]			25	25
Weight	[kg]	0.08	0.1	0.09	0.09
Recommended workpiece weight	[kg]	0.28	0.28	0.28	0.28
Cylinder volume per double stroke	[cm³]	1.8	1.8	4.2	3.2
Min./nom./max. operating pressure	[bar]	2/6/8	2/6/8	4/6/6.5	4/6/6.5
Closing/opening time	[s]	0.02/0.02	0.02/0.02	0.02/0.04	0.04/0.02
Closing/opening time with spring	[s]			0.30	0.30
Max. permissible finger length	[mm]	30	30	30	30
Max. permissible weight per finger	[kg]	0.03	0.03	0.03	0.03
IP protection class		40	40	40	40
Min./max. ambient temperature	[°C]	5/90	5/90	5/90	5/90
Repeat accuracy	[mm]	0.01	0.01	0.01	0.01
Cleanroom class ISO 14644-1		5	5	5	5
Dimensions Ø D x Z	[mm]	30 x 32	30 x 46	30 x 45	30 x 45

① It may take a few 100 gripping cycles until the full gripping force (as indicated in the data table) will be available.

Main view



The drawing shows the gripper in the basic version with closed jaws, without dimensional consideration of the options described below.

① As an alternative/in addition to spring-assisted mechanical gripping force maintenance, the SDV-P pressure maintenance valve can be used for I.D. and O.D. gripping (see "Accessories" section of catalog).

A, a Main / direct connection, gripper opening

B, b Main / direct connection, gripper closing

① Gripper connection

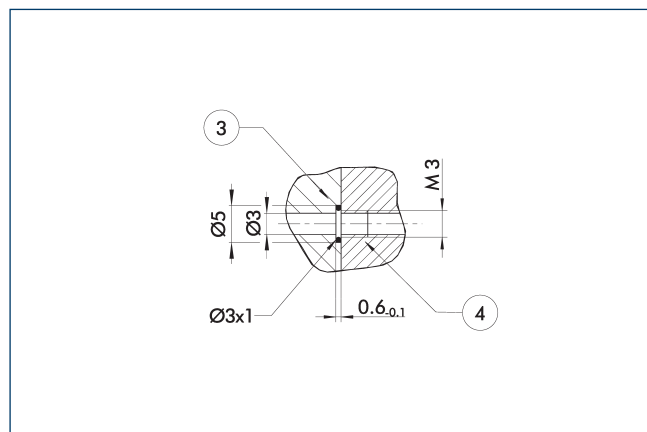
② Finger connection

72 Fit for centering sleeves

80 Depth of the centering sleeve hole in the counter part

90 Sensor MMS 22..

Hose-free direct connection M3

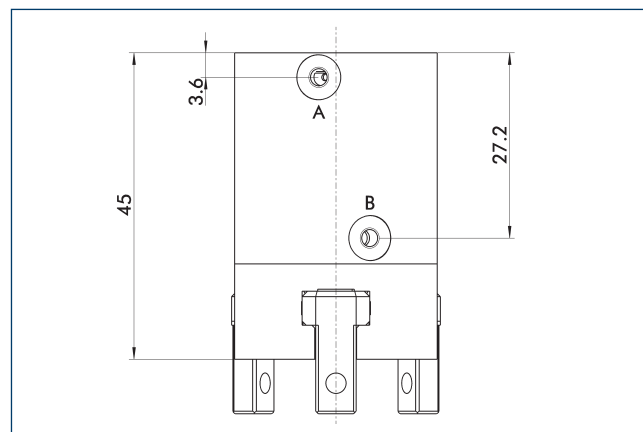


③ Adapter

④ Grippers

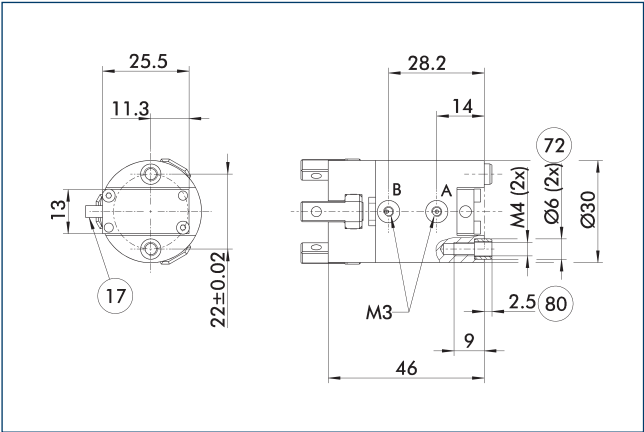
The direct connection is used for supplying compressed air without hoses. Instead, the pressure medium is fed through bore-holes in the mounting plate.

Gripping force maintenance version AS/IS



The mechanical gripping force maintenance device ensures that a minimum clamping force will be applied even if there is a drop in pressure. In the AS/S variant this acts as a closing force, in the IS variant as an opening force. Besides this, gripping force maintenance can be used to increase gripping force or for single actuated gripping.

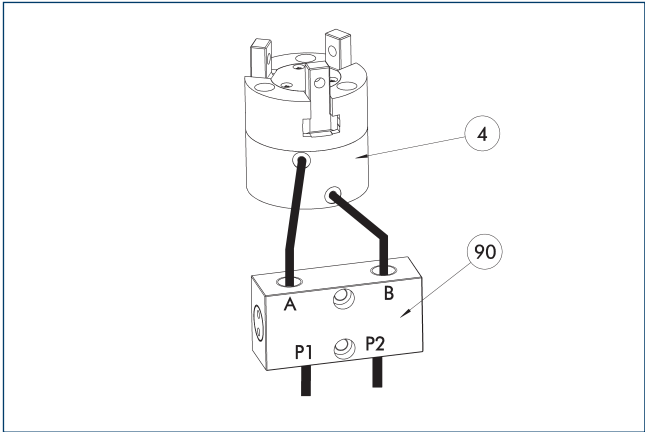
Flexible position sensor



- ①⑦ Cable outlet
⑦② Fit for centering sleeves
⑧⑦ Depth of the centering sleeve hole in the counter part

The following FPS position sensor can differentiate between five programmable areas or switching points for the stroke of a gripper, and can be used in connection with a PC as a measuring system.

SDV-P pressure maintenance valve



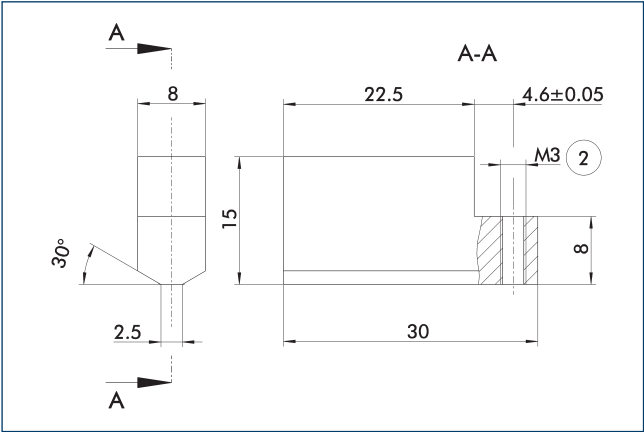
- ④ Grippers
⑨⑦ SDV-P pressure maintenance valve

The SDV-P pressure maintenance valves ensure in emergency stop situations that the pressure in the piston chamber of pneumatic gripper, swivel, and quick-change modules as well as in linear axes is temporarily maintained.

Description	ID	Recommended hose diameter
		[mm]
Pressure maintenance valve		
SDV-P 04	0403130	6
Pressure maintenance valve with air bleed screw		
SDV-P 04-E	0300120	6

- ⑩ In order to achieve the specified closing and opening time for each gripper variant, the recommended hose diameter must be used. The direct allocation of the respective variant of the gripper for the respective SDV-P can be found at schunk.com.

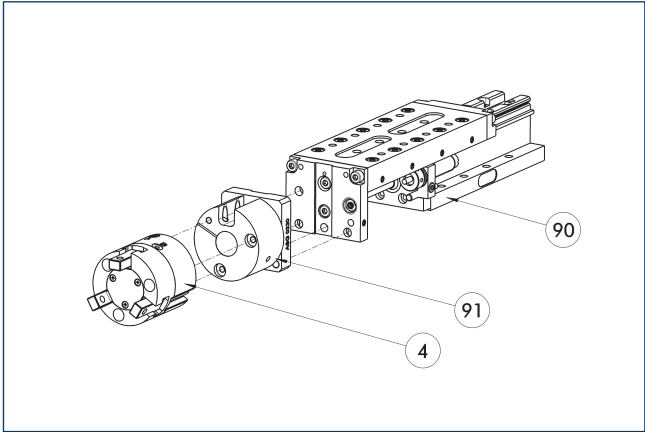
Finger blanks ABR-MPZ 30



- ② Finger connection
- The drawing shows the finger blank which can be reworked by the customer.

Description	ID	Material	Scope of delivery
Finger blank			
ABR-MPZ 30	0340519	Aluminum (3.4365)	3

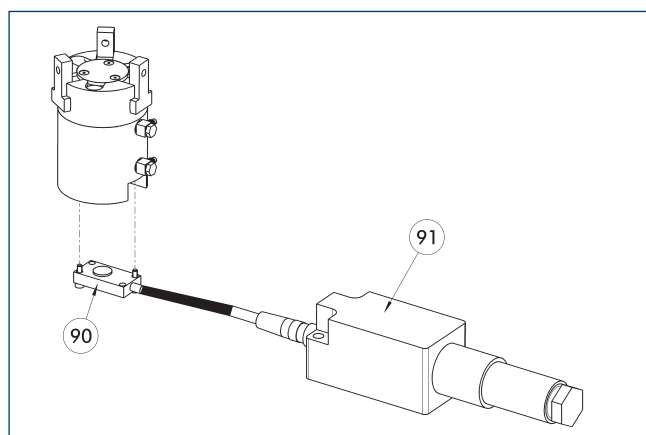
Modular Assembly Automation



- ④ Grippers
⑨⑦ Linear axis CLM/KLM/LM/ELP/ELM/ELS/HLM
⑨① ASG adapter plate

Grippers and linear axes can be combined as standard from the modular system of modular assembly automation. For more information see our main catalog "Modular Assembly Automation".

Flexible position sensor



90 FPS-S sensor

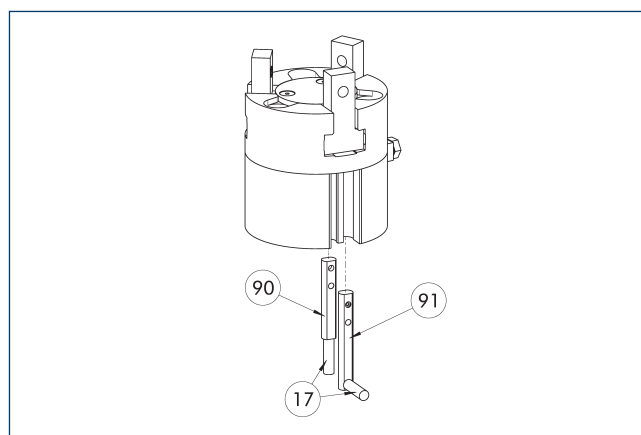
91 FPS-F5 evaluation electronic

Flexible position monitoring of up to five positions.

Description	ID	Often combined
Sensor		
FPS-S 13	0301705	
Evaluation electronics		
FPS-F5	0301805	●
Cable extension		
KV BG08-SG08 3P-0050	0301598	
KV BG08-SG08 3P-0100	0301599	
Connection cables		
KA BG16-L 12P-1000	0301801	
Clip for connector/socket		
CLI-M8	0301463	

- ① When using an FPS system, an FPS sensor (FPS-S) as well as an electronic processor (FPS-F5 / F5 T) are required for each gripper as well as a mounting kit (AS), if listed. Cable extensions (KV) are optionally available – see catalog chapter "Accessories."

Electronic magnetic switch MMS



17 Cable outlet

91 Sensor MMS 22...-SA

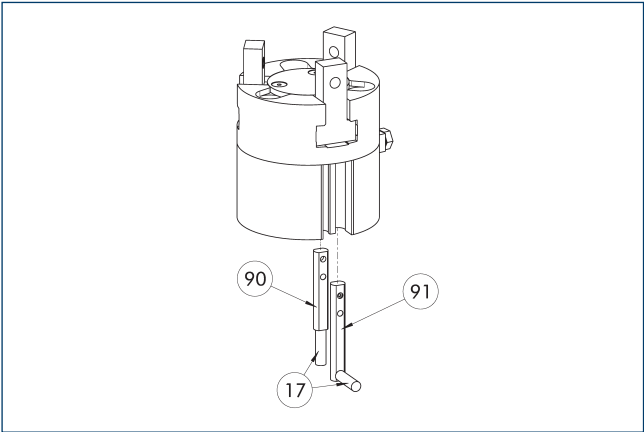
90 Sensor MMS 22..

End position monitoring for mounting in the C-slot.

Description	ID	Often combined
Electronic magnetic switch		
MMS 22-S-M8-PNP	0301032	●
MMSK 22-S-PNP	0301034	
Electronic magnetic switches with lateral cable outlet		
MMS 22-S-M8-PNP-SA	0301042	●
MMSK 22-S-PNP-SA	0301044	
Reed Switches		
RMS 22-S-M8	0377720	●
Connection cables		
KA BG08-L 3P-0300-PNP	0301622	●
KA BG08-L 3P-0500-PNP	0301623	
KA BW08-L 3P-0300-PNP	0301594	
KA BW08-L 3P-0500-PNP	0301502	
Clip for connector/socket		
CLI-M8	0301463	
Cable extension		
KV BW08-SG08 3P-0030-PNP	0301495	
KV BW08-SG08 3P-0100-PNP	0301496	
KV BW08-SG08 3P-0200-PNP	0301497	●
Sensor distributor		
V2-M8	0301775	●
V4-M8	0301746	
V8-M8	0301751	

- ① Two sensors are required per unit for monitoring two positions. On option, extension cables and sensor distributors are available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor system.

Programmable magnetic switch MMS 22-PI1



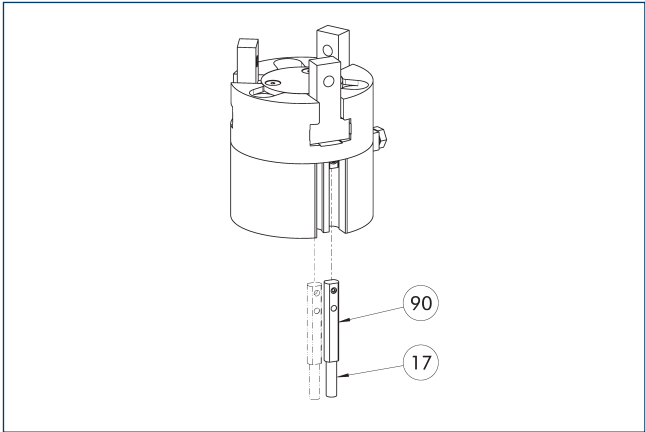
- 17 Cable outlet
- 91 Sensor MMS 22 ..-PI1-...-SA
- 90 Sensor MMS 22 PI1-...

Position monitoring with one programmable position per sensor and integrated electronic system in the sensor. Can be programmed using MT magnetic teaching tool (included in the scope of delivery, ID 0301030) or ST plug teaching tool (optional). End position monitoring for mounting in the C-slot. If the ST plug teaching tools are listed in the table provided, teaching is only possible with the ST teaching tools.

Description	ID	Often combined
Programmable magnetic switch		
MMS 22-PI1-S-M8-PNP	0301160	●
MMSK 22-PI1-S-PNP	0301162	
Programmable magnetic switch with lateral cable outlet		
MMS 22-PI1-S-M8-PNP-SA	0301166	●
MMSK 22-PI1-S-PNP-SA	0301168	
Programmable magnetic switch with stainless steel housing		
MMS 22-PI1-S-M8-PNP-HD	0301110	●
MMSK 22-PI1-S-PNP-HD	0301112	

- ① Two sensors are required per unit for monitoring two positions. On option, extension cables and sensor distributors are available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor system.

Programmable magnetic switch MMS 22-PI2



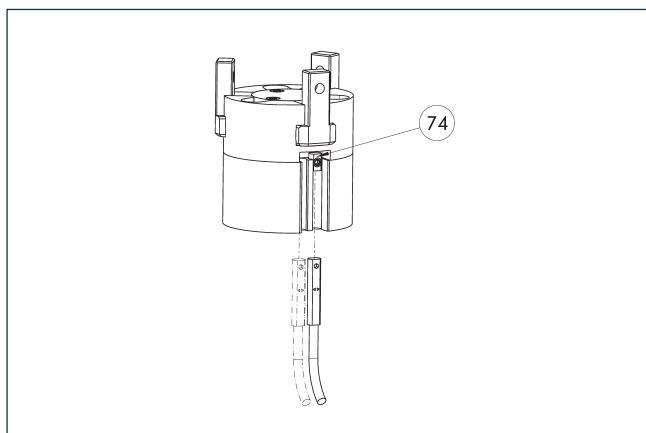
- 17 Cable outlet
- 90 MMS 22...-PI2-... sensor

Position monitoring with two programmable positions per sensor and electronics integrated in the sensor. Can be programmed using MT magnetic teaching tool (included in the scope of delivery, ID 0301030) or ST plug teaching tool (optional). End position monitoring for mounting in the C-slot. If the ST plug teaching tools are listed in the table provided, teaching is only possible with the ST teaching tools.

Description	ID	Often combined
Programmable magnetic switch		
MMS 22-PI2-S-M8-PNP	0301180	●
MMSK 22-PI2-S-PNP	0301182	
Programmable magnetic switch with lateral cable outlet		
MMS 22-PI2-S-M8-PNP-SA	0301186	●
MMSK 22-PI2-S-PNP-SA	0301188	
Programmable magnetic switch with stainless steel housing		
MMS 22-PI2-S-M8-PNP-HD	0301130	●
MMSK 22-PI2-S-PNP-HD	0301132	

- ① One sensor is required per unit for monitoring two positions. Extension cables and sensor distributors are optionally available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor systems.

MMS-P programmable magnetic switch



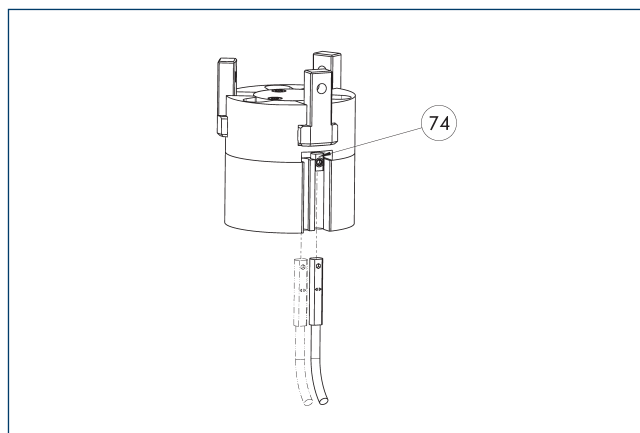
74 Limit stop for sensor

Position monitoring with two programmable positions per sensor. End position monitoring for mounting in the C-slot.

Description	ID	Often combined
Programmable magnetic switch		
MMSK-P 22-S-PNP	0301371	
MMS-P 22-S-M8-PNP	0301370	●
Connection cables		
KA GLN0804-LK-00500-A	0307767	●
KA GLN0804-LK-01000-A	0307768	
KA WLN0804-LK-00500-A	0307765	
KA WLN0804-LK-01000-A	0307766	
Clip for connector/socket		
CLI-M8	0301463	
Sensor distributor		
V2-M8-4P-2XM8-3P	0301380	

- ① One sensor is required per unit for monitoring two positions. Extension cables and sensor distributors are optionally available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor systems.

Programmable magnetic switch MMS-IO-Link



74 Limit stop for sensor

Sensor for multi-position monitoring through detection of the complete gripper stroke. The sensor is mounted directly in the C-slot of the gripper. The sensor is programmed for the gripper via the IO-Link interface, Magnet teaching tool MT (included in scope of delivery; ID 0301030) or the ST plug teaching tool (not included in scope of delivery; ID 0301026). An IO-Link master is required for operation.

Description	ID	
Programmable magnetic switch		
MMS 22-IO-L-M08	0315830	
MMS 22-IO-L-M12	0315835	

- ① One sensor is required for each gripper. No additional mounting kit is required – the gripper is equipped for use of the sensor by default. Further information and technical data can be found in the catalog chapter sensor systems.



SCHUNK SE & Co. KG

Spanntechnik

Greiftechnik

Automatisierungstechnik

Bahnhofstr. 106 - 134

D-74348 Lauffen/Neckar

Tel. +49-7133-103-0

Fax +49-7133-103-2399

info@de.schunk.com

schunk.com

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