

Release Notes

Version	Comment	Supported Grippers	Interface
1.2.0 Compatibility: ROBOGUIDE v9.40 P/79 Tablet TP V1.42 Tool I/F Version 1.4 Tool I/F Version 1.3	Changelog: <u>Only working on > V9.40P/70</u> Compatible to all Tool I/F Versions New Position input (Slider) Gripper Diagnostic code in Alarm log Gripper "STOP" on Flag. Gripper no longer stops when robot is not busy Wrist button support Jog possible with Wrist button	EZU: all types with firmware version 5.3 EGU: all types with firmware version 5.1 - 5.3 EGK: all types with firmware version 5.1 - 5.3	RS485/ Modbus RTU at EE-Connector
1.1.0 Compatibility: ROBOGUIDE v9.40 P/70 Tablet TP V1.36 Tool I/F Version 1.4	Changelog: Added Detach/Attach Auto register update	EZU: all types with firmware version 5.3 EGU: all types with firmware version 5.1 - 5.3 EGK: all types with firmware version 5.1 - 5.3	RS485/ Modbus RTU at EE-Connector
1.0.4 Compatibility: ROBOGUIDE v9.40 P/61 Tablet TP V1.32	Changelog: Added EZU	EZU: all types with firmware version 5.3 EGU: all types with firmware version 5.1 - 5.3 EGK: all types with firmware version 5.1 - 5.3	RS485/ Modbus RTU at EE-Connector
1.0.3 Compatibility: ROBOGUIDE v9.40 P/49 Tablet TP V1.28	Changelog: Fixed Register1 forced to '1'	EGU: all types with firmware version 5.1 and 5.2 EGK: all types with firmware version 5.1 and 5.2	RS485/ Modbus RTU at EE-Connector

1.0.2 Compatibility: ROBOGUIDE v9.40 P/49 Tablet TP V1.28	Changelog: Test UI: - Completed status bits list. - Added <i>Fast Stop</i> button, <i>Brake Test</i> button and target velocity input field. Settings UI: - Completed status bits list. - Changed validators of text input fields for parameters to comply with the gripper's policy for those values. Program Instructions: - Added <i>Brake Test</i> instruction. - Added remaining status bits to the <i>Get Status</i> instruction. - Pos/speed/force can set by register Status Bar: - Display error and warning codes as well as error and warning descriptions if the gripper is in the respective state. Manual: - Added examples for error handling in a program. Required Options: - Known issues: Register1 forced to '1'	EGU: all types with firmware version 5.1 and 5.2 EGK: all types with firmware version 5.1 and 5.2	RS485/ Modbus RTU at EE- Connector
1.0.1 Compatibility: ROBOGUIDE v9.40 P/38 Tablet TP V1.19	Initial Release Required Options: - Known issues: Register1 forced to '1'	EGU: all types with firmware version 5.1 EGK: all types with firmware version 5.1	RS485/ Modbus RTU at EE- Connector