



Superior Clamping and Gripping



Product Information

Universal gripper JGP 200

Loadable. Reliable. Compact.

Universal gripper JGP

Universal 2-finger parallel gripper of the compact class with T-slot guidance and best cost-performance ratio

Field of application

Optimum standard solution for many fields of application. Universal application in clean and slightly dirty surroundings in machine building and plant building industry, assembly and handling as well as automotive industry.

Advantages – Your benefits

A firm focus on the essentials for maximum profitability

Sturdy T-slot guidance for the precise handling of different workpieces

Compact dimensions and low weight for minimal interfering contours in handling

High maximum moments possible suitable for using long gripper fingers

Wedge-hook design for high power transmission and synchronized gripping

Comprehensive sensor accessories for monitoring and control of the stroke position

Mounting from two gripper sides for universal and flexible gripper assembly

Air supply via hose-free direct connection or screw connections for flexible pressure supply in all automated systems



Sizes
Quantity: 10



Weight
0.08 .. 17.5 kg



Gripping force
123 .. 7400 N



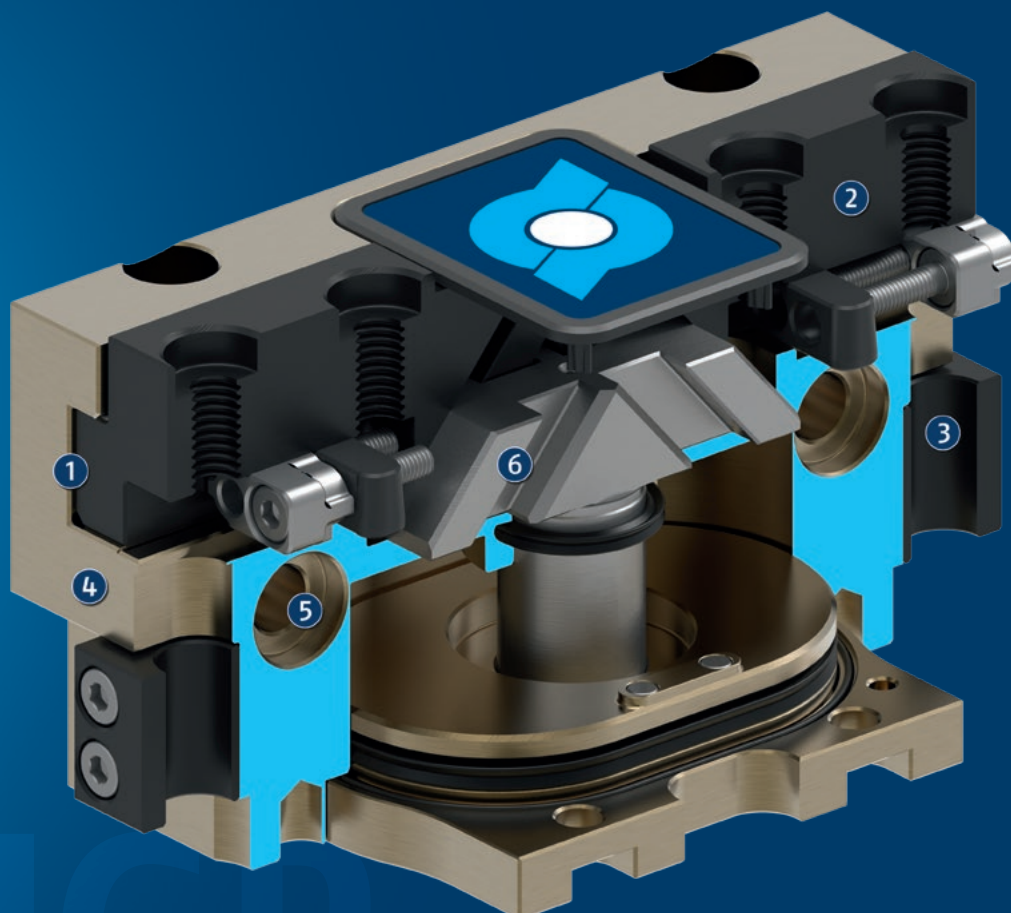
Stroke per jaw
2 .. 35 mm



Workpiece weight
0.62 .. 30 kg

Functional description

The oval piston is moved up or down by compressed air. The angled active surfaces of the wedge-hook produce a synchronized, parallel jaw motion.



- ① **T-slot guidance**
loadable, robust base jaw guidance for extremely long gripper fingers
- ② **Base jaw**
for the connection of workpiece-specific gripper fingers
- ③ **Sensor system**
Proximity switch can be assembled without mounting kit

- ④ **Housing**
is weight-optimized due to the use of high-strength aluminum alloy
- ⑤ **Centering and mounting possibilities**
for universal assembly of the gripper
- ⑥ **Wedge-hook design**
for high force transmission and centric gripping

General notes about the series

Operating principle: Wedge-hook kinematics

Housing material: Aluminum alloy, anodized

Base jaw material: Steel

Actuation: pneumatic, with filtered compressed air as per ISO 8573-1:2010 [7:4:4].

Warranty: 24 months

Service life characteristics: on request

Scope of delivery: Brackets for proximity switches, centering sleeves, O-rings for direct connection, assembly instructions (operating manual with declaration of incorporation is available online)

Gripping force maintenance device: possible by using the version with mechanical gripping force maintenance or pressure maintenance valve SDV-P

Gripping force: is the arithmetic sum of the individual force applied to each jaw at distance P (see illustration).

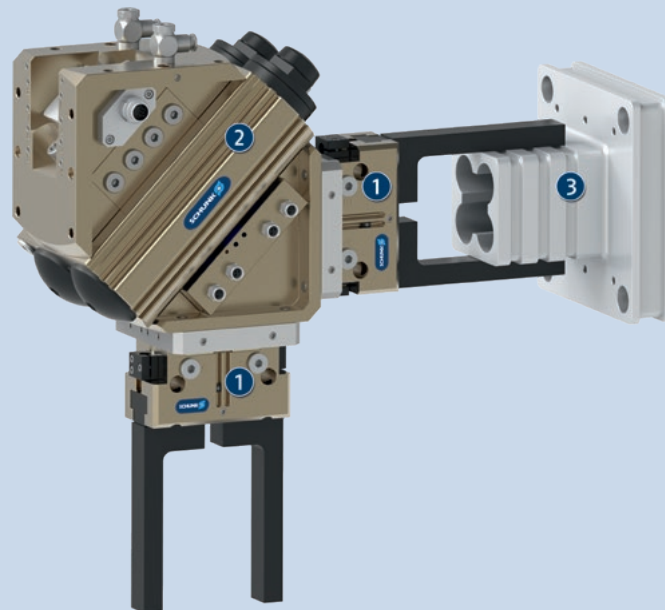
Finger length: is measured from the reference surface as the distance P in direction to the main axis.

The maximum permissible finger length applies until the nominal operating pressure is achieved. With higher pressures, the finger length must be reduced proportionally to the nominal operating pressure.

Repeat accuracy: is defined as a distribution of the end Position for 100 consecutive strokes.

Workpiece weight: is calculated for force-fit gripping with a coefficient of static friction of 0.1 and a safety factor of 2 against workpiece slippage at acceleration due to gravity g. For form-fit or capture gripping, there are significantly higher permissible workpiece weights.

Closing and opening times: are purely the times that the base jaws or fingers are in motion. Valve switching times, hose fill times, or PLC reaction times are not included, and are to be considered when cycle times are calculated.



Application example

Swivel head with double parallel gripper for simultaneous loading and unloading of workpieces in a machine.

① 2-finger parallel gripper JGP with workpiece-specific gripper fingers

② Swivel head SRH-plus

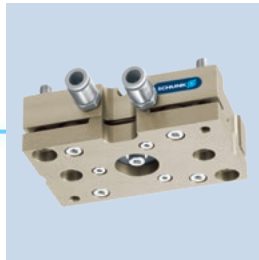
③ Workpiece

SCHUNK offers more ...

The following components make the product even more productive – the suitable addition for the highest functionality, flexibility, reliability, and controlled production.



Compensation unit



Tolerance compensation unit



Manual change system



Pressure maintenance valve



Analog position sensor



Finger blank



Jaw quick-change system



Universal intermediate jaw



Flexible position sensor



Magnetic switches



Inductive proximity switches

① For more information on these products can be found on the following product pages or at schunk.com.

Options and special information

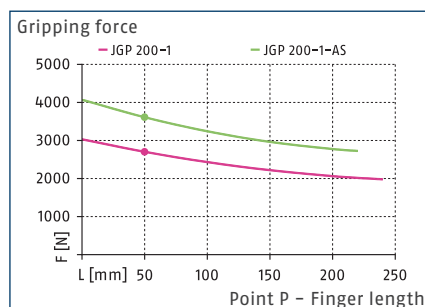
Gripping force maintenance version AS/IS: The mechanical gripping force maintenance version ensures minimum gripping force even in the event of a pressure drop. In the AS/S version this acts as a closing force, in the IS version as an opening force.

The JGP series is especially suitable for economic handling solutions and distinguishes by its high cost-benefit ratio.

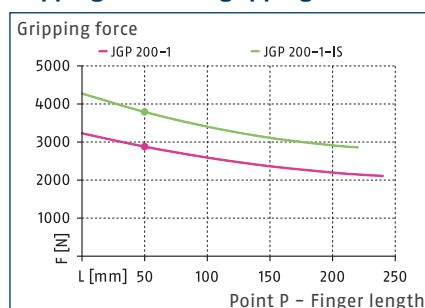
Integrated air purge connection: impedes the ingress of dirt into the inside of the gripper



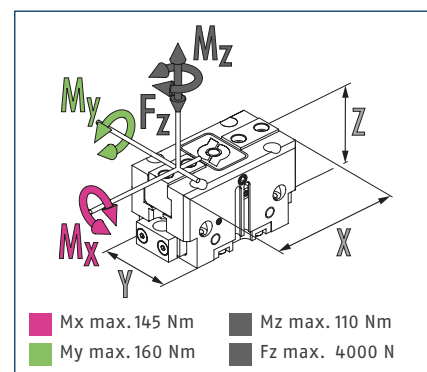
Gripping force O.D. gripping



Gripping force I.D. gripping



Dimensions and maximum loads



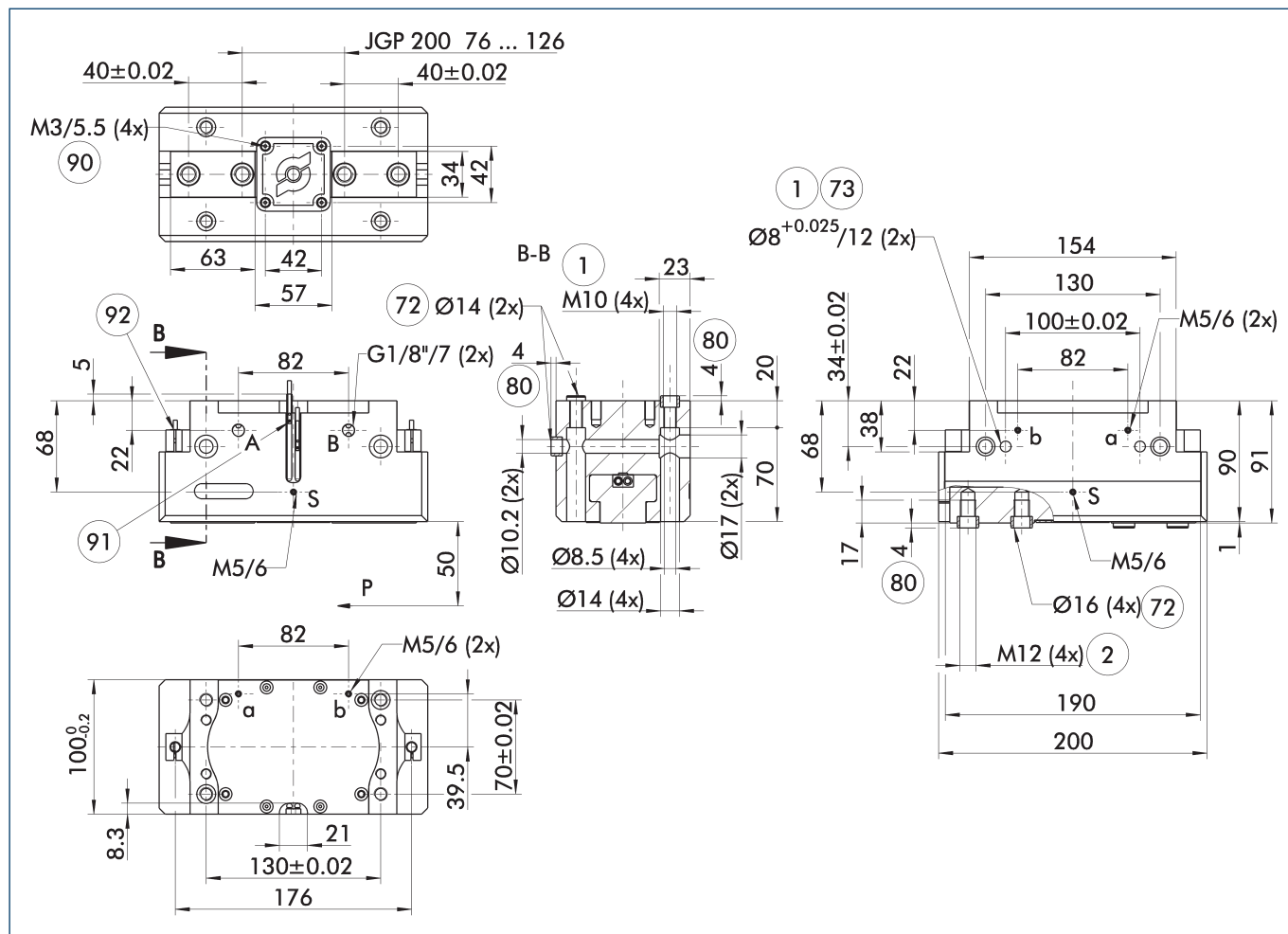
① The indicated moments and forces are static values, apply for each base jaw and may appear simultaneously. Loads may additionally occur to the moment produced by the gripping force itself.

Technical data

Description		JGP 200-1	JGP 200-1-AS	JGP 200-1-IS
ID		0308670	0308671	0308672
Stroke per jaw	[mm]	25	25	25
Closing/opening force	[N]	2700/2870	3610/-	-/3780
Min. spring force	[N]		910	910
Weight	[kg]	5.2	7	7
Recommended workpiece weight	[kg]	13.5	13.5	13.5
Fluid consumption double stroke	[cm³]	385	495	620
Min./nom./max. operating pressure	[bar]	2.5/6/8	4/6/6.5	4/6/6.5
Min./max. air purge pressure	[bar]	0.5/1	0.5/1	0.5/1
Closing/opening time	[s]	0.35/0.35	0.3/0.6	0.6/0.3
Closing/opening time with spring	[s]		0.50	0.50
Max. permissible finger length	[mm]	240	220	220
Max. permissible weight per finger	[kg]	6.5	6.5	6.5
IP protection class		40	40	40
Min./max. ambient temperature	[°C]	5/90	5/90	5/90
Repeat accuracy	[mm]	0.02	0.02	0.02
Dimensions X x Y x Z	[mm]	200 x 100 x 91	200 x 100 x 141	200 x 100 x 141

① It may take a few 100 gripping cycles until the full gripping force (as indicated in the data table) will be available.

Main view



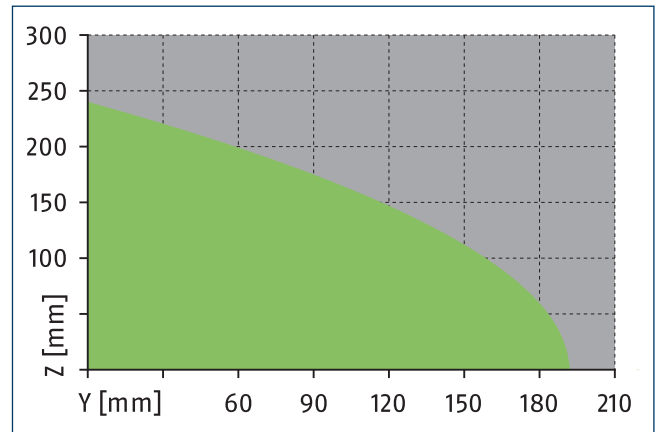
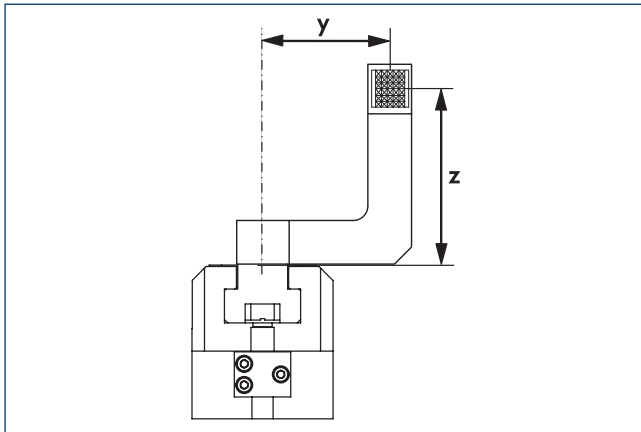
The drawing shows the gripper in the basic version with closed jaws, without dimensional consideration of the options described below.

① As an alternative/in addition to spring-assisted mechanical gripping force maintenance, the SDV-P pressure maintenance valve can be used for I.D. and O.D. gripping (see "Accessories" section of catalog).

- A, a Main / direct connection, gripper opening
- B, b Main / direct connection, gripper closing
- S Air purge connection
- ① Gripper connection
- ② Finger connection
- ⑦② Fit for centering sleeves

- ⑦③ Fit for centering pins
- ⑧① Depth of the centering sleeve hole in the counter part
- ⑨① Thread below the cover for fastening external attachments
- ⑨① Sensor MMS 22..
- ⑨② Sensor IN ...

Maximum permitted finger projection

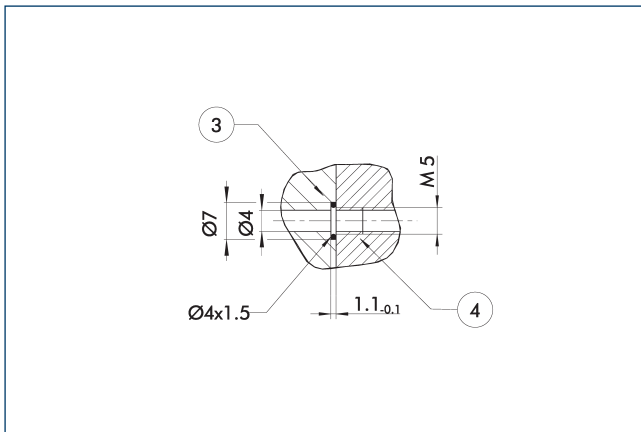


■ Permitted range

■ Inadmissible range

The curve applies for stroke version 1. For other versions, the curve must be parallelly off-set to the max. permissible finger length.

Hose-free direct connection M5

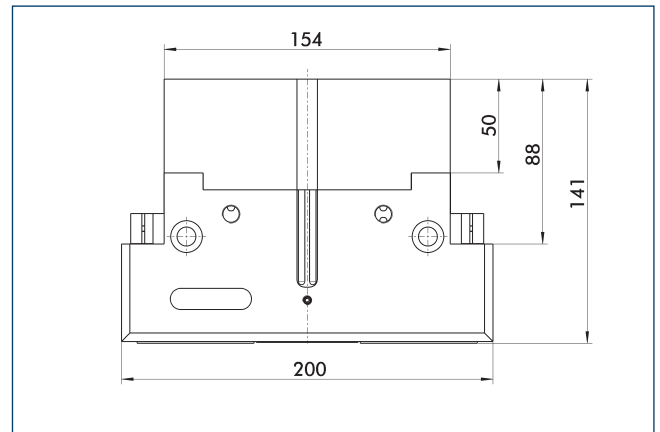


③ Adapter

④ Grippers

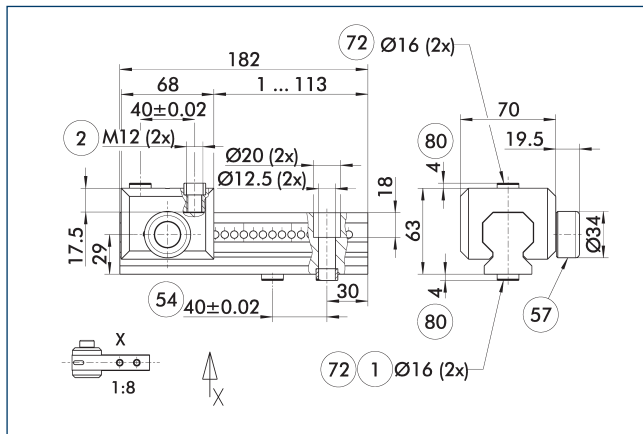
The direct connection is used for supplying compressed air without hoses. Instead, the pressure medium is fed through bore-holes in the mounting plate.

Gripping force maintenance version AS/IS



The mechanical gripping force maintenance device ensures that a minimum clamping force will be applied even if there is a drop in pressure. In the AS/S variant this acts as a closing force, in the IS variant as an opening force. Besides this, gripping force maintenance can be used to increase gripping force or for single actuated gripping.

UZH 200 universal intermediate jaw



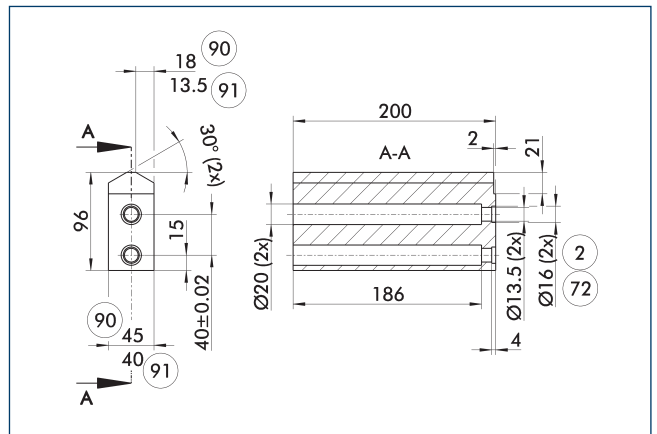
- | | |
|--------------------------------------|---|
| ① Gripper connection | ⑤7 Locking |
| ② Finger connection | ⑦2 Fit for centering sleeves |
| ⑤4 Optional right or left connection | ⑧0 Depth of the centering sleeve hole in the counter part |

The drawing shows the UZB universal intermediate jaw. The fully removable UZB-S slide (can also be ordered separately) allows for a quick jaw change.

Description	ID	Grid dimension
		[mm]
Universal intermediate jaw		
UZF 200	0300047	7
Finger blank		
ABR-PGZN-plus 200	0300015	
SBR-PGZN-plus 200	0300025	
Slide for universal intermediate jaw		
UZF-S 200	5518275	7

- ① If the operating pressure is higher than 6 bar, suitability for use beyond the application limits must be checked.

Finger blanks ABR/SBR-PGZN-plus 200

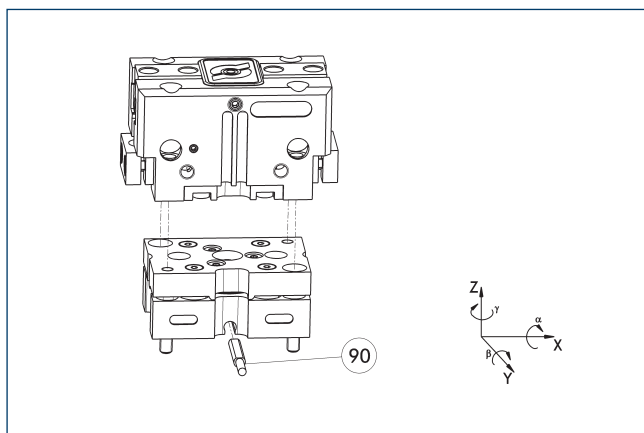


- ② Finger connection ⑨0 ABR-PGZN-plus
⑦2 Fit for centering sleeves ⑨1 SBR-PGZN-plus

The drawing shows the finger blank which can be reworked by the customer.

Description	ID	Material	Scope of delivery
Finger blank			
ABR-PGZN-plus 200	0300015	Aluminum (3.4365)	1
SBR-PGZN-plus 200	0300025	Steel (1.7131)	1

Tolerance compensation unit TCU

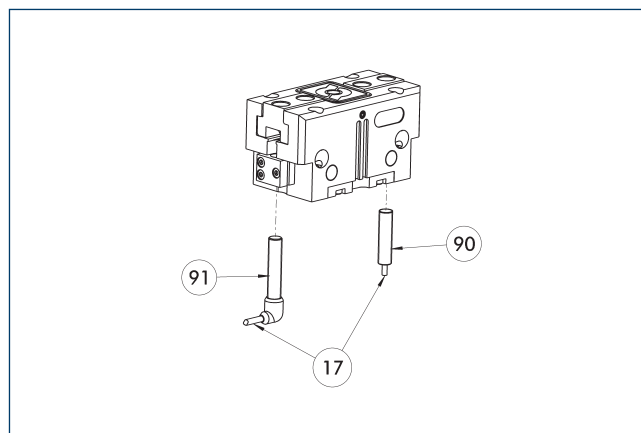


90 Monitoring of locking

Grippers can be directly mounted without an adapter plate. Tolerance compensation unit and gripper have an identical screw connection diagram. Therefore the tolerance compensation units can be assembled later. Please consider the additional assembly height of the tolerance compensation unit. For details please refer to our catalog robot accessories.

Description	ID	Locking	Deflection	Often combined
Compensation unit				
TCU-P-200-3-MV	0324864	yes	$\pm 1^\circ / \pm 2^\circ / \pm 1,5^\circ$	●
TCU-P-200-3-0V	0324865	no	$\pm 1^\circ / \pm 2^\circ / \pm 1,5^\circ$	

Inductive proximity switches



17 Cable outlet

90 Sensor IN ...

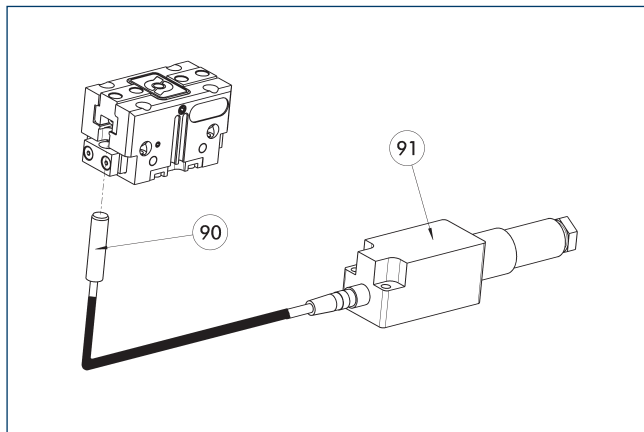
91 Sensor IN...-SA

Directly mounted end position monitoring.

Description	ID	Often combined
Inductive proximity switches		
IN 80-S-M12	0301578	
IN 80-S-M8	0301478	●
INK 80-S	0301550	
Inductive proximity switch with lateral cable outlet		
IN 80-S-M12-SA	0301587	
IN 80-S-M8-SA	0301483	●
INK 80-S-SA	0301566	
Connection cables		
KA BG08-L 3P-0300-PNP	0301622	●
KA BG08-L 3P-0500-PNP	0301623	
KA BG12-L 3P-0500-PNP	30016369	
KA BW08-L 3P-0300-PNP	0301594	
KA BW08-L 3P-0500-PNP	0301502	
KA BW12-L 3P-0300-PNP	0301503	
KA BW12-L 3P-0500-PNP	0301507	
Clip for connector/socket		
CLI-M12	0301464	
CLI-M8	0301463	
Cable extension		
KV BG12-SG12 3P-0030-PNP	0301999	
KV BG12-SG12 3P-0060-PNP	0301998	
KV BW08-SG08 3P-0030-PNP	0301495	
KV BW08-SG08 3P-0100-PNP	0301496	
KV BW08-SG08 3P-0200-PNP	0301497	●
KV BW12-SG12 3P-0030-PNP	0301595	
KV BW12-SG12 3P-0100-PNP	0301596	
KV BW12-SG12 3P-0200-PNP	0301597	
Sensor distributor		
V2-M12	0301776	●
V2-M8	0301775	●
V4-M8	0301746	
V8-M8	0301751	

- ① Two sensors are required per unit for monitoring two positions. On option, extension cables and sensor distributors are available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor system.

Flexible position sensor



90 FPS-S sensor

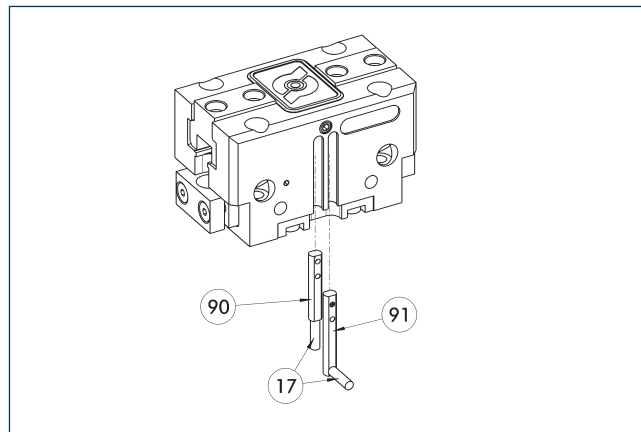
91 FPS-F5 evaluation electronic

Flexible position monitoring of up to five positions.

Description	ID	
Attachment kit for FPS		
AS-FPS-PGZN-plus 200-1	0301640	
Sensor		
FPS-S M8	0301704	
Evaluation electronics		
FPS-F5	0301805	
Cable extension		
KV BG08-SG08 3P-0050	0301598	
KV BG08-SG08 3P-0100	0301599	

- ① When using an FPS system, an FPS sensor (FPS-S) as well as an electronic processor (FPS-F5 / F5 T) are required for each gripper as well as a mounting kit (AS), if listed. Cable extensions (KV) are optionally available – see catalog chapter “Accessories.”

Electronic magnetic switch MMS



17 Cable outlet

91 Sensor MMS 22...-SA

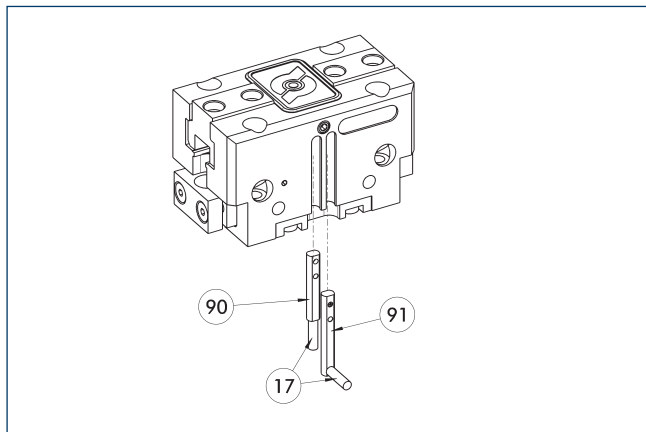
90 Sensor MMS 22..

End position monitoring for mounting in the C-slot.

Description	ID	Often combined
Electronic magnetic switch		
MMS 22-S-M8-PNP	0301032	●
MMSK 22-S-PNP	0301034	
Electronic magnetic switches with lateral cable outlet		
MMS 22-S-M8-PNP-SA	0301042	●
MMSK 22-S-PNP-SA	0301044	
Reed Switches		
RMS 22-S-M8	0377720	●
Connection cables		
KA BG08-L 3P-0300-PNP	0301622	●
KA BG08-L 3P-0500-PNP	0301623	
KA BW08-L 3P-0300-PNP	0301594	
KA BW08-L 3P-0500-PNP	0301502	
Clip for connector/socket		
CLI-M8	0301463	
Cable extension		
KV BW08-SG08 3P-0030-PNP	0301495	
KV BW08-SG08 3P-0100-PNP	0301496	
KV BW08-SG08 3P-0200-PNP	0301497	●
Sensor distributor		
V2-M8	0301775	●
V4-M8	0301746	
V8-M8	0301751	

- ① Two sensors are required per unit for monitoring two positions. On option, extension cables and sensor distributors are available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor system.

Programmable magnetic switch MMS 22-PI1



①⑦ Cable outlet

①⑨ Sensor MMS 22 ..-PI1-...-SA

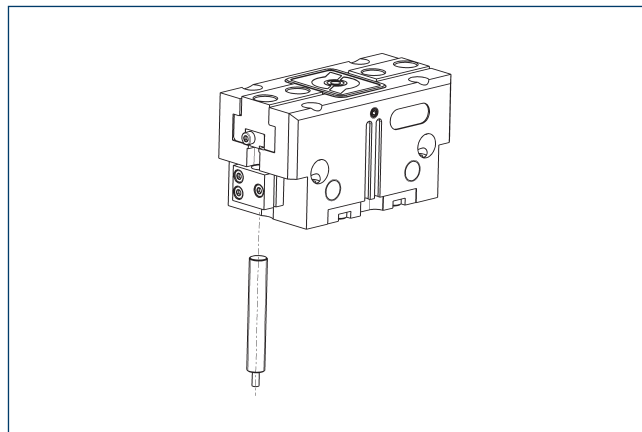
①⑩ Sensor MMS 22 PI1-...

Position monitoring with one programmable position per sensor and integrated electronic system in the sensor. Can be programmed using MT magnetic teaching tool (included in the scope of delivery, ID 0301030) or ST plug teaching tool (optional). End position monitoring for mounting in the C-slot. If the ST plug teaching tools are listed in the table provided, teaching is only possible with the ST teaching tools.

Description	ID	Often combined
Programmable magnetic switch		
MMS 22-PI1-S-M8-PNP	0301160	●
MMSK 22-PI1-S-PNP	0301162	
Programmable magnetic switch with lateral cable outlet		
MMS 22-PI1-S-M8-PNP-SA	0301166	●
MMSK 22-PI1-S-PNP-SA	0301168	
Programmable magnetic switch with stainless steel housing		
MMS 22-PI1-S-M8-PNP-HD	0301110	●
MMSK 22-PI1-S-PNP-HD	0301112	

- ① Two sensors are required per unit for monitoring two positions. On option, extension cables and sensor distributors are available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor system.

APS-Z80 analog position sensor

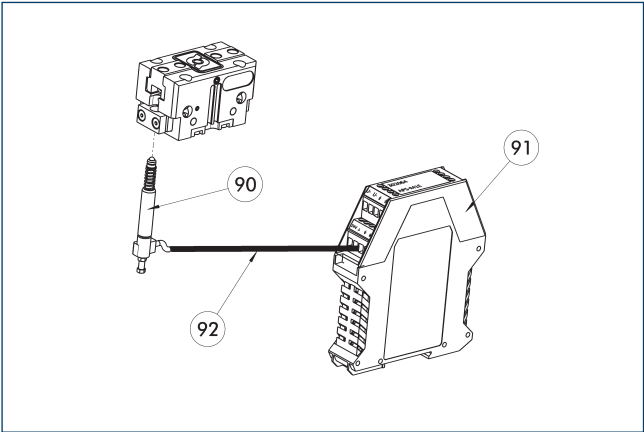


Non-contact measuring, analog multi-position monitoring for any number of positions.

Description	ID	Often combined
Mounting kit for APS-Z80		
AS-APS-Z80-PGZN-plus 200-1	0302115	
Analog position sensor		
APS-Z80-K	0302072	
APS-Z80-M8	0302070	●

- ① When using an APS system, one mounting kit (AS-APS-Z80) and one APS-Z80 sensor is required per gripper. The resolution of the sensor can be lower in the peripheral areas of the gripper. You can find further information on the product in the operating manual.

APS-M1 analog position sensor



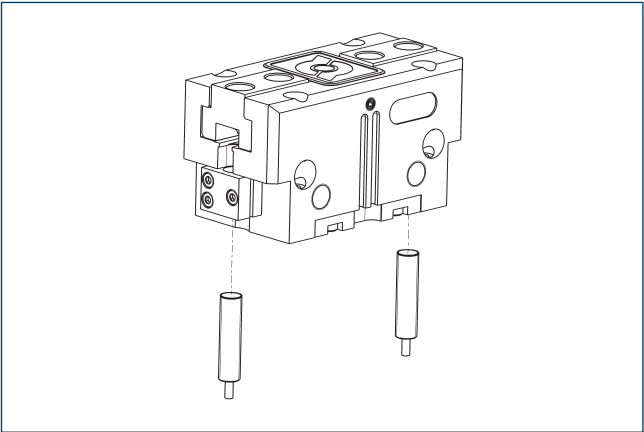
- 90 APS-M1S sensor
- 91 APS-M1E electronic processor
- 92 APS-K extension cable

Analog multi position monitoring for any desired positions

Description	ID	
Mounting kit for APS-M1		
AS-APS-M1-PGZN-plus 200-1/380-2	0302085	
Analog position sensor		
APS-M1S	0302062	
Connection cables		
APS-K0200	0302066	
APS-K0700	0302068	
Evaluation electronics		
APS-M1E	0302064	

- ① When using an APS system, for each gripper an attachment kit (AS-APS-M1), an APS-M1S sensor (incl. 3 m cable) as well as an electronics (APS-M1e) are required. An extension cable (APS-K) can be connected between the sensor and the electronics as an option. The max. cable length between the sensor and the electronics is 10 m, between the electronics and their control unit (PLC) it is max. 1 m.

Cylindrical reed switches



End position monitoring can be mounted with an attachment kit.

Description	ID	
Attachment kit for proximity switch		
AS-RMS 80 PGN/PZN-plus 160-380	0377727	
Reed Switches		
RMS 80-S-M8	0377721	

- ① Two sensors (closer/S) are required for each unit and extension cables are available as an option. This attachment kit needs to be ordered optionally as an accessory. Two mounting kits are required for each gripper. For sensor cables, note the minimum permissible bending radii. These are generally 35 mm.



SCHUNK GmbH & Co. KG
Spann- und Greiftechnik

Bahnhofstr. 106 - 134
D-74348 Lauffen/Neckar
Tel. +49-7133-103-0
Fax +49-7133-103-2399
info@de.schunk.com
schunk.com

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