



Superior Clamping and Gripping



## Product Information

Universal gripper JGP 50

## Loadable. Reliable. Compact.

### Universal gripper JGP

Universal 2-finger parallel gripper of the compact class with T-slot guidance and best cost-performance ratio

#### Field of application

Optimum standard solution for many fields of application. Universal application in clean and slightly dirty surroundings in machine building and plant building industry, assembly and handling as well as automotive industry.

#### Advantages – Your benefits

**A firm focus on the essentials** for maximum profitability

**Sturdy T-slot guidance** for the precise handling of different workpieces

**Compact dimensions and low weight** for minimal interfering contours in handling

**High maximum moments possible** suitable for using long gripper fingers

**Wedge-hook design** for high power transmission and synchronized gripping

**Comprehensive sensor accessories** for monitoring and control of the stroke position

**Mounting from two gripper sides** for universal and flexible gripper assembly

**Air supply via hose-free direct connection or screw connections** for flexible pressure supply in all automated systems



Sizes  
Quantity: 10



Weight  
0.08 .. 17.5 kg



Gripping force  
123 .. 7400 N



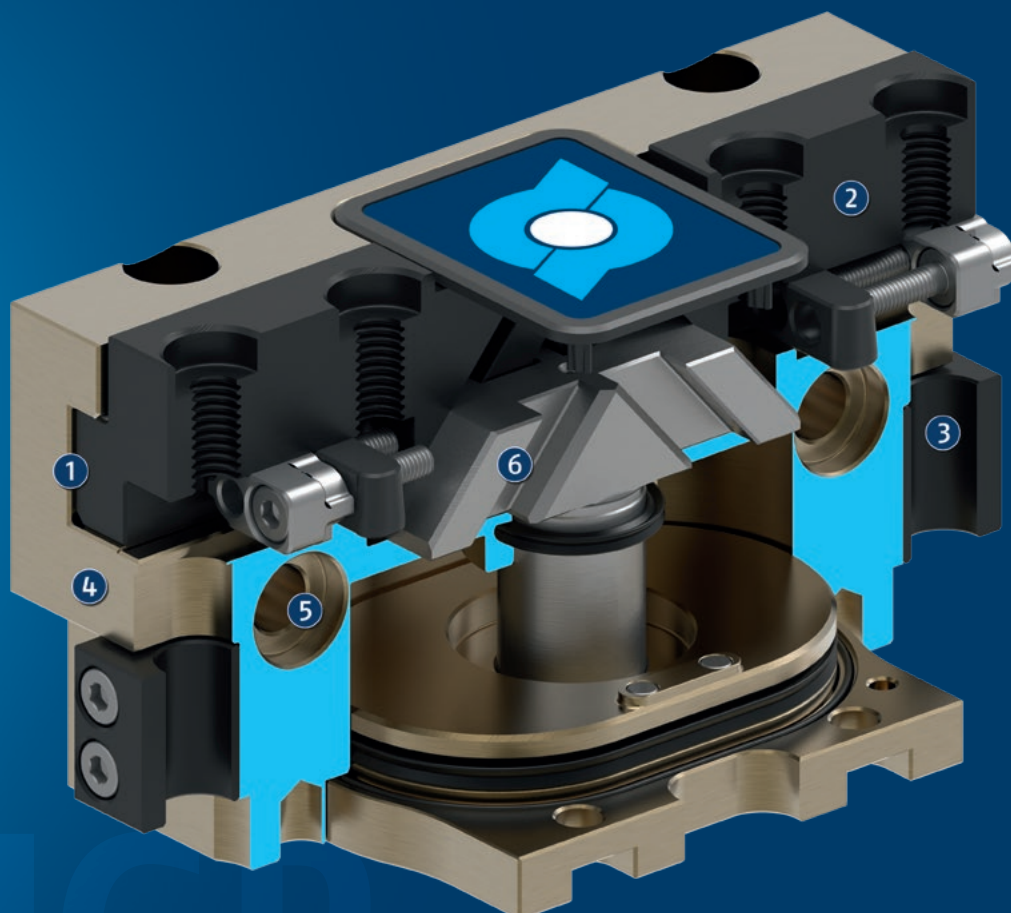
Stroke per jaw  
2 .. 35 mm



Workpiece weight  
0.62 .. 30 kg

## Functional description

The oval piston is moved up or down by compressed air. The angled active surfaces of the wedge-hook produce a synchronized, parallel jaw motion.



- ① **T-slot guidance**  
loadable, robust base jaw guidance for extremely long gripper fingers
- ② **Base jaw**  
for the connection of workpiece-specific gripper fingers
- ③ **Sensor system**  
Proximity switch can be assembled without mounting kit

- ④ **Housing**  
is weight-optimized due to the use of high-strength aluminum alloy
- ⑤ **Centering and mounting possibilities**  
for universal assembly of the gripper
- ⑥ **Wedge-hook design**  
for high force transmission and centric gripping

## General notes about the series

**Operating principle:** Wedge-hook kinematics

**Housing material:** Aluminum alloy, anodized

**Base jaw material:** Steel

**Actuation:** pneumatic, with filtered compressed air as per ISO 8573-1:2010 [7:4:4].

**Warranty:** 24 months

**Service life characteristics:** on request

**Scope of delivery:** Brackets for proximity switches, centering sleeves, O-rings for direct connection, assembly instructions (operating manual with declaration of incorporation is available online)

**Gripping force maintenance device:** possible by using the version with mechanical gripping force maintenance or pressure maintenance valve SDV-P

**Gripping force:** is the arithmetic sum of the individual force applied to each jaw at distance P (see illustration).

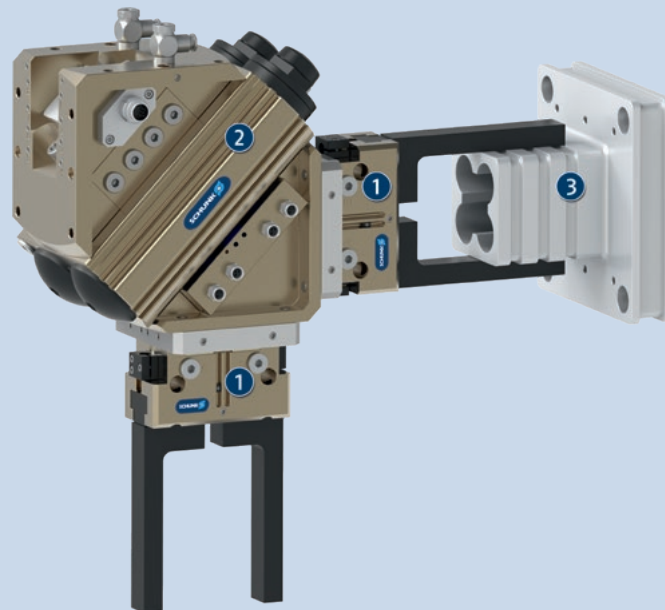
**Finger length:** is measured from the reference surface as the distance P in direction to the main axis.

The maximum permissible finger length applies until the nominal operating pressure is achieved. With higher pressures, the finger length must be reduced proportionally to the nominal operating pressure.

**Repeat accuracy:** is defined as a distribution of the end Position for 100 consecutive strokes.

**Workpiece weight:** is calculated for force-fit gripping with a coefficient of static friction of 0.1 and a safety factor of 2 against workpiece slippage at acceleration due to gravity g. For form-fit or capture gripping, there are significantly higher permissible workpiece weights.

**Closing and opening times:** are purely the times that the base jaws or fingers are in motion. Valve switching times, hose fill times, or PLC reaction times are not included, and are to be considered when cycle times are calculated.



## Application example

Swivel head with double parallel gripper for simultaneous loading and unloading of workpieces in a machine.

① 2-finger parallel gripper JGP with workpiece-specific gripper fingers

② Swivel head SRH-plus

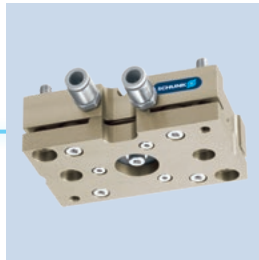
③ Workpiece

## SCHUNK offers more ...

The following components make the product even more productive – the suitable addition for the highest functionality, flexibility, reliability, and controlled production.



Compensation unit



Tolerance compensation unit



Manual change system



Pressure maintenance valve



Analog position sensor



Finger blank



Jaw quick-change system



Universal intermediate jaw



Flexible position sensor



Magnetic switches



Inductive proximity switches

① For more information on these products can be found on the following product pages or at [schunk.com](https://www.schunk.com).

## Options and special information

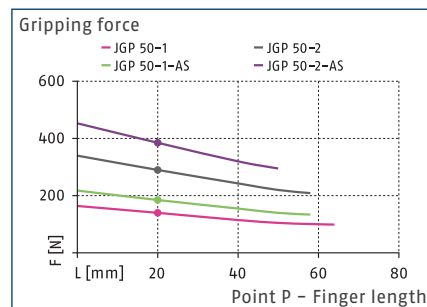
**Gripping force maintenance version AS/IS:** The mechanical gripping force maintenance version ensures minimum gripping force even in the event of a pressure drop. In the AS/S version this acts as a closing force, in the IS version as an opening force.

The JGP series is especially suitable for economic handling solutions and distinguishes by its high cost-benefit ratio.

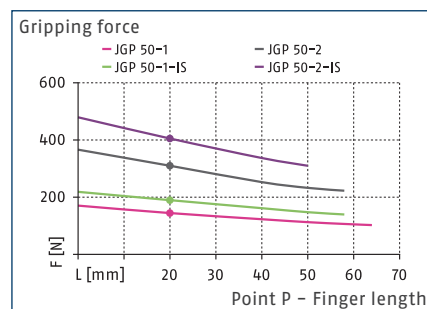
**Integrated air purge connection:** impedes the ingress of dirt into the inside of the gripper



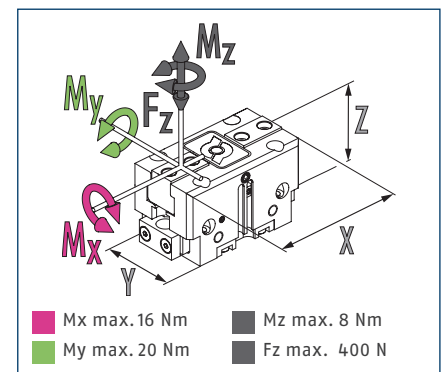
### Gripping force O.D. gripping



### Gripping force I.D. gripping



### Dimensions and maximum loads



① The indicated moments and forces are static values, apply for each base jaw and may appear simultaneously. Loads may additionally occur to the moment produced by the gripping force itself.

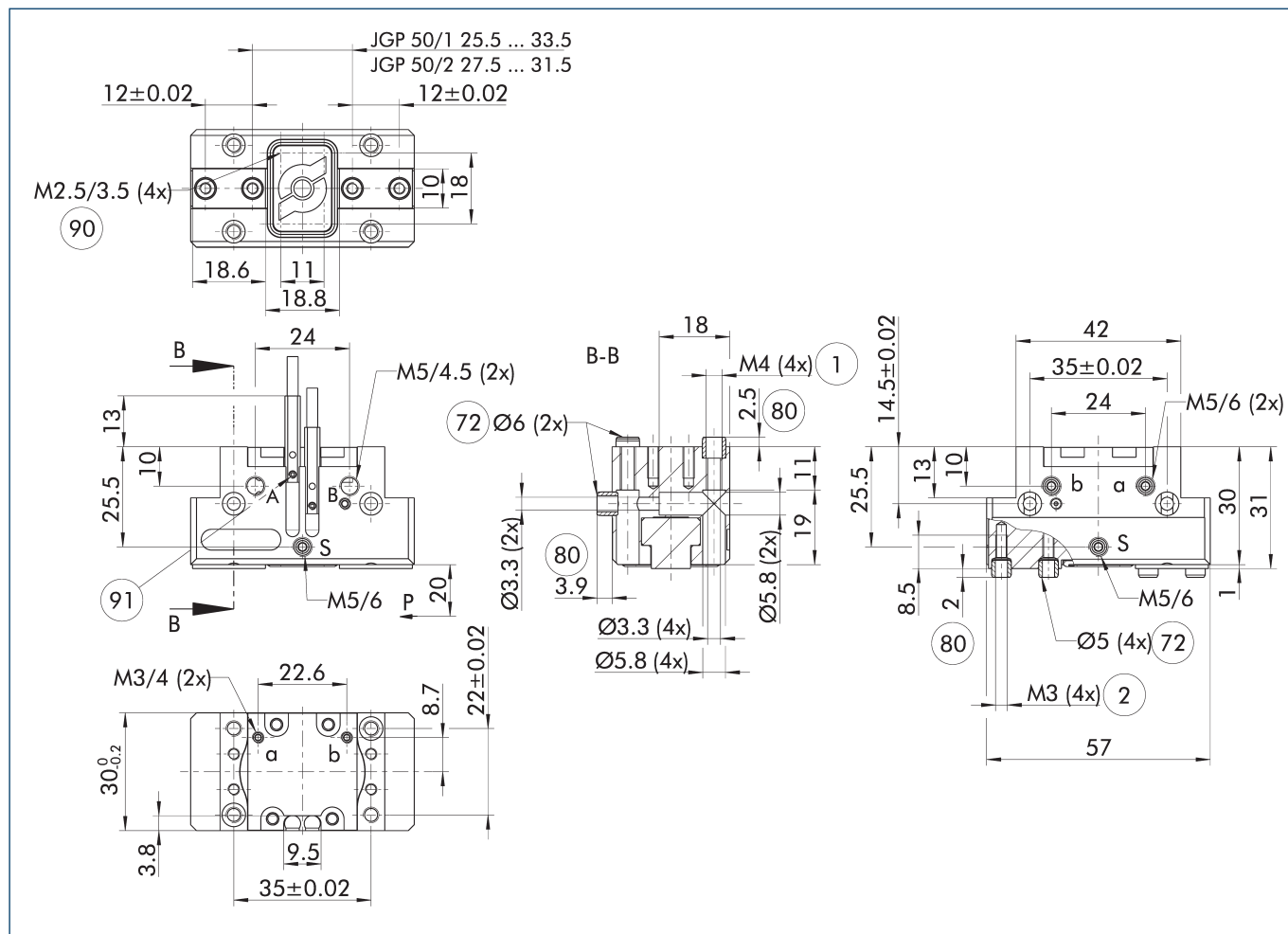
### Technical data

| Description                        |       | JGP 50-1     | JGP 50-2     | JGP 50-1-AS  | JGP 50-2-AS  | JGP 50-1-IS  | JGP 50-2-IS  |
|------------------------------------|-------|--------------|--------------|--------------|--------------|--------------|--------------|
| ID                                 |       | 0308610      | 0308615      | 0308611      | 0308616      | 0308612      | 0308617      |
| Stroke per jaw                     | [mm]  | 4            | 2            | 4            | 2            | 4            | 2            |
| Closing/opening force              | [N]   | 140/145      | 290/310      | 185/-        | 385/-        | -/190        | -/405        |
| Min. spring force                  | [N]   |              |              | 45           | 95           | 45           | 95           |
| Weight                             | [kg]  | 0.15         | 0.15         | 0.2          | 0.2          | 0.2          | 0.21         |
| Recommended workpiece weight       | [kg]  | 0.7          | 1.45         | 0.7          | 1.45         | 0.7          | 1.45         |
| Fluid consumption double stroke    | [cm³] | 5            | 5            | 8.5          | 8.5          | 11           | 11           |
| Min./nom./max. operating pressure  | [bar] | 2.5/6/8      | 2.5/6/8      | 4/6/6.5      | 4/6/6.5      | 4/6/6.5      | 4/6/6.5      |
| Min./max. air purge pressure       | [bar] | 0.5/1        | 0.5/1        | 0.5/1        | 0.5/1        | 0.5/1        | 0.5/1        |
| Closing/opening time               | [s]   | 0.02/0.02    | 0.02/0.02    | 0.02/0.03    | 0.02/0.03    | 0.03/0.02    | 0.03/0.02    |
| Closing/opening time with spring   | [s]   |              |              | 0.05         | 0.05         | 0.05         | 0.05         |
| Max. permissible finger length     | [mm]  | 64           | 58           | 58           | 50           | 58           | 50           |
| Max. permissible weight per finger | [kg]  | 0.18         | 0.18         | 0.18         | 0.18         | 0.18         | 0.18         |
| IP protection class                |       | 40           | 40           | 40           | 40           | 40           | 40           |
| Min./max. ambient temperature      | [°C]  | 5/90         | 5/90         | 5/90         | 5/90         | 5/90         | 5/90         |
| Repeat accuracy                    | [mm]  | 0.01         | 0.01         | 0.01         | 0.01         | 0.01         | 0.01         |
| Dimensions X x Y x Z               | [mm]  | 57 x 30 x 32 | 57 x 30 x 32 | 57 x 30 x 47 | 57 x 30 x 47 | 57 x 30 x 47 | 57 x 30 x 47 |

① It may take a few 100 gripping cycles until the full gripping force (as indicated in the data table) will be available.



## Main view



The drawing shows the gripper in the basic version with closed jaws, without dimensional consideration of the options described below.

① As an alternative/in addition to spring-assisted mechanical gripping force maintenance, the SDV-P pressure maintenance valve can be used for I.D. and O.D. gripping (see "Accessories" section of catalog).

A, a Main / direct connection, gripper opening

B, b Main / direct connection, gripper closing

S Air purge connection

① Gripper connection

② Finger connection

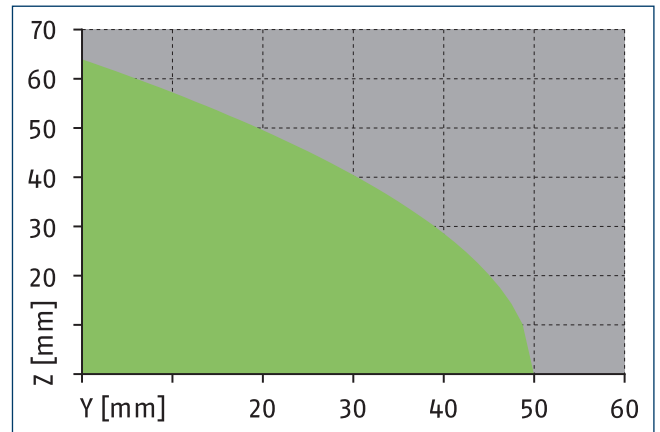
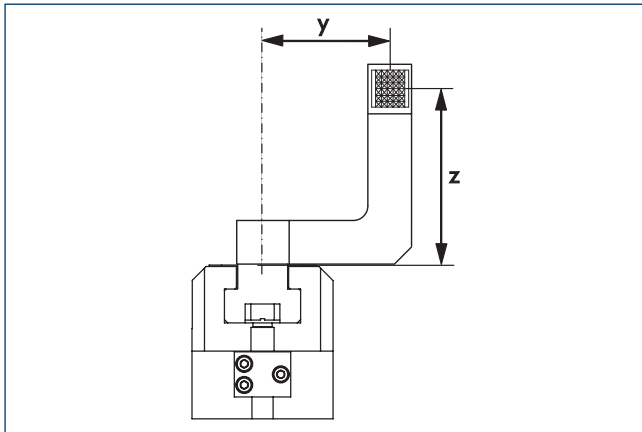
⑦② Fit for centering sleeves

⑧② Depth of the centering sleeve hole in the counter part

⑨② Thread below the cover for fastening external attachments

⑩② Sensor MMS 22..

### Maximum permitted finger projection

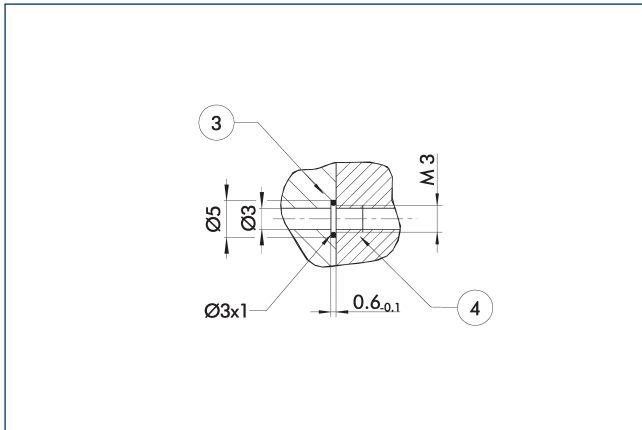


■ Permitted range

■ Inadmissible range

The curve applies for stroke version 1. For other versions, the curve must be parallelly off-set to the max. permissible finger length.

### Hose-free direct connection M3

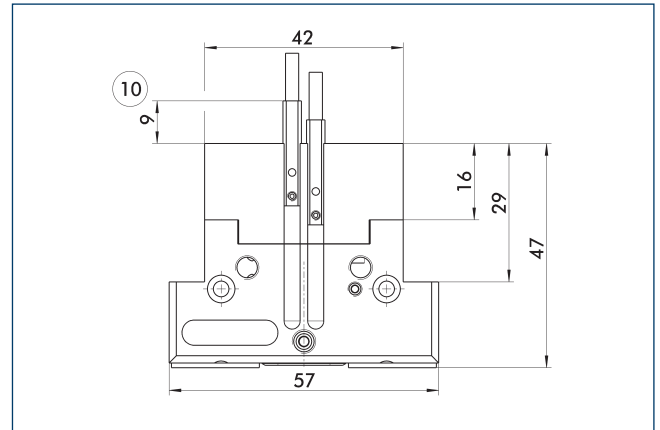


③ Adapter

④ Grippers

The direct connection is used for supplying compressed air without hoses. Instead, the pressure medium is fed through bore-holes in the mounting plate.

### Gripping force maintenance version AS/IS

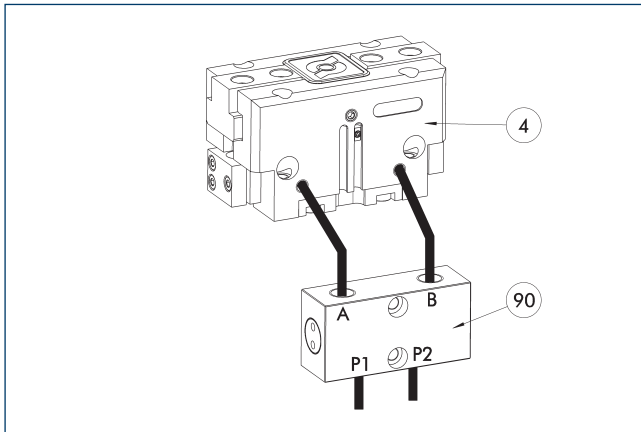


⑩ Projection applies only for AS version

The mechanical gripping force maintenance device ensures that a minimum clamping force will be applied even if there is a drop in pressure. In the AS/S variant this acts as a closing force, in the IS variant as an opening force. Besides this, gripping force maintenance can be used to increase gripping force or for single actuated gripping.



## SDV-P pressure maintenance valve



④ Grippers

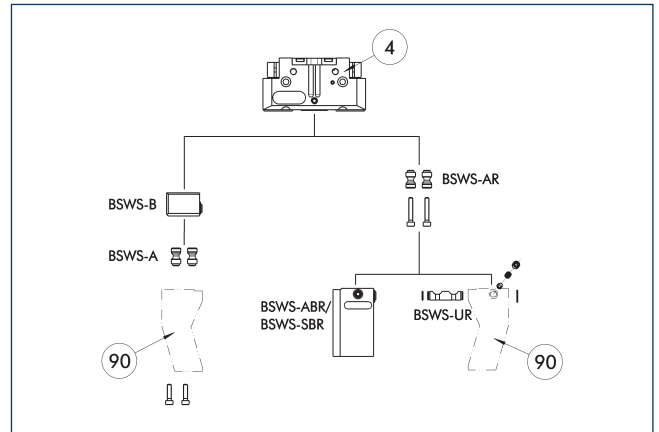
⑨⑩ SDV-P pressure maintenance valve

The SDV-P pressure maintenance valve ensures in emergency STOP situations that the pressure in the piston chamber of pneumatic gripper, swivel, linear, and quick-change modules is temporarily maintained.

| Description                                     | ID      | Recommended hose diameter<br>[mm] |
|-------------------------------------------------|---------|-----------------------------------|
| Pressure maintenance valve                      |         |                                   |
| SDV-P 04                                        | 0403130 | 6                                 |
| Pressure maintenance valve with air bleed screw |         |                                   |
| SDV-P 04-E                                      | 0300120 | 6                                 |

① In order to achieve the specified closing and opening time for each gripper variant, the recommended hose diameter must be used. The direct allocation of the respective variant of the gripper for the respective SDV-P can be found at [schunk.com](http://schunk.com).

## BSWS jaw quick-change jaw systems



④ Grippers

⑨⑩ Customized gripper fingers

There are various jaw quick-change systems available for the gripper. For detailed information, please refer to the corresponding product.

| Description                               | ID      | Scope of delivery |
|-------------------------------------------|---------|-------------------|
| Jaw quick-change system adapter pin       |         |                   |
| BSWS-A 50                                 | 0303020 | 2                 |
| BSWS-AR 50                                | 0300091 | 2                 |
| Quick-change jaw system base              |         |                   |
| BSWS-B 50                                 | 0303021 | 1                 |
| Jaw quick-change system finger blank      |         |                   |
| BSWS-ABR-PGZN-plus 50                     | 0300071 | 1                 |
| BSWS-SBR-PGZN-plus 50                     | 0300081 | 1                 |
| Jaw quick-change system locking mechanism |         |                   |
| BSWS-UR 50                                | 0302990 | 1                 |

① If the operating pressure is higher than 6 bar, suitability for use beyond the application limits must be checked. Only systems that are listed in the table, can be used.

The diagram illustrates the BSWS system architecture. A central unit (4) is connected to five other components: BSWS-BM, BSWS-A, BSWS-AR, BSWS-ABRM, and BSWS-URM. BSWS-A and BSWS-URM are connected to a component labeled 90.

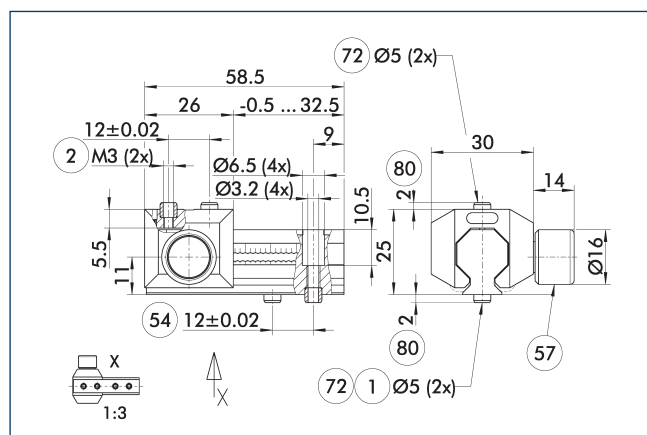
- ④** Grippers                      **90** Customized gripper fingers

| Description                               | ID      | Scope of delivery |
|-------------------------------------------|---------|-------------------|
| Jaw quick-change system adapter pin       |         |                   |
| BSWS-A 50                                 | 0303020 | 2                 |
| BSWS-AR 50                                | 0300091 | 2                 |
| Quick-change jaw system base              |         |                   |
| BSWS-BM 50                                | 1313899 | 1                 |
| Jaw quick-change system finger blank      |         |                   |
| BSWS-ABRM-PGZN-plus 50                    | 1420850 | 1                 |
| Jaw quick-change system locking mechanism |         |                   |
| BSWS-URM 50                               | 1380614 | 1                 |

- 

- | Description      | ID      | Material | Finger interface | Scope of delivery |
|------------------|---------|----------|------------------|-------------------|
| Intermediate jaw |         |          |                  |                   |
| ZBA-L-plus 50    | 0311712 | Aluminum | PGN-plus 50      | 1                 |

### Finger blanks ABR/SBR-PGZN-plus 50



- ① Gripper connection
- ② Finger connection
- ⑤④ Optional right or left connection
- ⑤⑦ Locking
- ⑦② Fit for centering sleeves
- ⑧① Depth of the centering sleeve hole in the counter part

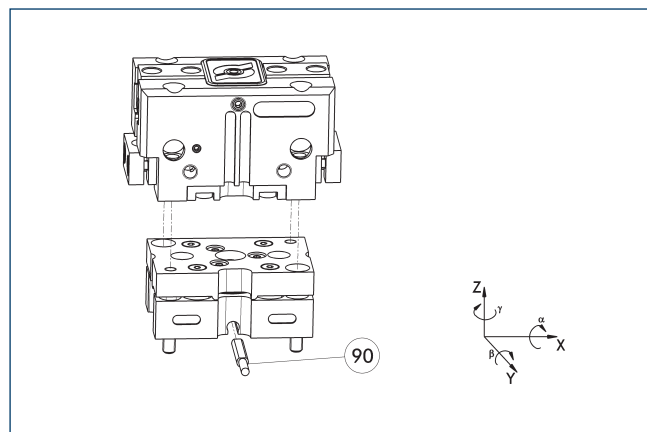
- (72) Fit for centering sleeves

The drawing shows the finger blank which can be reworked by the customer.

| Description      | ID      | Material          | Scope of delivery |
|------------------|---------|-------------------|-------------------|
| Finger blank     |         |                   |                   |
| ABR-PGZN-plus 50 | 0300009 | Aluminum (3.4365) | 1                 |
| SBR-PGZN-plus 50 | 0300019 | Steel (1.7131)    | 1                 |

❗ If the operating pressure is higher than 6 bar, suitability for use beyond the application limits must be checked.

### Tolerance compensation unit TCU

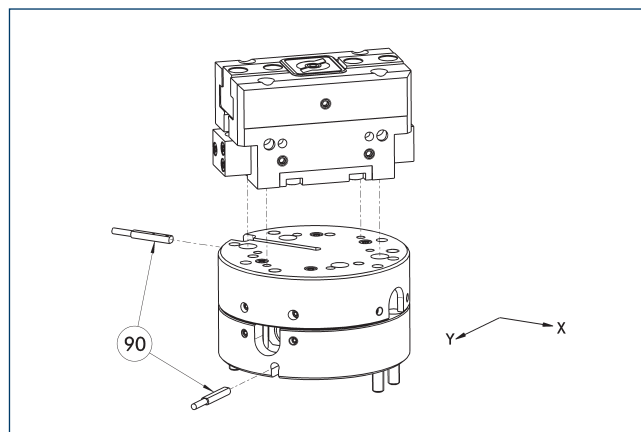


- ⑨⑩ Monitoring of locking

Grippers can be directly mounted without an adapter plate. Tolerance compensation unit and gripper have an identical screw connection diagram. Therefore the tolerance compensation units can be assembled later. Please consider the additional assembly height of the tolerance compensation unit. For details please refer to our catalog robot accessories.

| Description       | ID      | Locking | Deflection    |
|-------------------|---------|---------|---------------|
| Compensation unit |         |         |               |
| TCU-P-050-3-0V    | 0324757 | no      | ±1°/±1°/±1,5° |

### Compensation unit AGE-F

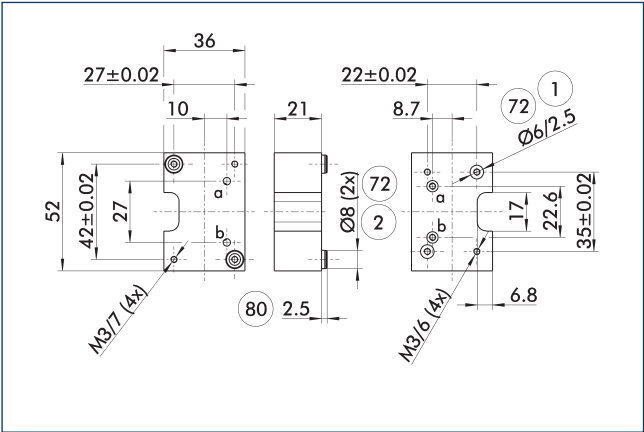


- ## 90 Monitoring

Grippers can be directly mounted without an adapter plate. For details see our catalog Gripping or Robot Accessories.

| Description       | ID      | Compensation<br>XY | Reset force | Often<br>combined |
|-------------------|---------|--------------------|-------------|-------------------|
|                   |         | [mm]               | [N]         |                   |
| Compensation unit |         |                    |             |                   |
| AGE-F-XY-040-1    | 0324920 | ± 2                | 3           |                   |
| AGE-F-XY-040-2    | 0324921 | ± 2                | 4           |                   |
| AGE-F-XY-040-3    | 0324922 | ± 2                | 4.5         | ●                 |

Adapter plate for PGN-plus 50

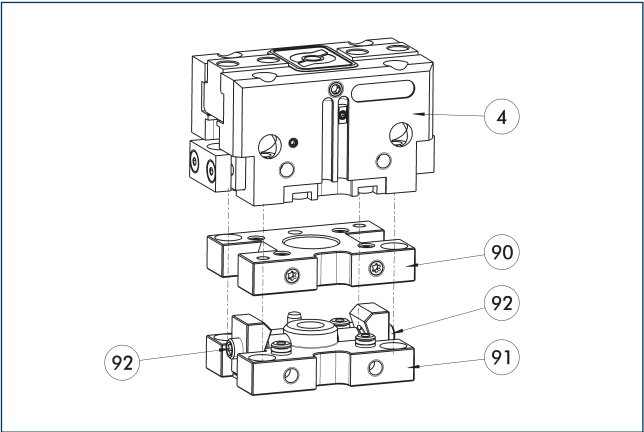


- ① Robot-side connection
- ② Tool-side connection
- ⑦ Fit for centering sleeves
- ⑧ Depth of the centering sleeve hole in the counter part

The adapter plate has integrated air feed-throughs in order to be able to use the hose-free direct connection of the appropriate gripper.

| Description     | ID      |  |
|-----------------|---------|--|
| Tool side       |         |  |
| A-CWA-064-050-P | 0305768 |  |

Compact change system for grippers

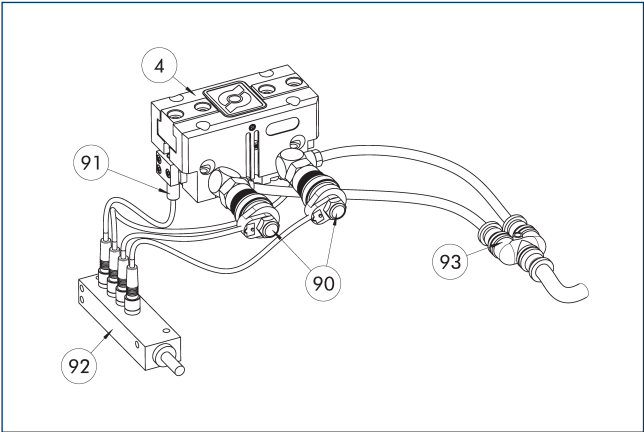


- ④ Grippers
- ⑨ CWA compact change adapter
- ⑨ CWK compact change master
- ⑨ Locking mechanism

Grippers can be directly mounted without an adapter plate. For details see our catalog Gripping or Robot Accessories.

| Description                | ID      |  |
|----------------------------|---------|--|
| Tool side                  |         |  |
| A-CWA-064-050-P            | 0305768 |  |
| CWA compact change adapter |         |  |
| CWA-050-P                  | 0305751 |  |
| CWK compact change master  |         |  |
| CWK-050-P                  | 0305750 |  |

Add-on valves for single grippers



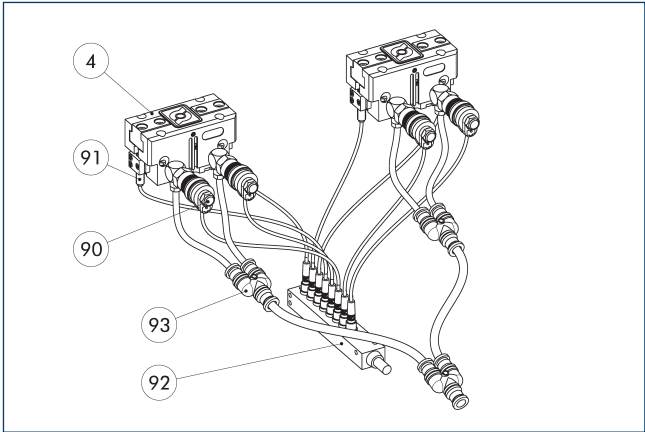
- ④ Grippers
- ⑨② Sensor distributor
- ⑨① Micro valves
- ⑨③ Y distributor
- ⑨① Sensor

The set of attachment valves reduces the compressed air consumption as there is no need to ventilate or bleed the supply lines. This can also reduce cycle time. The hose-free direct assembly of the micro valves reduces the hosing effort for the gripper. To further simplify electrical connection of the valves and sensors, their signals can be bundled via an optional distributor.

| Description       | ID      | Often combined |
|-------------------|---------|----------------|
| Add-on valve set  |         |                |
| ABV-MV15-M5       | 0303323 |                |
| ABV-MV15-M5-V2-M8 | 0303386 |                |
| ABV-MV15-M5-V4-M8 | 0303356 | ●              |

- ① A set of add-on valves ABV is required per actuator. The ABV set contains two 3/2 micro valves, an Y-distributor for compressed air supply and optionally a sensor distributor with two or four inputs or outputs. Sensors for monitoring the gripper need to be ordered separately. Pneumatic hoses are not included in the scope of delivery.

Add-on valves for double grippers



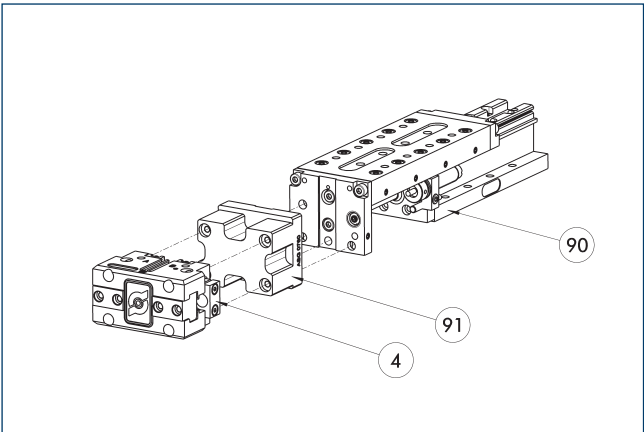
- ④ Grippers
- ⑨② Sensor distributor
- ⑨① Micro valves
- ⑨③ Y distributor
- ⑨① Sensor

The add-on valve set reduces compressed air consumption as there is no need to ventilate or bleed the supply lines. This can also reduce cycle time. The hose-free direct assembly of the micro valves reduces the hosing effort for the gripper. To further simplify electrical connection of the valves and sensors, their signals can be bundled via a distributor.

| Description       | ID      |  |
|-------------------|---------|--|
| Add-on valve set  |         |  |
| ABV-MV15-M5-V8-M8 | 0303357 |  |

- ① A set of add-on valves ABV is required per double gripping unit. The ABV set contains four 3/2 microvalves, three Y-distributors for compressed air supply and a sensor distributor with eight inputs or outputs. Sensors for monitoring the gripper need to be ordered separately. Pneumatic hoses are not included in the scope of delivery.

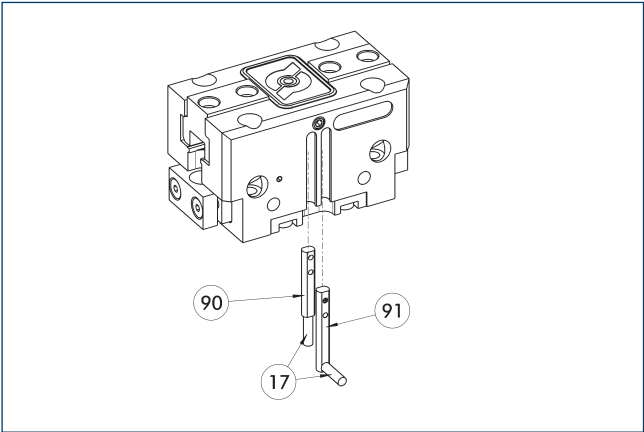
Modular Assembly Automation



- ④ Grippers
- ⑨① ASG adapter plate
- ⑨① Linear module CLM/KLM/LM/ELP/ELM/ELS/HLM

Grippers and linear modules can be combined with standard adapter plates from the modular assembly system. For more information see our main catalog "Modular Assembly Automation".

Electronic magnetic switch MMS



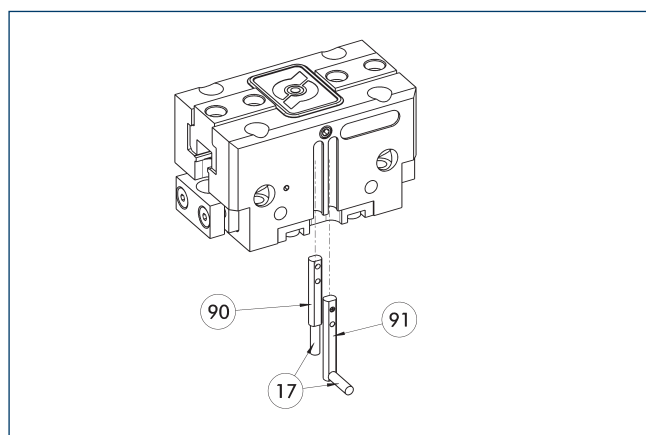
- 17 Cable outlet
- 91 Sensor MMS 22...-SA
- 90 Sensor MMS 22..

End position monitoring for mounting in the C-slot.

| Description                                            | ID      | Often combined |
|--------------------------------------------------------|---------|----------------|
| Electronic magnetic switch                             |         |                |
| MMS 22-S-M8-PNP                                        | 0301032 | ●              |
| MMSK 22-S-PNP                                          | 0301034 |                |
| Electronic magnetic switches with lateral cable outlet |         |                |
| MMS 22-S-M8-PNP-SA                                     | 0301042 | ●              |
| MMSK 22-S-PNP-SA                                       | 0301044 |                |
| Connection cables                                      |         |                |
| KA BG08-L 3P-0300-PNP                                  | 0301622 | ●              |
| KA BG08-L 3P-0500-PNP                                  | 0301623 |                |
| KA BW08-L 3P-0300-PNP                                  | 0301594 |                |
| KA BW08-L 3P-0500-PNP                                  | 0301502 |                |
| Clip for connector/socket                              |         |                |
| CLI-M8                                                 | 0301463 |                |
| Cable extension                                        |         |                |
| KV BW08-SG08 3P-0030-PNP                               | 0301495 |                |
| KV BW08-SG08 3P-0100-PNP                               | 0301496 |                |
| KV BW08-SG08 3P-0200-PNP                               | 0301497 | ●              |
| Sensor distributor                                     |         |                |
| V2-M8                                                  | 0301775 | ●              |
| V4-M8                                                  | 0301746 |                |
| V8-M8                                                  | 0301751 |                |

- ① Two sensors are required per unit for monitoring two positions. On option, extension cables and sensor distributors are available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor system.

### Programmable magnetic switch MMS 22-PI1



①⑦ Cable outlet

①⑨ Sensor MMS 22 ..-PI1-...-SA

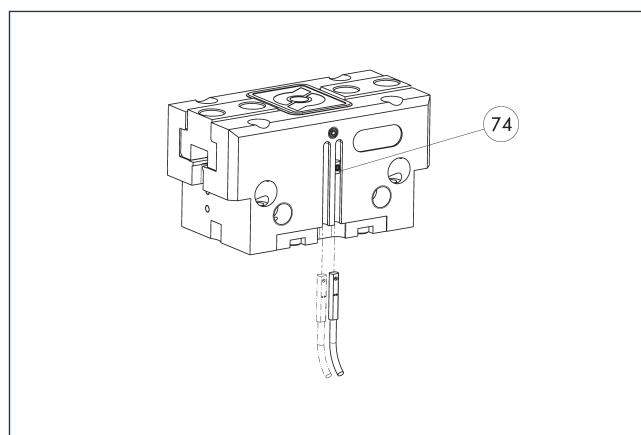
①⑩ Sensor MMS 22 PI1-...

Position monitoring with one programmable position per sensor and integrated electronic system in the sensor. Can be programmed using MT magnetic teaching tool (included in the scope of delivery, ID 0301030) or ST plug teaching tool (optional). End position monitoring for mounting in the C-slot. If the ST plug teaching tools are listed in the table provided, teaching is only possible with the ST teaching tools.

| Description                                               | ID      | Often combined |
|-----------------------------------------------------------|---------|----------------|
| Programmable magnetic switch                              |         |                |
| MMS 22-PI1-S-M8-PNP                                       | 0301160 | ●              |
| MMSK 22-PI1-S-PNP                                         | 0301162 |                |
| Programmable magnetic switch with lateral cable outlet    |         |                |
| MMS 22-PI1-S-M8-PNP-SA                                    | 0301166 | ●              |
| MMSK 22-PI1-S-PNP-SA                                      | 0301168 |                |
| Programmable magnetic switch with stainless steel housing |         |                |
| MMS 22-PI1-S-M8-PNP-HD                                    | 0301110 | ●              |
| MMSK 22-PI1-S-PNP-HD                                      | 0301112 |                |

- ① Two sensors are required per unit for monitoring two positions. On option, extension cables and sensor distributors are available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor system.

### MMS-P programmable magnetic switch



①④ Limit stop for sensor

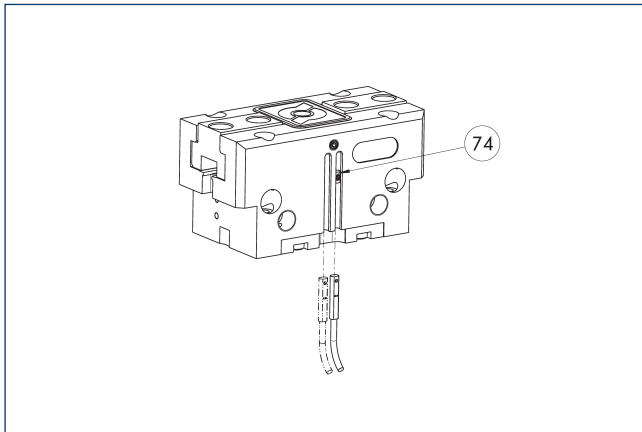
Position monitoring with two programmable positions per sensor. End position monitoring for mounting in the C-slot.

| Description                  | ID      | Often combined |
|------------------------------|---------|----------------|
| Programmable magnetic switch |         |                |
| MMSK-P 22-S-PNP              | 0301371 |                |
| MMS-P 22-S-M8-PNP            | 0301370 | ●              |
| Connection cables            |         |                |
| KA GLN0804-LK-00500-A        | 0307767 | ●              |
| KA GLN0804-LK-01000-A        | 0307768 |                |
| KA WLN0804-LK-00500-A        | 0307765 |                |
| KA WLN0804-LK-01000-A        | 0307766 |                |
| Clip for connector/socket    |         |                |
| CLI-M8                       | 0301463 |                |
| Sensor distributor           |         |                |
| V2-M8-4P-2XM8-3P             | 0301380 |                |

- ① One sensor is required per unit for monitoring two positions. Extension cables and sensor distributors are optionally available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor systems.



### Programmable magnetic switch MMS-I0-Link



#### 74 Limit stop for sensor

Sensor zur Multi-Positionsabfrage durch Erfassung des kompletten Greiferhubs. Der Sensor wird direkt in der C-Nut des Greifers montiert. Die Programmierung des Sensors auf den Greifer erfolgt via IO-Link-Schnittstelle, Magneteachtool MT (im Lieferumfang enthalten; Ident.-Nr.: 0301030) oder Steckerteachwerkzeug ST (optional). Sind die Steckerteachwerkzeuge ST in der aufgeführten Tabelle gelistet, kann nicht mit dem Magneteachtool MT geteacht werden. Zum Betrieb ist ein IO-Link-Master notwendig.

| Description                  | ID      |  |
|------------------------------|---------|--|
| Programmable magnetic switch |         |  |
| MMS 22-I0L-M08               | 0315830 |  |
| MMS 22-I0L-M12               | 0315835 |  |

- ① One sensor is required for each gripper. No additional mounting kit is required – the gripper is equipped for use of the sensor by default. Further information and technical data can be found in the catalog chapter sensor systems.





**SCHUNK GmbH & Co. KG**  
**Spann- und Greiftechnik**

Bahnhofstr. 106 - 134  
D-74348 Lauffen/Neckar  
Tel. +49-7133-103-0  
Fax +49-7133-103-2399  
[info@de.schunk.com](mailto:info@de.schunk.com)  
[schunk.com](http://schunk.com)

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