

Release Notes

Version	Comment	Supported	Interface
1.0.2 Compatibility: E-Series Robots Polyscope 5.13	Changelog: Changed maximum velocity to 80 mm/s for EGU 50 grippers only. Removed the command “workpiece gripping at expected position” for EGU 50 grippers only. Changed number of digits of the target velocity to 2 Fixed Bug that led to high target positions or target velocities when using the + and – Buttons in the program nodes Corrected range for gripper parameters Required Options: - Known issues: Comma as number delimiter used by European languages causes errors. Plugin is only working when the robot language is set to English. Parameter “grip position margin” is not considered when calculating position ranges in program nodes If the gripper is not connected when the robot is started, gripper parameters are set to default values in the program nodes	Grippers EGU: all types with firmware version 5.1 EGK: all types with firmware version 5.1 Firmware version 5.2 is compatible but new functions of version 5.2 are not supported	Modbus RTU at tool interface

1.0.1 Compatibility: E-Series Robots Polyscope 5.13	Changelog: Initial Version Required Options: - Known issues: High target velocities for EGU 50 cause the robot arm to shut down Setting gripper parameters outside of the parameter's range cause the plugin to stop communicating with the gripper	EGU: all types with firmware version 5.1 EGK: all types with firmware version 5.1	Modbus RTU at tool interface
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